

# Micro-arcsecond Astrometry Small Satellite (MASS)

#### **To Discover and Measure Masses of Nearby Earth-like Exoplanets**

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#### CL# 19-8215

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## How Can We Search for Exo-Earths around Nearby Stars?

- Radial Velocity Limitations:
  - Sensitive to small orbital radius
  - Also has  $(M \cdot \sin i)$  ambiguity
- Transit technique Limitations:
  - Sensitive to smaller orbital radius
  - Favorable planet orbit inclination

# • Astrometry more sensitive to large orbital radius



#### **MASS Overview**

- Goal is ~4uas (1 hr) astrometric precision
- Would enable a search for Earth mass planets
  - around ~20 'nearest' FGK stars for
    - ~ 5×1  $M_{\oplus}$  and
    - ~  $12 \times 2 M_{\oplus}$ planets in the mid Habitable Zone.
- Potential low cost possible taking advantage of low cost mass produced commercial Spacecraft.





чтр	Name	Depth,	V	Spect.	Dist.,	signature	Ref	hours to	cumul.
1111		ME	mag	Туре	pc	μas	Stars	SNR=6	hours
71683	α Cen A	1	0.0	G2V	1.3	2.42	1228	59	59
71681	α Cen B	1	1.4	K1V	1.3	1.71	1228	121	180
2021	β Ηγί	1	2.8	G2IV	7.5	0.55	105	<b>9</b> 57	1136
3821	η Cas	1	3.5	G0V	6.0	0.53	488	1530	2667
77952	β TrA	1	2.8	F1V	12.3	0.44	999	1511	4178
99240	δ Pav	2	3.6	G8IV	6.1	0.99	119	444	4622
22449	π3 Ori	2	3.2	F6V	8.0	0.98	139	543	5164
27072	γ Lep	2	3.6	F6V	9.0	0.84	127	602	5766
746	β Cas	2	2.3	F2III	16.7	0.87	372	703	6469
96100	σ Dra	2	4.7	K0V	5.8	0.79	133	1236	7705
14632	ι Per	2	4.1	G0V	10.5	0.69	231	1377	9081
12777	θ Per	2	4.1	F8V	11.2	0.67	328	1591	10673
19849	40 Eri	2	4.4	K1V	5.0	0.89	77	1652	12325
105858	γ Pav	2	4.2	F9V	9.2	0.72	94	1701	14026
8102	τ Ceti	2	3.5	G8V	3.6	1.31	28	1715	15741
108870	ε Ind	2	4.7	K5V	3.6	0.96	65	1950	17691
1599	ζTuc	3	4.2	G0V	8.6	1.10	68	1238	18929
78072	γ Ser	3	3.9	F6V	11.1	1.07	62	1340	20269
57757	βVir	3	3.6	F9V	10.9	1.14	41	1453	21722
64924	61 Vir	3	4.7	G7V	8.5	0.97	121	1661	23383
15510	e Eri	3	4.3	G6V	6.1	1.28	51	1961	25344
64394	β Com	3	4.2	G0V	9.2	1.06	31	3419	28763

#### **MASS Flight System Basic Elements**

**MASS Flight System Context** 



#### MASS Flight System Preliminary Design

## **MASS Telescope & Focal Plane**

- Telescope: corrected RC
  - Modified version of the AOS AP-35
    - 35cm Telescope
    - > 0.5 deg FOV
    - Nyquist-sampled Focal Plane
    - SiC OTA



#### • Focal Plane: next gen sCMOS

- SONY IMX 411 large format sensor
  - 150 Mpix (14,208 x 10,656 pixels)
    - Pixel size 3.76 um
  - Backside illuminated
    - cover glass removed
  - ~90% peak QE
  - 1.5 e- Read noise
  - 40 ke- full well, 2 Hz full frame rate



#### Spacecraft

#### • Commercial ESPA class spacecraft from Blue Canyon



Similar to the S5 mission: ESPA using cubesat parts





#### **Sun-Synchronous Orbit Operational Concept**



## Single-Digit µas Astrometry

- $\lambda$ /D for a 35cm telescope ~ 0.35 arcsec
- 10uas  $\rightarrow$  centroiding to 1 part in 30,000.
- 3 major noise/error sources
  - 1. Photon noise (of ref stars)
    - Use wide FOV
  - 2. Optical distortion
    - Use crowded field of stars to calibrate
      - High degree of thermal stability so distortion calibration needed < 1/day
      - Prefer GEO or HEO altitude
  - 3. Detector imperfections
    - Use laser fringes to calibrate Pixel positions





## SubPixel detector calibration, centroid to $10^{-5}\lambda/D$

log<sub>10</sub> Upsampled Filtered Image -0.5 10 -1 20 -1.5 metrology 30 -2 metrology light CCD block Y, pixel 2 x N Pol. Adj. laser -2.5 fiber oscillating -3 phase 50 matrix fiber fringes  $\delta \varphi$ function -3.5 shifter switch 60 generator  $\delta \varphi$ 70 -4.5 80 10 20 30 50 60 70 Irregularity in pixel location, ∆ X<sub>ma</sub> (pixel) Irregularity in pixel locations,  $\Delta Y_{m}$  (pixel) X. pixel Astrometric Error after Averaging 10 Placements x 10<sup>-5</sup> Y : σ = 8.4e-06 λ/D Error as fraction of  $\lambda$  / D X : σ = 9.7e-06 λ/D 0.5 0 -0.5 10 20 30 40 50 60 -1 2.5 3.5 0.5 1.5 2 3 Average Position of Image, pixels

#### Preliminary tests on a Larger sCMOS detector

- Last fiscal year we did conduct some tests on a larger format backside sCMOS detector.
  - The sensor was a 2K\*2K backside sCMOS with 11um pixels.
- We found two issues
  - Like many sCMOS sensors it had two A/D converters (one with a high gain amplifier for low level signals, one with low gain that provide a large full well)
  - In this case the two 11 bit A/D were blended in the camera electronics to produce a 16 bit output. There were photometric errors >> 0.1% in the blended output. Fortunately the very large format 150Mpix sCMOS sensor we plan to use for MASS has a single 16 bit A/D. (the 1st sCMOS to feature a 16bit A/D)
  - We also saw geometric errors in the pixel positions, the left/right halves of the sensor had slightly different pixel spacing. (diff by ~0.2% (11um vs 11.02um) This was a discontinuity in the slope (not the position) and even at 1/1000 pixel would be modeled with a low order polynomial (as field distortion)
  - But at 1e-4 pixel this has to be measured and explicitely.

#### New setup with MASS sensor



## **Optics Field Distortion**

- Optics field distortion has several sources
  - Perfectly fabricated optics will have distortion. (part of design)
  - Optics are not perfectly manufactured. (I/20 errors 1/f3) to be expected
  - Possible chromatic errors when lenses are used.
- All in modeling, found distortion of the design can be modeled to < 5uas with 9<sup>th</sup> order poly.

- Also we found that λ/20 optical figure errors are also well modeld by the 9<sup>th</sup> order poly. (optic closes to focal has the most beam walk)
  - Made errors ~2X worse with I/20
- Chromatic errors were dealt with by limiting spectrum to 500~750nm. And designing the system accordingly.
  - What matters is shift in position when star's temperature changes. (offsets don't matter because we're looking for periodic motion)



#### **Bright Stars (and detector saturation)**

- The closest stars are very bright. (Alp Cen is ~0 mag) and even though the CMOS detectors have much higher frame rates than CCDs, saturation is an issue.
- Our approach is to use a technique that has been used on HST and planned for WFIRST (WFI) perform astrometry on the diff spikes of very bright stars.
- The diffracting aperture is on the primary mirror (oversized from the physical spider support)
  - The % of light diffracted was increased to ensure that the its photon noise was smaller than photon noise from reference stars, for the dimest target star whose central peak was saturated.
- This will be simulated and tested in the lab.



All diff apertures (spider and secondary) on primary mirror slightly enlarged so there is no beam walk over the ~0.5 deg FOV

#### **Astrometric Error Budget**

4 uas astrometry of a bright target star against 11~16 mag reference stars
100~200 ref stars



- We simulated a thermal control system (for flight)
  - turned out to be very capable.
- SSO orbit was chosen
  - few eclipses
- Examined 1 orbit in SSO
  - heating by Earth changed
- Detector stable to < 0.5 mK
- Telescope optics and structure stable to ~ 10mK.
  - SiC structure
- Detector stable to < 5uas (over field)
- Distortion stable to < 5uas (over field)



Temperatures in $^\circ \text{C}$	РМ	SM	Optics 1	Optics 2	Optics 3	Detector
Mean Temp	-10.5174	-10.5011	-6.9487	-6.5735	-6.3522	-4.9996
Maximum Temp	-10.3406	-10.4907	-6.9462	-6.5717	-6.3409	-4.9993
Minimum Temp	-10.6589	-10.5059	-6.9617	-6.5832	-6.3542	-5.0000
∆T overall	0.3183	0.0152	0.0155	0.0115	0.0133	0.0007



# **Spacecraft capabilities needed/Orbit etc**

- The focal plane can be read out quickly (compared to CCDs) but because its so large, it does take time. (3 hz). The spacecraft attitude has to be stable to < I/D on the time scale to read the array. (ideally 0.25~ 0.5 I/D)</li>
- JPL's Asteria achieved ( on a cubesat budget) the type of pointing stability we want.
  - This may require a separate ~6cm telescope with sCMOS focal plane as a fine guidance camera.
- Default SSO orbit. Thermal design to aim for 1 digit mK sensor stability and < 10 mK telescope thermal stability. (SiC telescope thermal stability is slightly better at low Temp (<200K), reducing heater power needed to maintain thermal stability.
  - Sufficient battery energy to maintain thermal control during eclipse of S/C in SSO orbit for part of the year.

# Commercial Space Industry has dramatically lowered the cost of ESPA class spacecraft

- Dozens of ESPA class S/C now orbit the earth providing Earth sensing data for Business/Industry. Many of these are "mass produced" in quantities ~10. Mostly they use cubesat parts. (some eg reaction wheels, scaled up for microsats)
  - Mass produced satellites with 30~35cm telescopes and CMOS focal planes can be below \$10M/each.
  - One of a kind science missions will be more expensive, but affordable
- Unlike traditional NASA and DoD missions, the spacecraft bus for commercial satellites are bid "fixed price". Major components such as small (30~35cm telescopes and CCD/CMOS focal planes are also bid fixed price).
  - Reducing the mission cost risk.
- Life time (on their website) advertised as ~5 yrs. (very different from "student cubesat" projects of 10yrs ago)
  - The very low cost of cubesat components, lets one think of redundant components (eg reaction wheels, star trackers, solar panels) to ensure 3~5 yr mission life.
- BUT the cost of these commercial missions are NOT in the NASA/DoD data base. (in some cases historical costs are proprietary, (bid fixed price), NASA Centers and NASA costing may or may not accept these low costs.

# **Exoplanet Science / Mission Cost**

- 5 nearby stars down to 1 Mearth in 1 AU equiv orbit
- ~20 stars down to 2 Mearth in 1 AU equiv orbit
- JPL Team X costing exercise
  - ~3 cost numbers
    - Grass roots (based on ROM quotes)
      - ~ \$24M (all costs include 30% reserve)
    - 50% cost (based on historical data)
      - ~ \$40M
    - 70% cost
      - ~ \$44M: 70% prob mission will be completed within this cost

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