

SAG19 Update

Exoplanet Imaging Data Challenge

Benchmarking Image Processing Methods

<https://exoplanet-imaging-challenge.github.io/>

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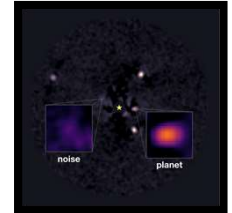
Data set host



Data challenge host

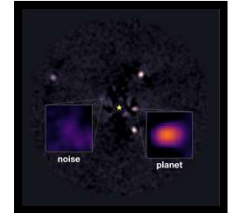
See Cantalloube et al. 2020
SPIE Proceedings paper!

Context & Goals



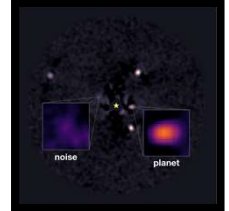
- Goals
 - Provide a **library** of pre-processed HCI datasets to test the various algos.
 - Provide tools to **compare new algorithms** to the state-of-the-art.
- Context
 - **Collaborative initiative** between several institutes worldwide.
 - Direct **support** from the Grenoble Alpes Data Institute (France)
 - **Feedback** from a large international team of researchers.

Data sets



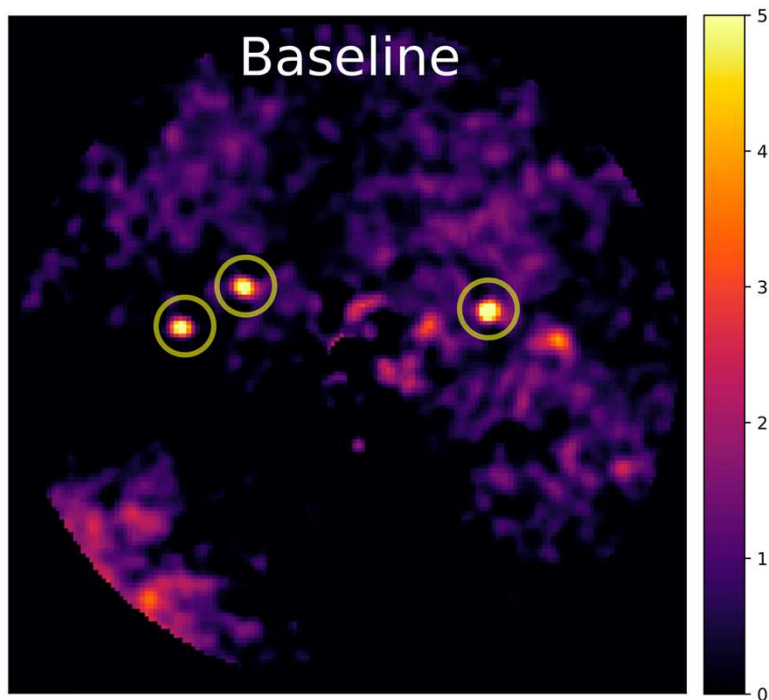
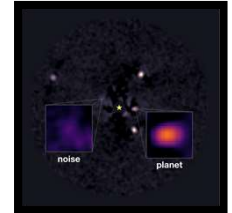
- **ADI subchallenge:** 9 datasets from 3 instruments
 - **VLT/SPHERE-IRDIS** using an Apodized Lyot Coronagraph (H-band)
 - **Keck/NIRC2** using an Annular Groove Phase Mask (L-band)
 - **LBT/LMIRCam** without coronagraph (L-band)
- **ADI+mSDI subchallenge:** 10 datasets from 2 instruments
 - **VLT/SPHERE-IFS** using an Apodized Lyot Coronagraph
 - **Gemini-S/GPI** using an Apodized Lyot Coronagraph
- All data are pre-reduced and cropped to $20 \lambda/D \times 20 \lambda/D$
- Data are given with the pixel scale (arcsec/px) of the instrument

Injecting Synthetic Planetary Signals



- **Injected** synthetic exoplanet signals: 0 to 5 per image
- Injections are **standard** (no smearing, photometric variability, anisoplanetism etc.).
- For multispectral, a **specific spectrum** is used.
- The (separation; position angle) is randomly picked in the field-of-view
- The contrast is randomly chosen within a range close to the 5-sigma detection limit of the baseline annular Principal Component Analysis algorithm

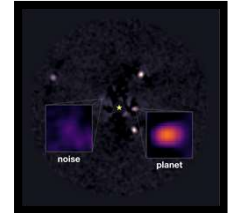
Required Input from Participants



After running a given algorithm on **all** pre-reduced datasets, the participants must provide:

- A detection map for each dataset
- A single detection threshold value for all datasets

Detection Metrics



For each threshold, we count the:

- True Positives (TP)
- False Positives (FP)
- False Negatives (FN)
- True Negatives (TN)

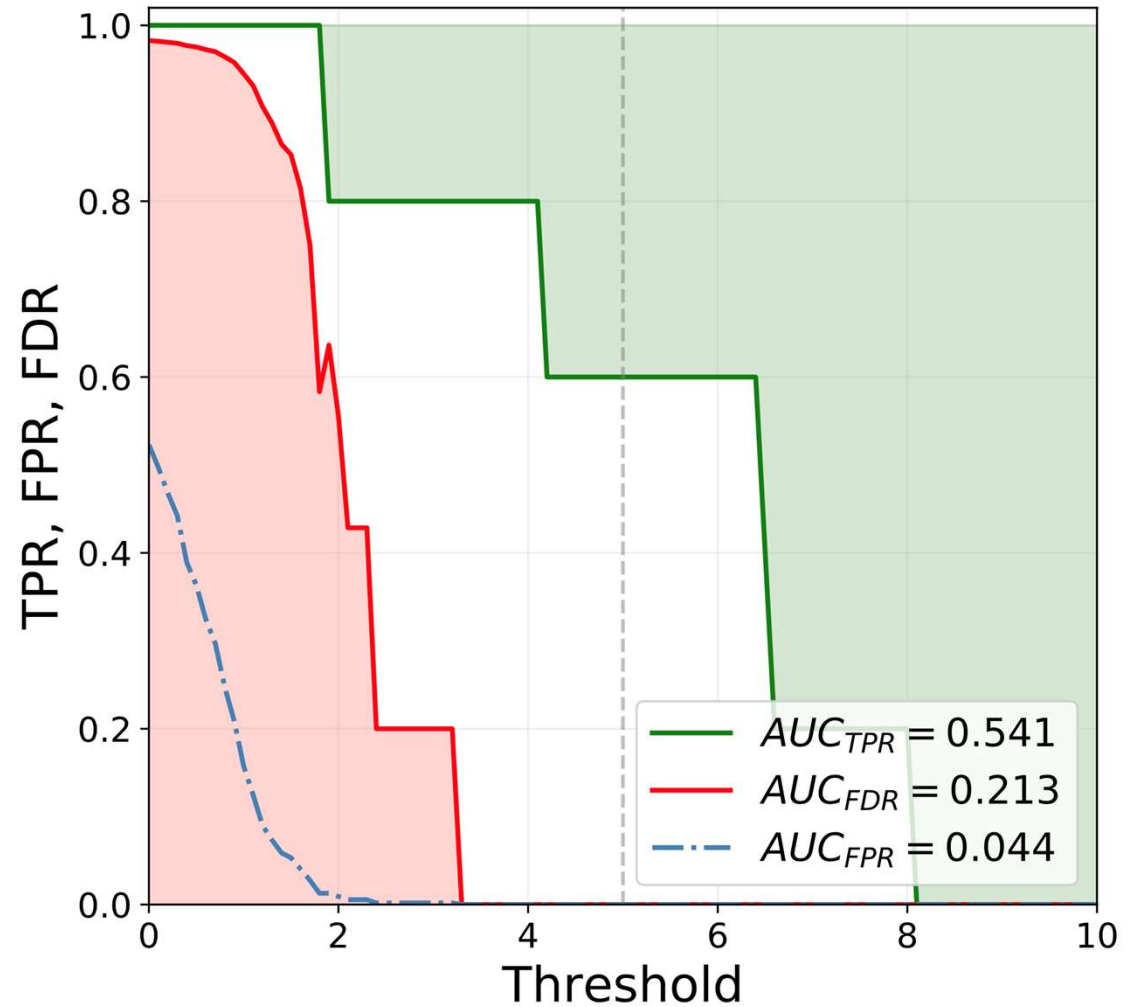
Then, we define the:

- True positive rate: $TPR = TP / (TP + FN)$
- False positive rate: $FPR = FP / (FP + TN)$
- False discovery rate: $FDR = FP / (FP + TP)$
- Final F1-score (or harmonic mean of TPR): $F1 = 2 * TP / (2 * TP + FP + FN)$

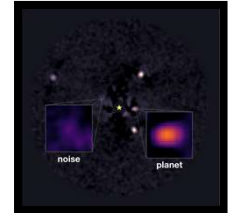
Detection Metrics

1. F1-score (ideally 1)
2. AUC of the TPR (ideally 1)
3. AUC of the FDR (ideally 0)

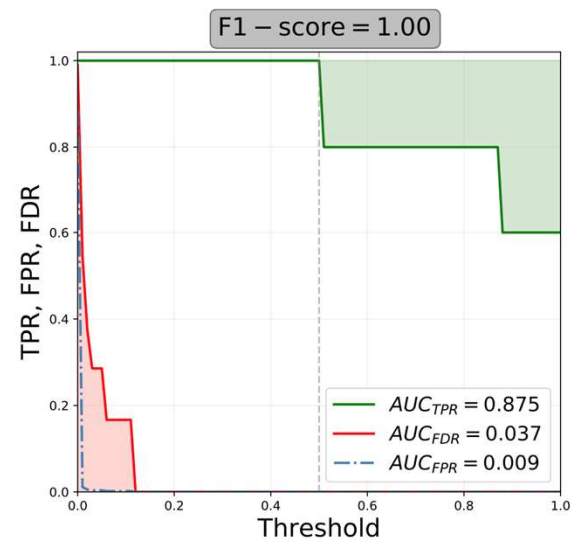
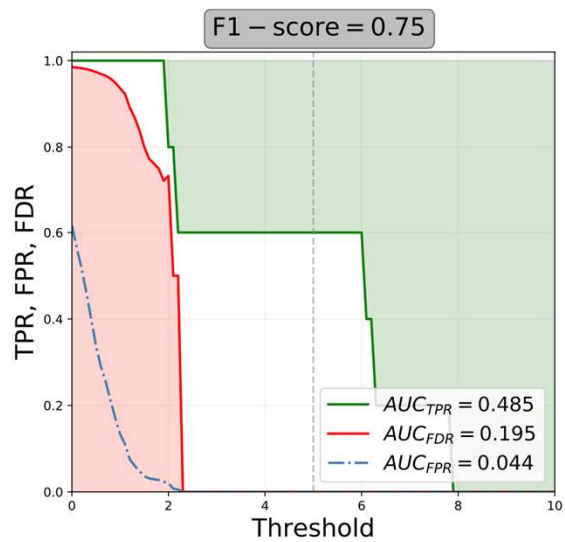
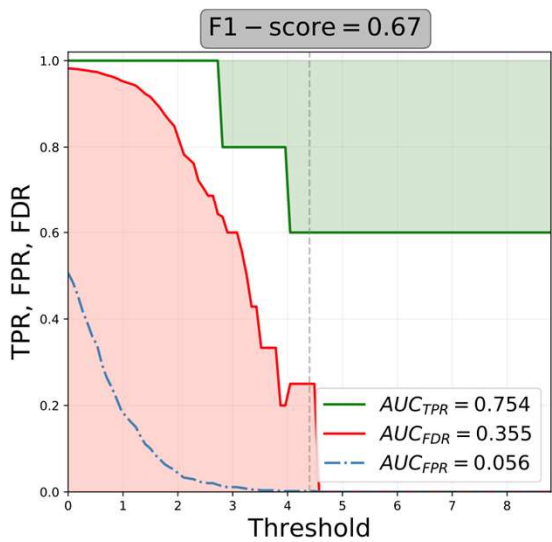
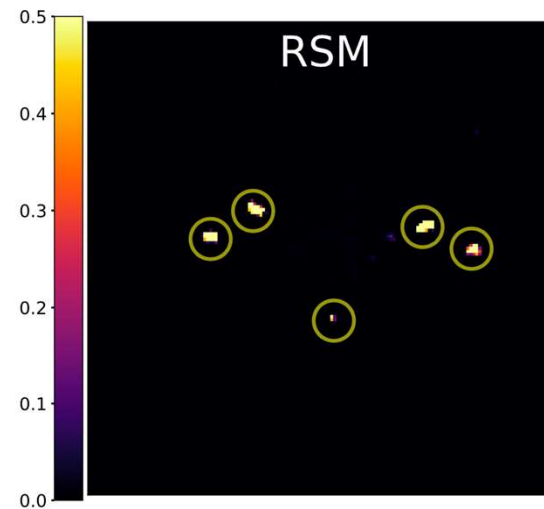
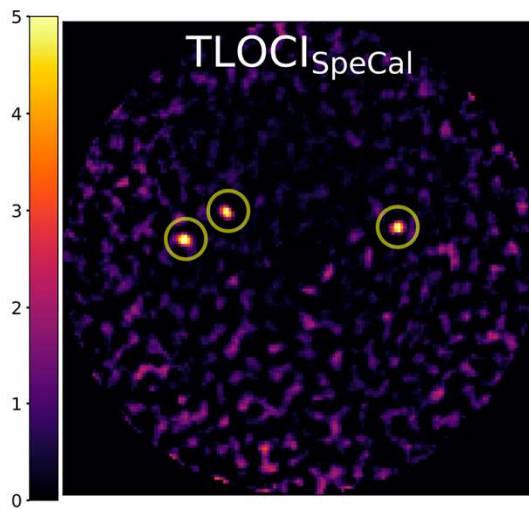
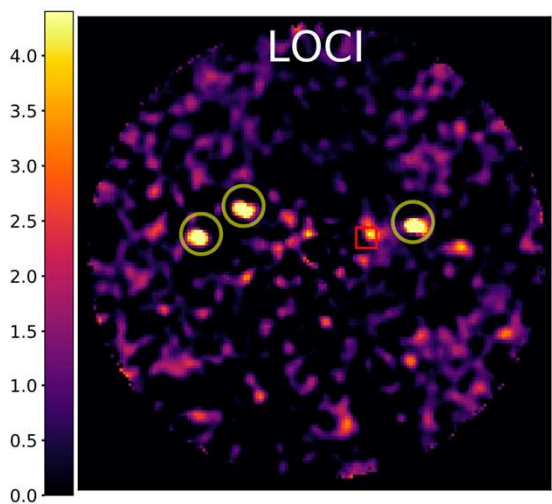
AUC = Area Under Curve

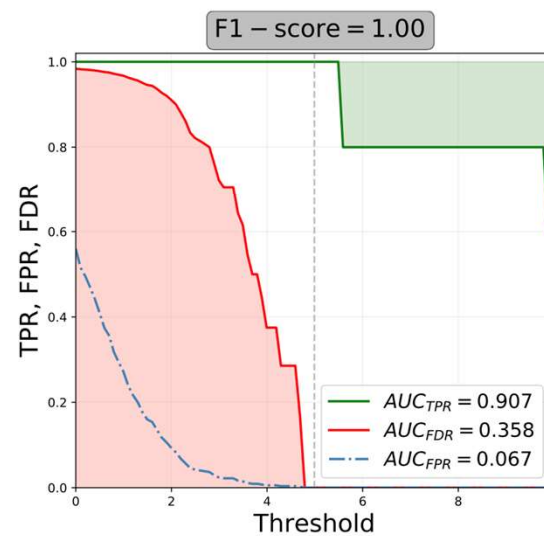
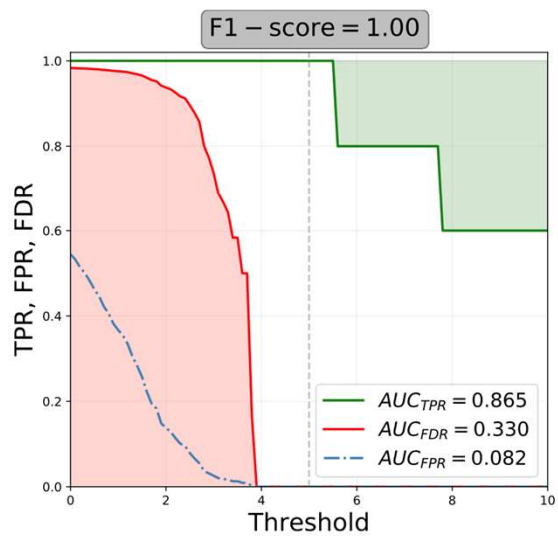
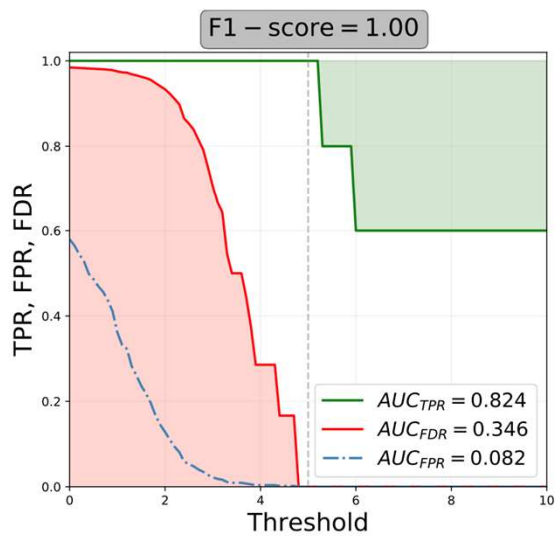
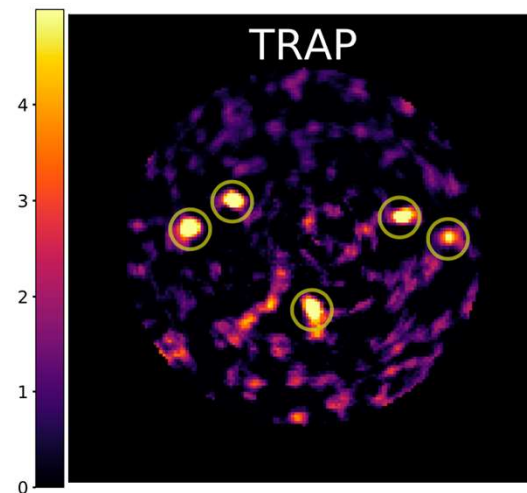
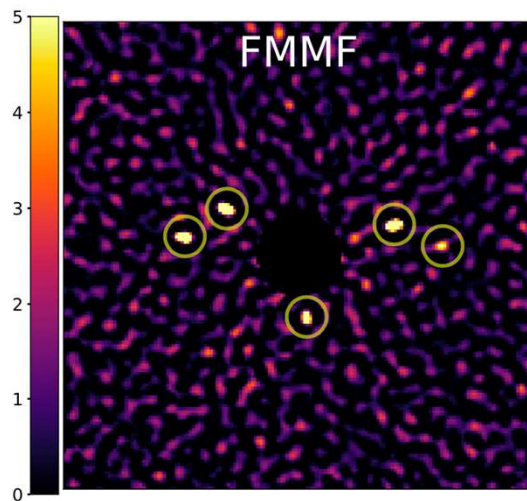
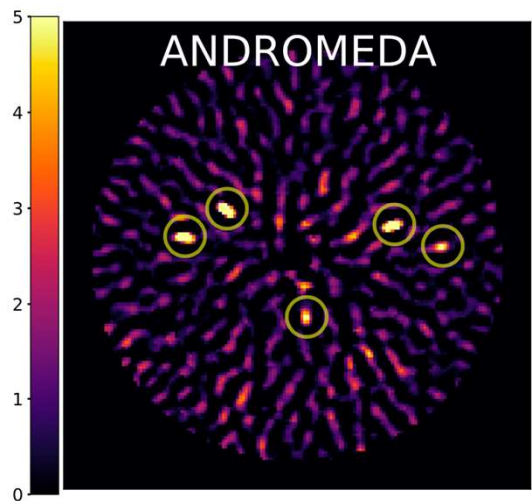


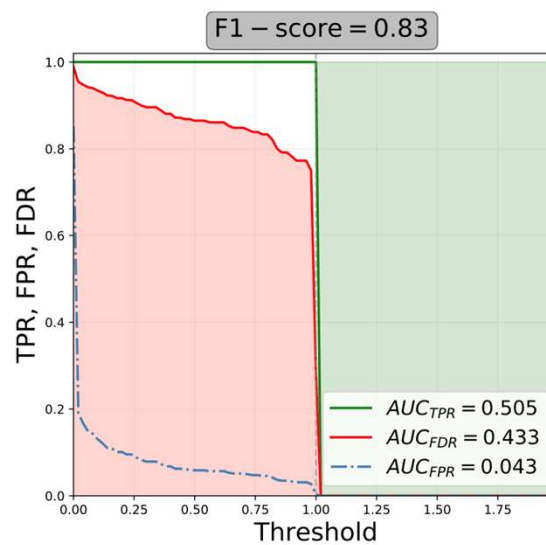
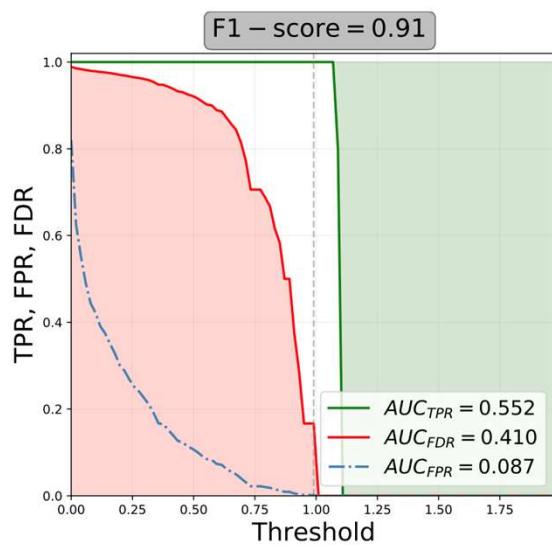
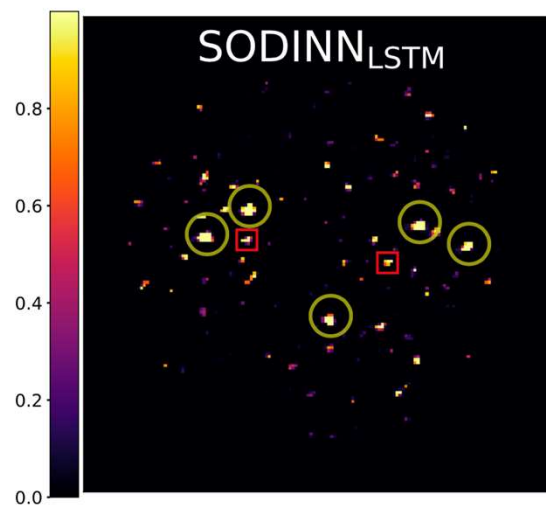
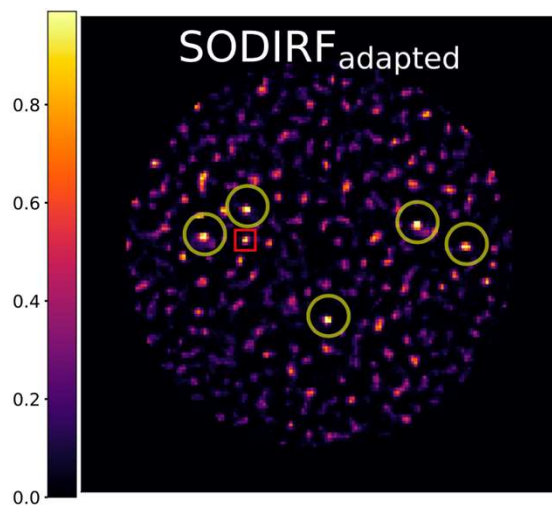
Submissions



- **ADI subchallenge:** 22 valid submissions from 12 participants
 - 12 submissions used speckle subtraction techniques:
 - cADI, PCA, LOCI, STIM map, RSM map
 - 5 submissions used inverse problem approaches:
 - ANDROMEDA, FMMF, PACO, TRAP
 - 5 submissions used supervised machine learning:
 - SODIRF, SODINN
- **ADI+mSDI subchallenge:** 4 valid submissions from 3 participants
 - 1 submission used a speckle subtraction technique: PCA-ASDI
 - 3 submissions used the inverse problem approach:
 - PACO-ASDI, FMMF, ANDROMEDA

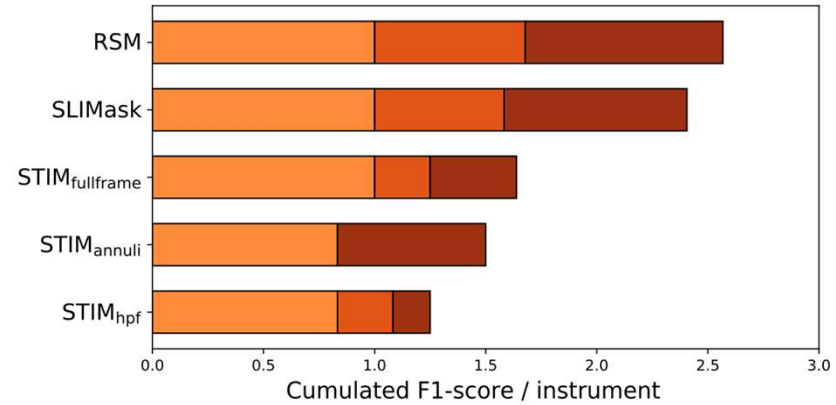




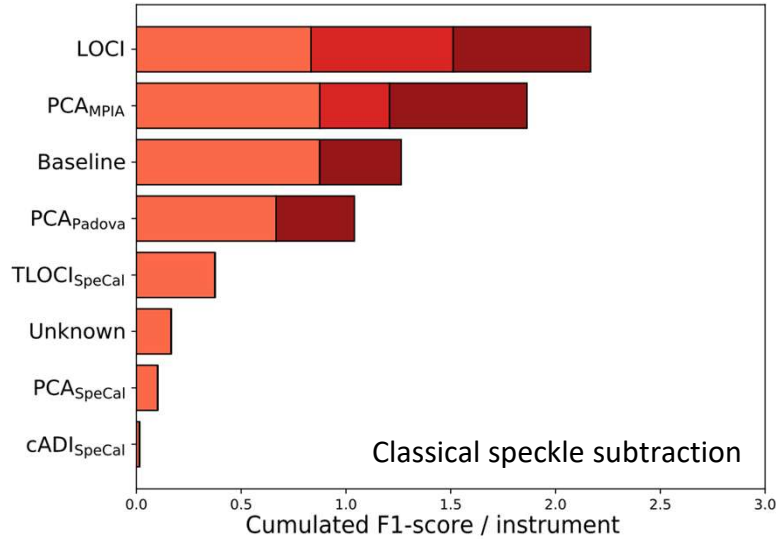


ADI Subchallenge: Ranking the results by the F-1 score

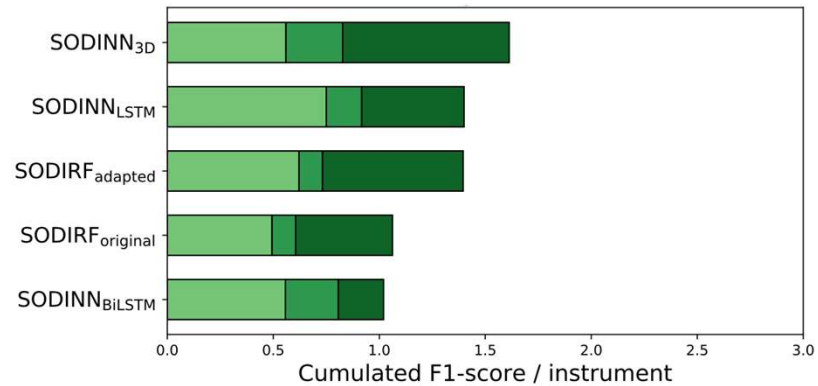
Advanced speckle subtraction



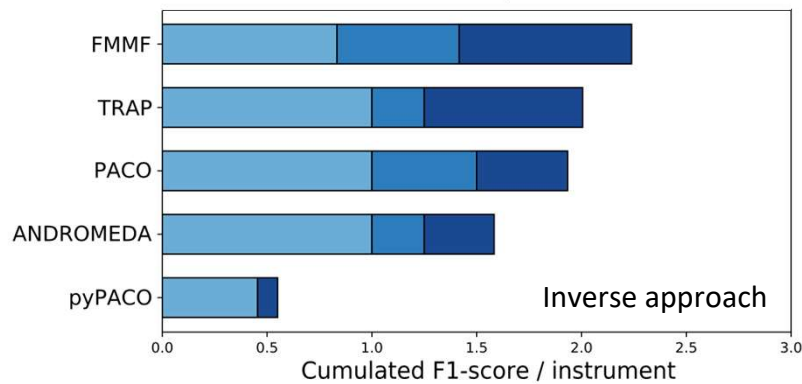
Classical speckle subtraction

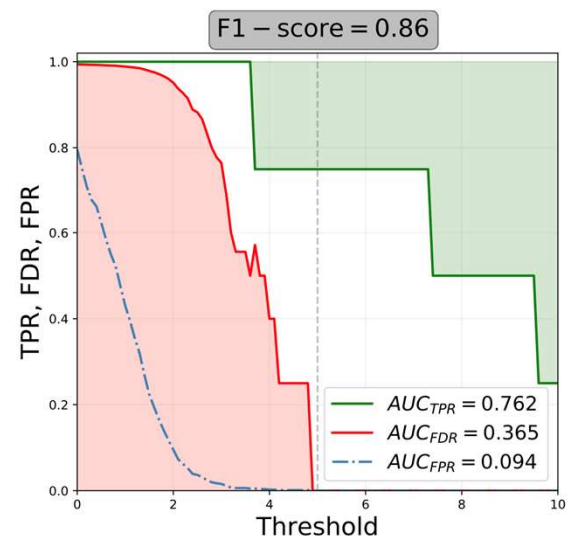
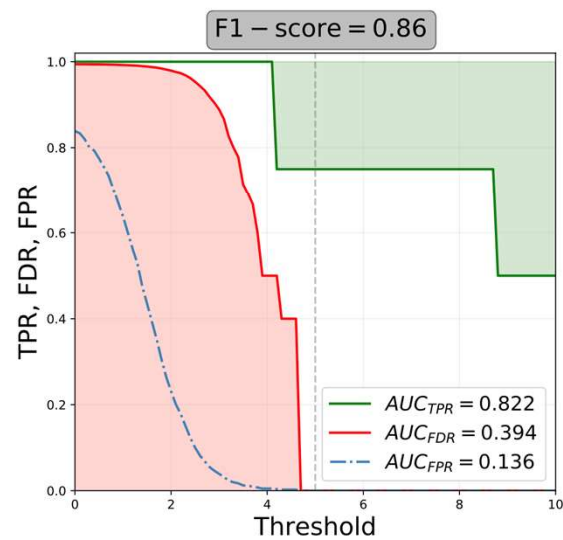
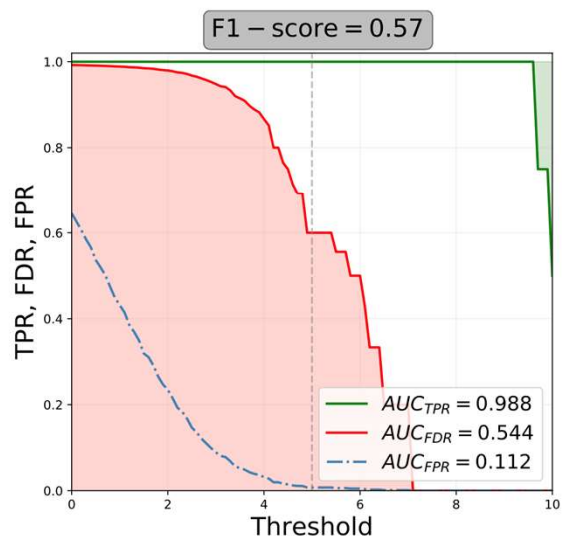
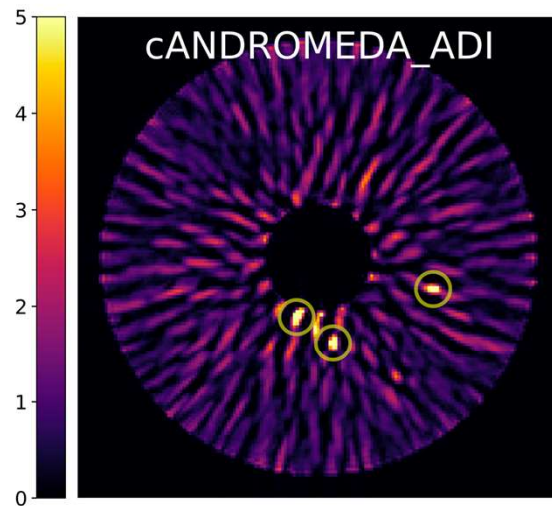
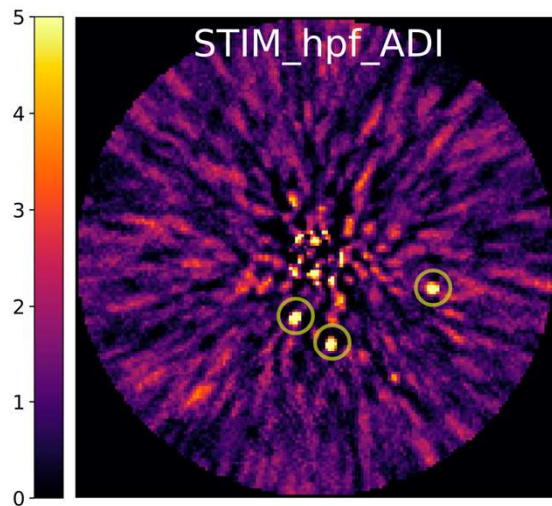
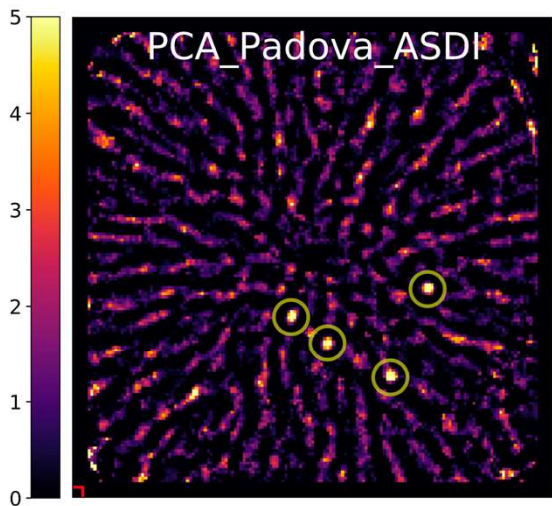


Supervised machine learning

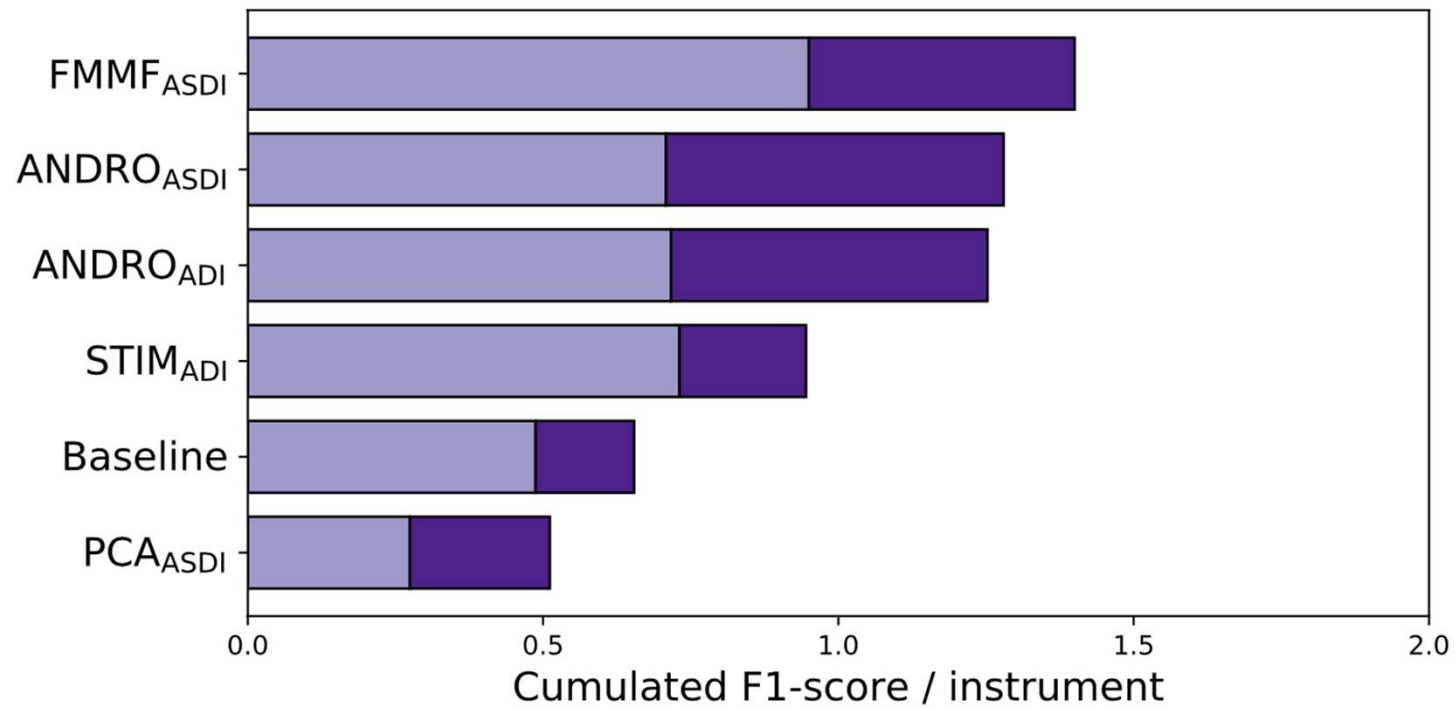


Inverse approach

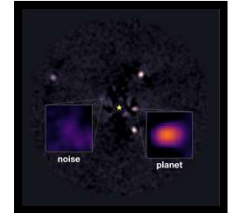




ADI+mSDI Subchallenge: Ranking the results by the F-1 score

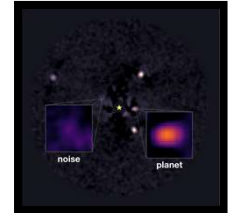


Results



- **ADI subchallenge:**
 - The rankings based on the three scores generally give consistent results
 - The latest techniques (e.g. RSM) perform better than classical speckle subtraction techniques
 - However, the supervised machine learning techniques tested here suffer from high FPs
 - Performance depends on the instrument and dataset
- **ADI+mSDI subchallenge:**
 - Spectral information enables the detection of fainter sources
 - More recent methods are generally better, but with some exceptions
 - The inverse problem approach allows for a comparison between the candidate and speckle spectrum

Future Work



- These results represent only Phase 1 of the data challenge!
- Future phases will:
 - Provide additional datasets, e.g. high spectral resolution data
 - Incorporate detection characterization (e.g. position and contrast)
 - Include extended sources to be detected
- Stay tuned for updates at future SPIE meetings!