

# Achieving Future Major Astronomical Goals in Space: Promises And Challenges of Servicing and In-Space Assembly of Very Large Apertures

**Harley Thronson**

**Physics of the Cosmos & Cosmic Origins Program Offices**

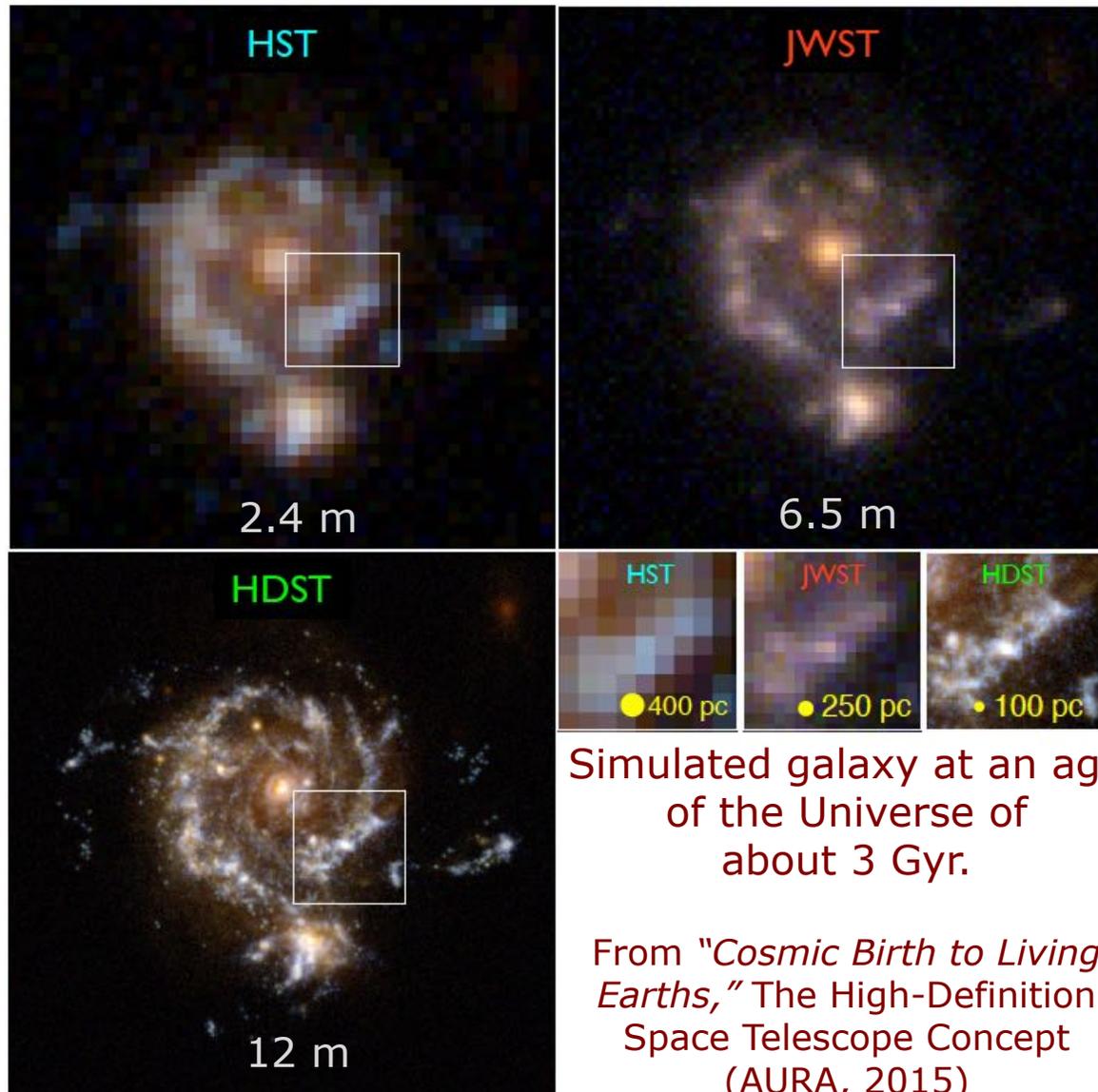
**NASA Goddard Space Flight Center**

**AND**

**The Future Assembly/Servicing Study Team (FASST)**

Supported by the NASA HQ Science Mission Directorate, Astrophysics Division

# Motivation: Cosmic Revelations Increase Rapidly with Telescope Aperture



Simulated galaxy at an age of the Universe of about 3 Gyr.

From "Cosmic Birth to Living Earths," The High-Definition Space Telescope Concept (AURA, 2015)

**With spatial resolutions achievable by apertures in excess of  $\sim 10$  meters, regions of active star formation in extremely distant galaxies can be separated from the older stellar populations.**

**The evolution over cosmic time of the star formation in galaxies can be studied in detail.**

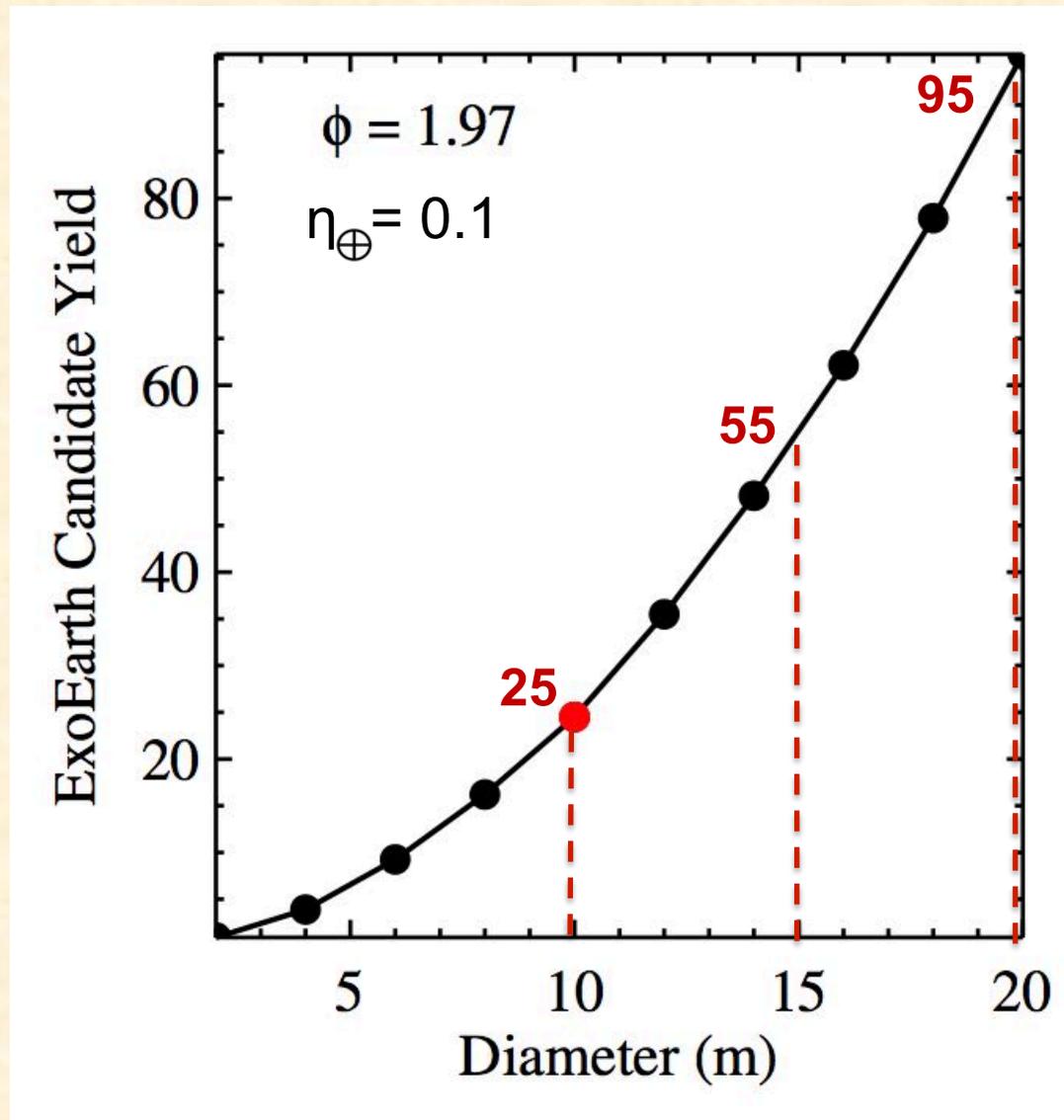
**Moreover, the dynamic structure of very young galaxies, include the presence of dwarf and colliding companions, can be revealed.**

# Motivation: Enormous Public Interest in Exoplanets: *Are We Alone?*



Multiple Thursday presentations on searches for exoplanets and required technologies.

# Exo-Planet Discoveries Increase Rapidly with Telescope Aperture



Number of candidate exo-Earths increases approximately as  $D^2$ .

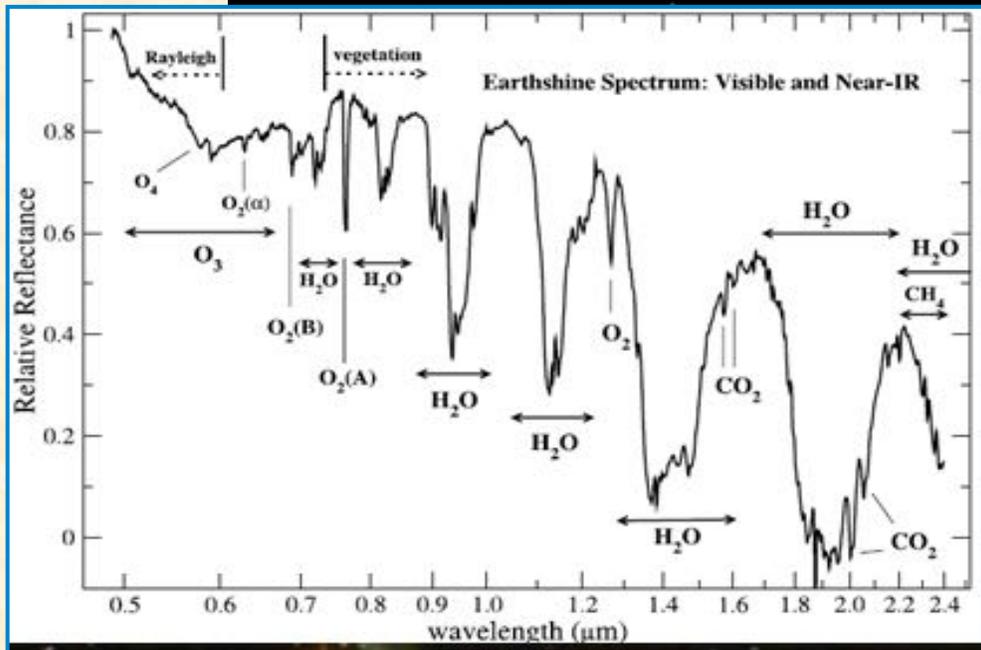
Increasing sample size will increase likelihood of discovery of an exo-Earth . . . or else put credible limits on their existence.

With  $\sim 30$  candidates and  $\eta_{\text{Life}} = 0.1$ , one life-bearing world should be detected with a confidence of  $\sim 95\%$ .

In addition, a large aperture will reduce the integration time to obtain diagnostic spectra.

Calculated number of candidate exoEarths in the solar neighborhood observed with a coronagraph, assuming the fraction of Sun-like stars orbited by an Earth-size planet in the HZ is 0.1 (Stark *et alia*, 2015).

# That is, In the Search for Life Bigger is Way, Way Better



M. Turnbull *et alia* (2006)

- Improved sensitivity to faint objects
- Improved angular resolution
- Improved spectral resolution to search for bio-markers
- Enables time-resolved images to characterize individual sections of an exoplanet

ATLAST Study Team (2015)

Exo-Earths will be *by far* the faintest celestial objects ever observed.

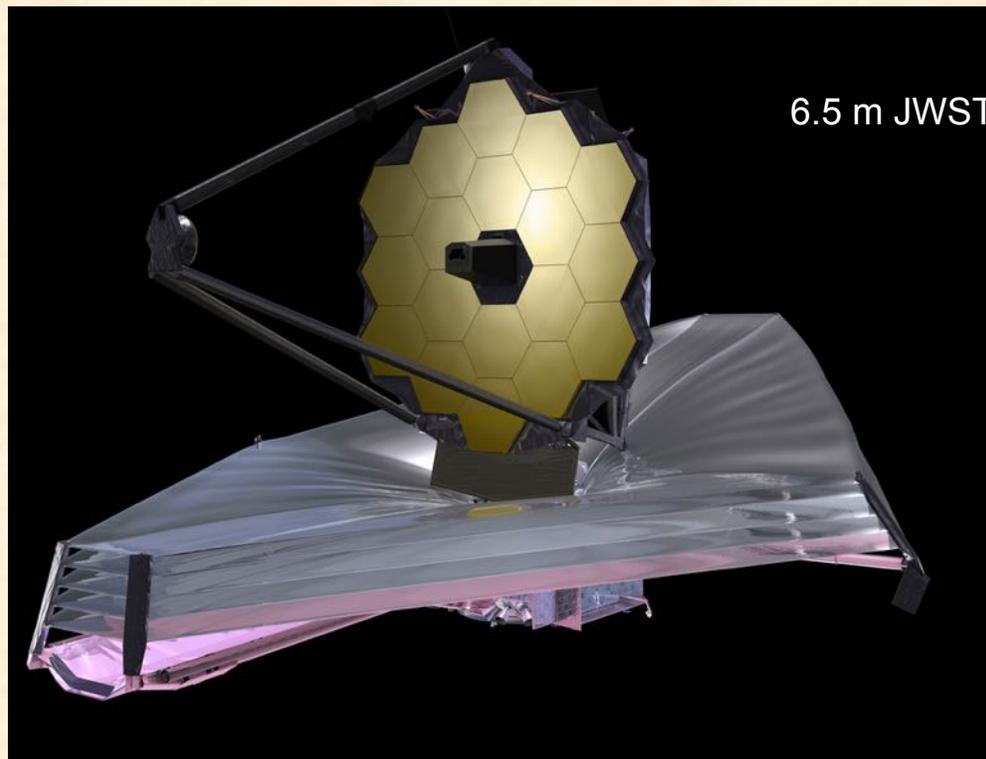
# For Self-Deployment: Telescope Size Currently Limited by LV



*“...we are now ‘hitting a wall’ in terms of the ability to build the missions we are considering, and thus novel methods may be needed, such as on-orbit assembly.” -- Scott Gaudi (OSU) Chair, Astrophysics Advisory Committee*



JWST within Ariane 5 (4.6 m fairing)



6.5 m JWST

NASA

- Falcon Heavy (5.2 m fairing) ~ 9 m telescope
- SLS Block 1B (5.2 & 8.4 m fairings) ~ 12 m telescope
- SLS Block 2 (8.4 & 10 m fairings) ~ 15 m telescope
- ? > 15 m telescope



## **Future Assembly/Service Study Team (FASST) Co-Authors**

Nicholas Siegler (Exoplanet Exploration Program Office, Caltech/JPL), FASST *Co-Chair*  
Lynn Bowman (NASA LaRC), Matthew Greenhouse (NASA GSFC), John Grunsfeld (NASA GSFC),  
Sharon Jefferies (NASA LaRC), Rudranarayan Mukherjee (Caltech/JPL),  
Bradley Peterson (OSU/STScI), and Ronald Polidan (PSSC, LLC)

## **Thank You to Colleagues**

Brendan Crill (Caltech/JPL), Howard MacEwen (Reverisco, LLC), Erica Rodgers (NASA HQ/LaRC),  
Gordon Roesler, Hsiao Smith (NASA GSFC), Todd Master (DARPA), Ben Reed (NASA GSFC),  
Chris Stark (STScI), and Al Tadros (SSL)



## In-space assembly may . . .

- **enable space telescope designs that are not limited by launch vehicle fairing size and mass constraints.**
  - Examples: > 15 meter apertures and long-baseline interferometers
  - ~15 meters is the reported maximum telescope aperture that fits in the large fairing of a future SLS Block 2
- **enable space observatories and large structures to be designed with architectures too complex to be reliably deployed autonomously.**
  - Examples: large JWST-like segmented telescopes, interferometers, starshades
- **enable the use of new materials in space**
  - Example: ultra-low weight optics and structures, that cannot be adequately tested at 1 g or safely survive launch environment in an integrated state.
- **apply increasingly capable space robotic systems**
- **employ on-site astronauts at the cislunar Gateway analogous to servicing HST**



## Potential cost savings made possible by in-space assembly (iSA):

- **Eliminates engineering design work and I&T required to (1) creatively fit large structures into existing fairings and (2) autonomously deploy**
  - JWST invested a significant effort into designing and testing the telescope's folded-wing design
- **Leverages existing, widely available, and less-costly medium-lift launch vehicles**
- **Moves architecture away from “every new telescope is a new point design”**
  - Greater commonality with preceding systems reduces development costs
  - Development may approach “assembly line” model, thus reducing “standing army” costs
- **Reduces requirements for system “ruggedization” to survive launch environment**
- **Reduces need for new and unique ground test facilities**
  - JWST required expensive new ground facilities to be built
- **Reduces need for hardware redundancy and potentially provides that *launch* failure need not be equivalent to *mission* failure**
- **Servicing allows instruments to be swapped out without having to design and build a new observatory: *Lesson #1 from HST***



**The case for space assembly of large observatories (~4 – 15-meter apertures) being less expensive than autonomous deployment has to date not been made.**

- Potential cost savings may very likely be offset with new sets of unknown challenges.
- Assessing potential cost savings is a priority activity for the NASA HQ Astrophysics Division-supported FASST studies described later.

***And, now, a few words about some of the capabilities that might be available over the next two decades to allow lower-cost assembly in space of very large observatories, beginning with the growing capabilities in space robotics . . .***

# Thumbnails of Work in this Field: In-Space Servicing and Assembly

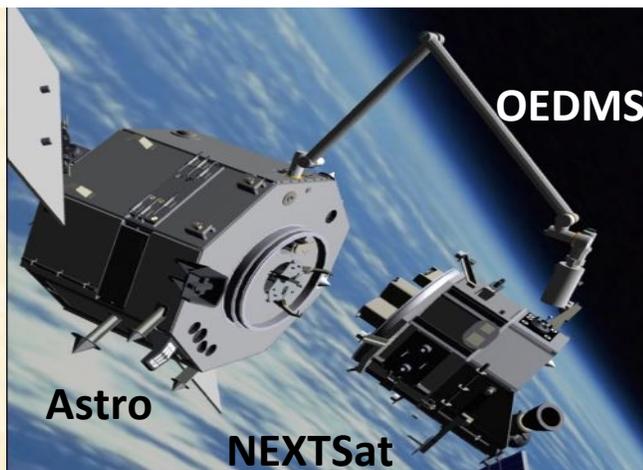


Capabilities being developed to service and eventually assemble are accelerating with government and commercial involvement.

NASA - Astronaut-Enabled Servicing



DARPA - Orbital Express



DARPA - Robotic Servicing of Geosynchronous Satellites



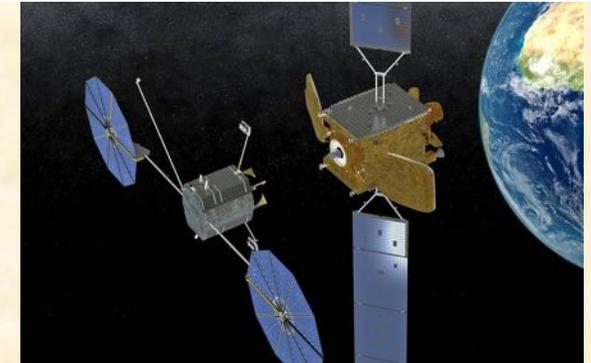
NASA - Restore-L



ISS Robotics



Orbital ATK - Mission Extension Vehicle



# The Restore-L Mission (GSFC's Satellite Servicing Projects Division)



Restore-L Advancement

## Technologies

- Relative Navigation Sensors and Algorithms
- Advanced Avionics
- Servicing Robotics
- Servicing Tools
- Fluid Transfer
- Mission Autonomy Manager
- Berthing System
- Vision System

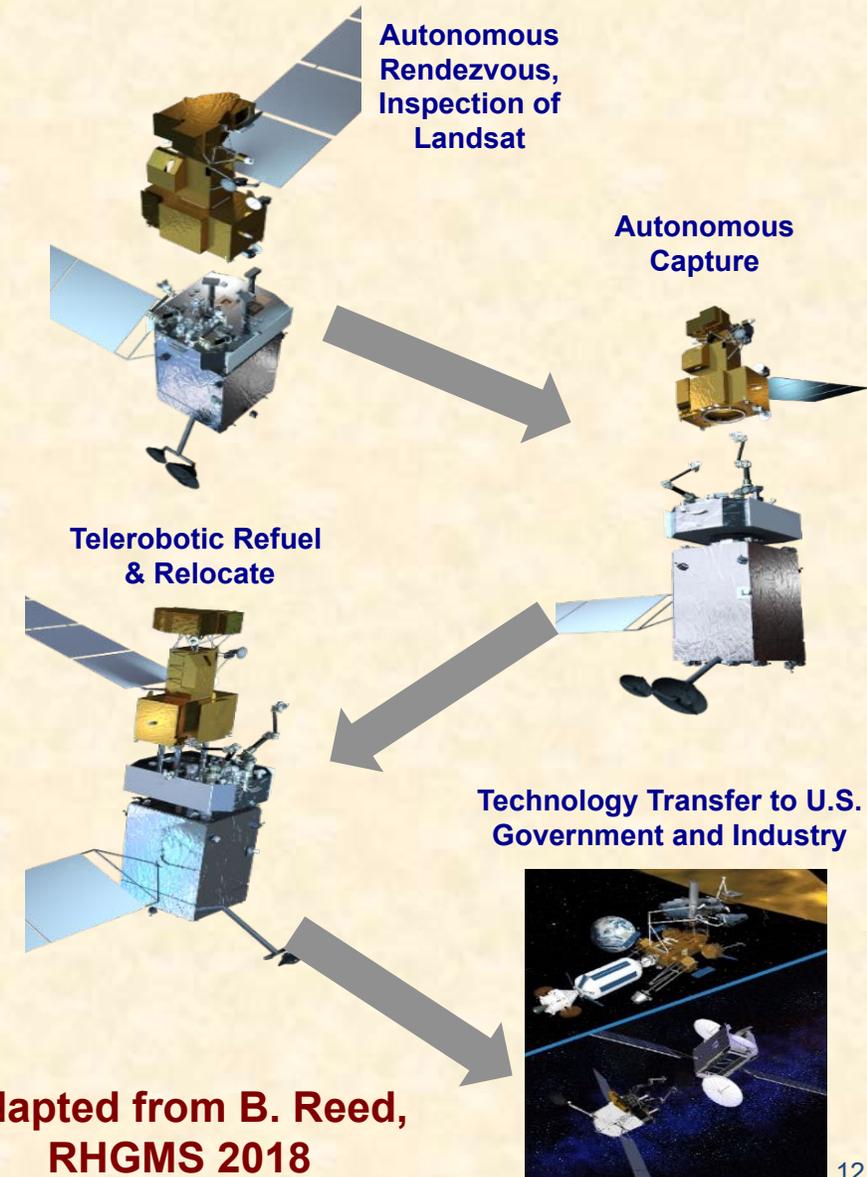
## Capabilities

- Remote Inspection
- Legacy Rendezvous
- Legacy Capture
- Legacy Refueling
- Client Relocation

Other SSPD Projects

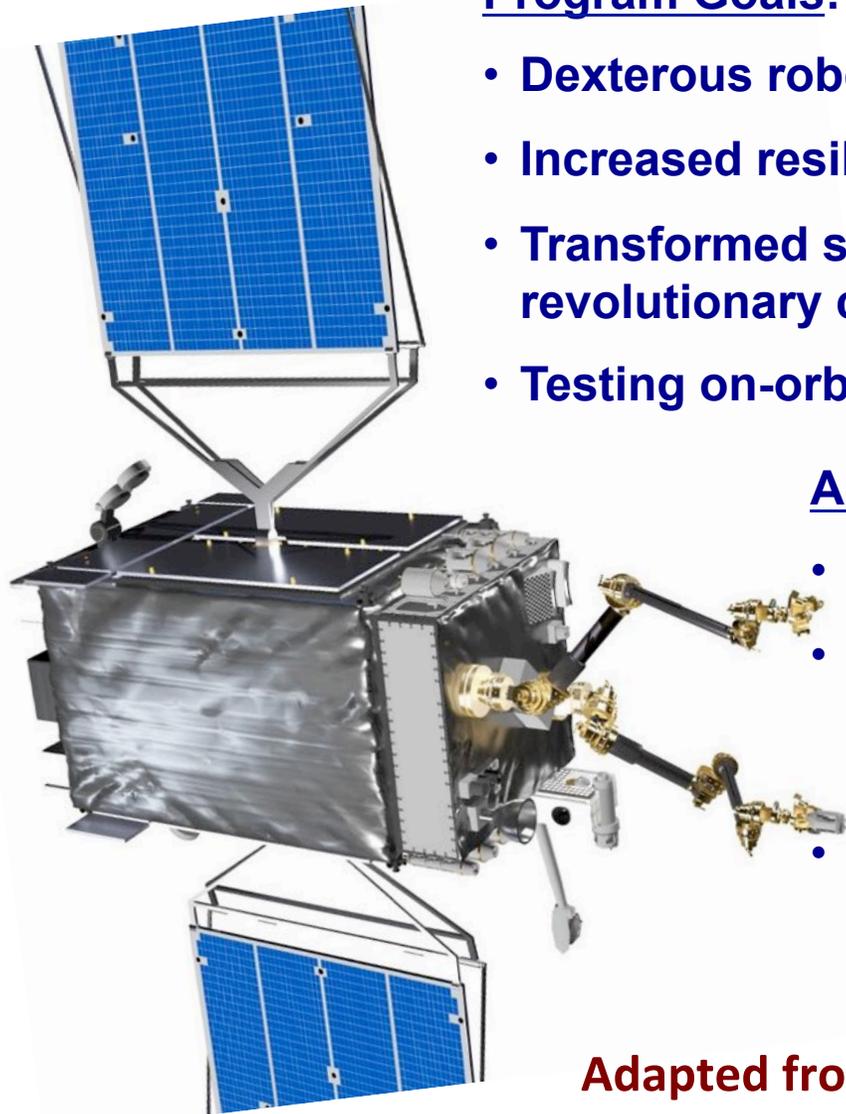
- Cryogen Transfer
- Cooperative Servicing Aids
- Xenon Transfer
- Modular Components

- Repair
- Replenish
- Replace
- Assemble



**Adapted from B. Reed, RHGMS 2018**

# Robotic Servicing of Geosynchronous Satellites (RSGS)



## Program Goals:

- Dexterous robotic capability in GEO
- Increased resilience for current infrastructure
- Transformed space architecture, revolutionary capabilities
- Testing on-orbit assembly techniques



## Approach:

- Public-private-partnership
- Major investments by both the US government and private industry
- Partners: SSL and Space Infrastructure Services (SIS)

Adapted from G. Roesler (FISO seminar; May 2, 2018)

## EXAMPLE BASELINE MISSION SET



Anomaly Correction



Install Upgrade Modules



*Artist's conception: SSL*

**Enables larger and more powerful satellites that cannot be launched fully assembled**

- packaged in pieces within a standard launch vehicle fairing
- The first step in changing the GEO infrastructure paradigm

**On-orbit robotic assembly from efficiently stowed state**

- Lower satellite mass while enabling higher satellite performance
- Commercial and government applications

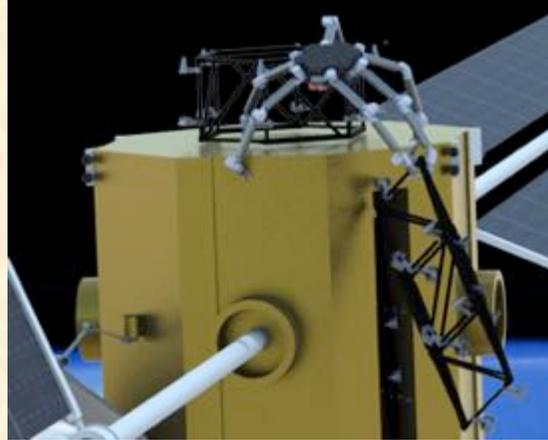
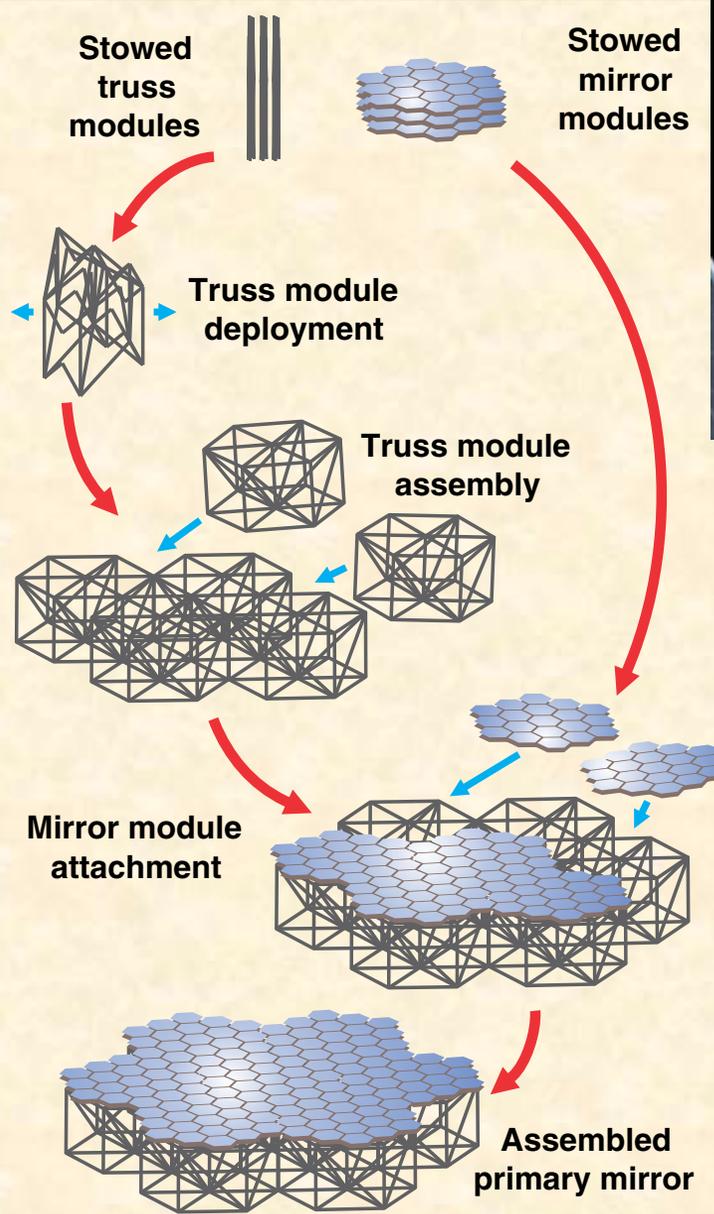
- **Robotic arm replaces traditional deployment mechanism**
- **Less cost, less weight, more reflectors**

- **Future applications:**
  - On-orbit upgrade
  - Assembly
  - Repair

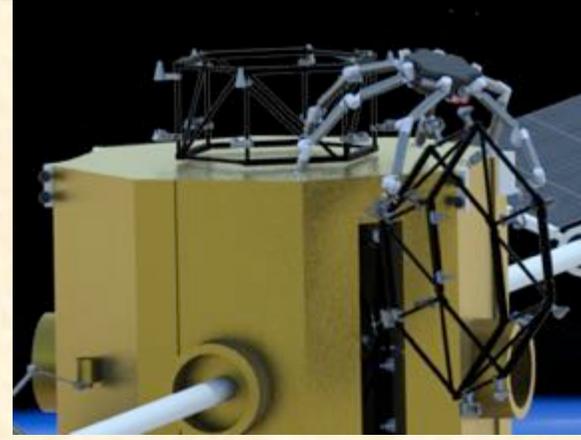
**DARPA Seedling/NASA Tipping Point Project**

**Adapted from G. Roesler (FISO seminar; May 2, 2018) and A. Tadros (RHGMS 2018)**

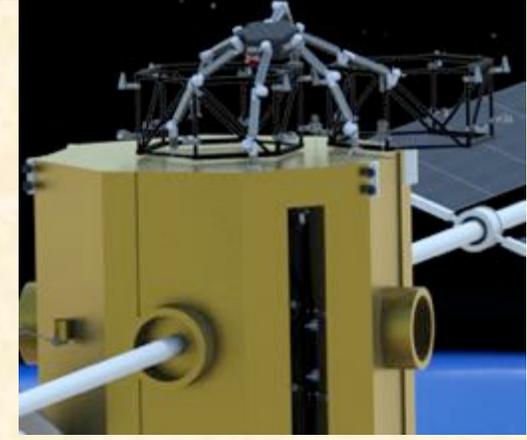
# A Concept for Robotic Large-Aperture Assembly (JPL/Caltech)



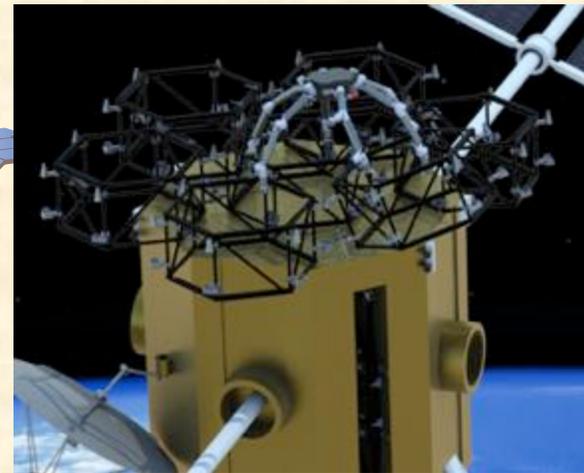
1. Extract Deployable Truss Module (DTM) from spacecraft



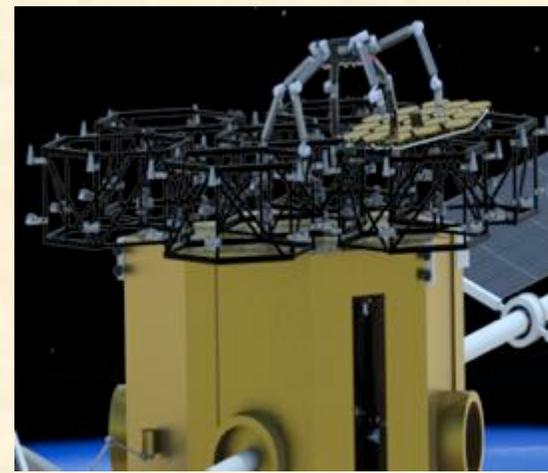
2. Deploy DTM



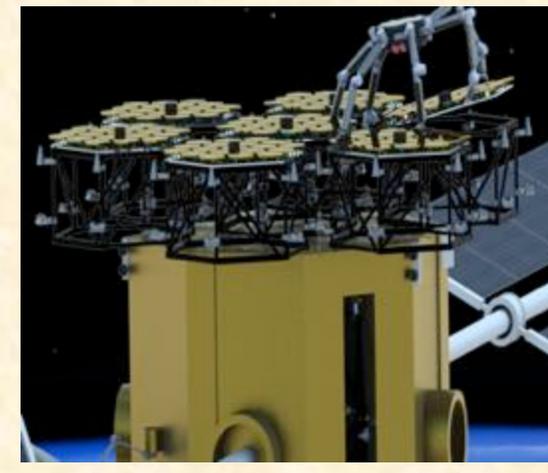
3. Assemble DTM



4. Repeat and finish backplane



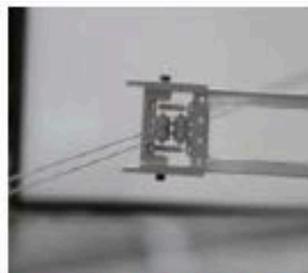
5. Assemble Mirror Module



6. Repeat and finish primary mirror

## Assembly Operations

- Long reach & dexterous manipulation
- Joining – Intelligent Precision Jigging Robot (IPJR)
- Joining – Electron Beam (E-Beam) Welding
- Joining – SBIR Technologies



Spreader Constrained Lift Off



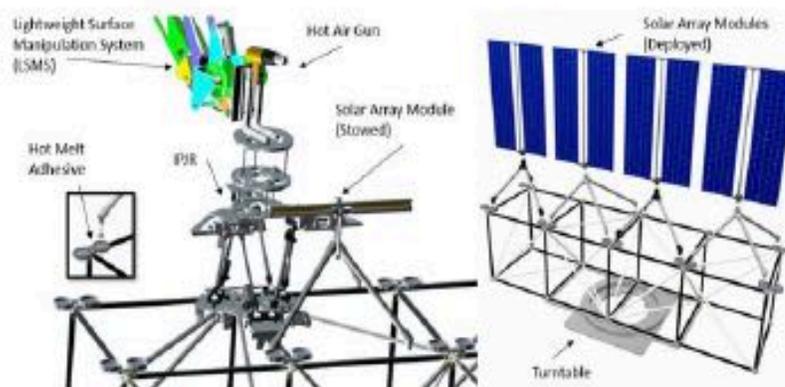
Gravity Off-Loading System



Hinge Joint



Motor/Gear-Box



# In Addition to Robotics, Astronauts May Also Be On-Site



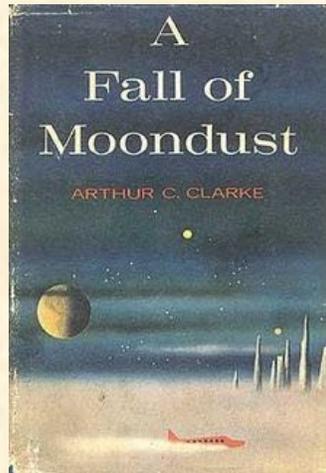
*One of the ways to cope with [pressure on the federal discretionary budget]—not to solve it—is to look for synergies between exploration and science.*

*So for example, let's look at the "Deep Space Gateway," a space station near the moon, which NASA has proposed.*

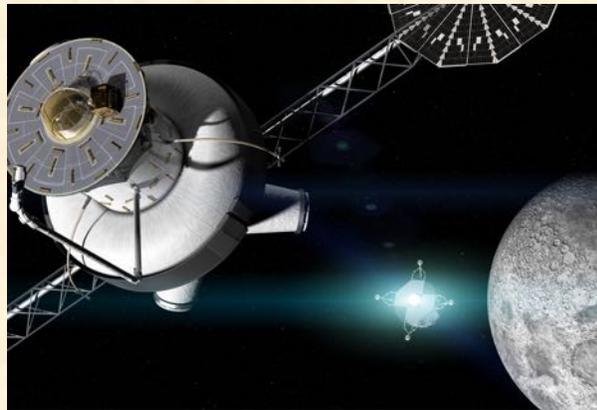
*What kinds of astrophysics or lunar science might be done using that?*

**--- Scott Pace, Executive Secretary, National Space Council, November 6, 2017**

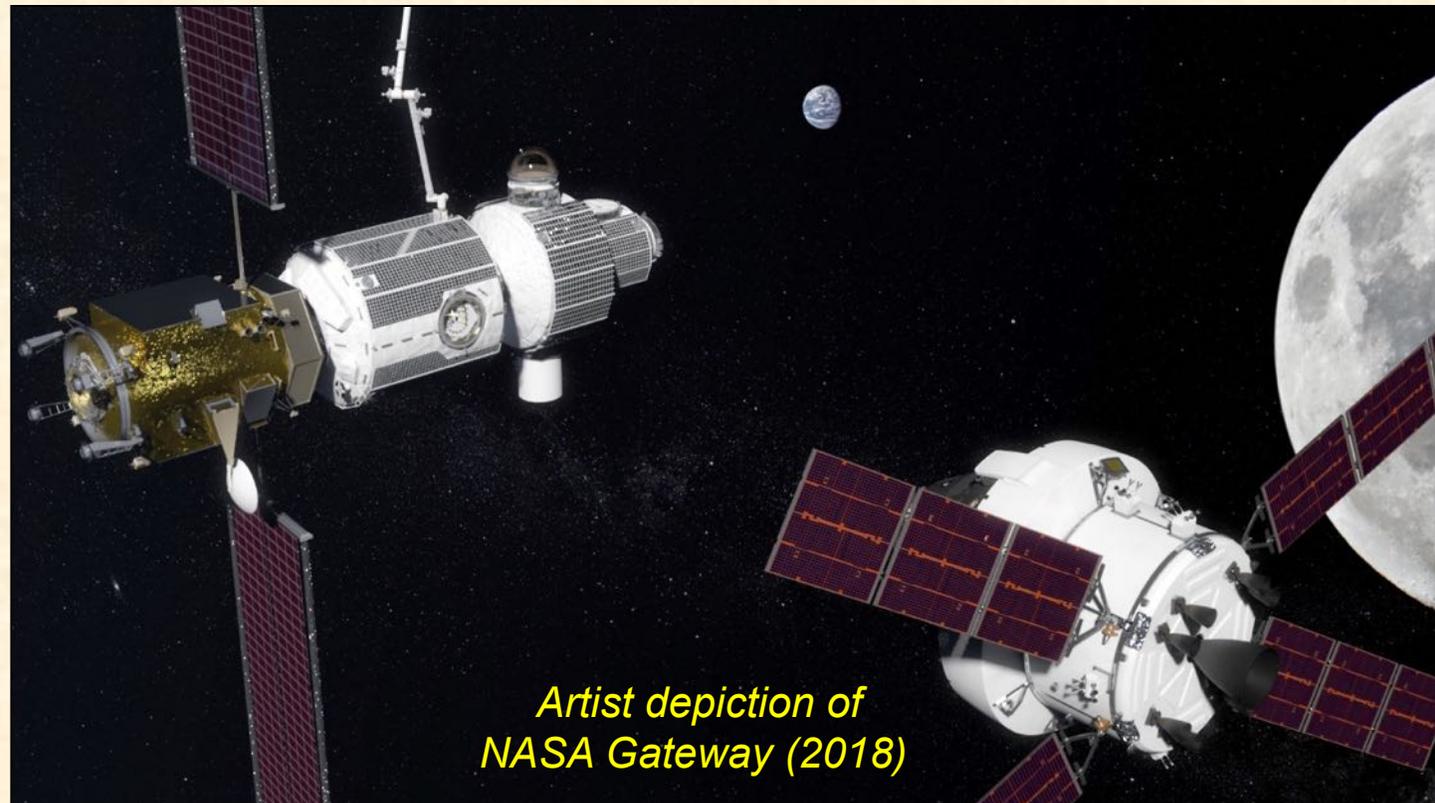
**Cis-lunar Gateways: from science fiction to early designs**



**Arthur C. Clarke  
1961**



**JF&A and Thronson  
2007**



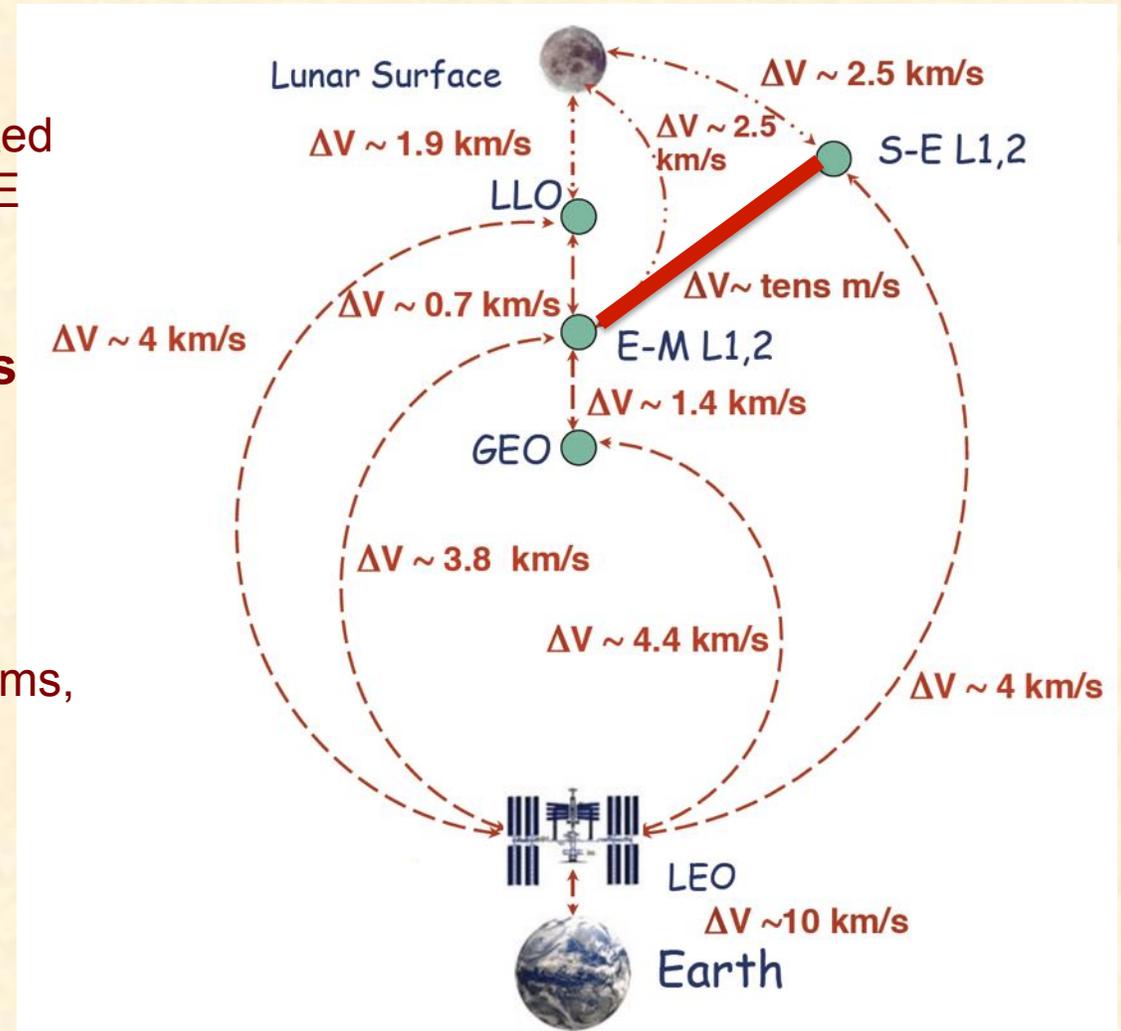
**Artist depiction of  
NASA Gateway (2018)**

# Why a habitation and operations site in cis-lunar space?



Next major human exploration “stepping stone” offers major capabilities useful to space assembly

- **Likely venue is readily accessible to Sun-Earth L2**
  - SE L2: thermally stable; Earth, Moon, Sun easily blocked
  - $\Delta v \sim 10$ s of m/s: low propulsion to go (EML1,2  $\leftrightarrow$  SE L2) for servicing
- **Expected to offer both astronaut and tele-robotics capabilities**
- **Expected to be equipped with important infrastructure**
  - High-data rate communication, versatile imaging systems, robotic arms, astronaut support
- **Analogous with Shuttle adapted to enable HST upgrade**
  - Public recognition of value to science of human space flight



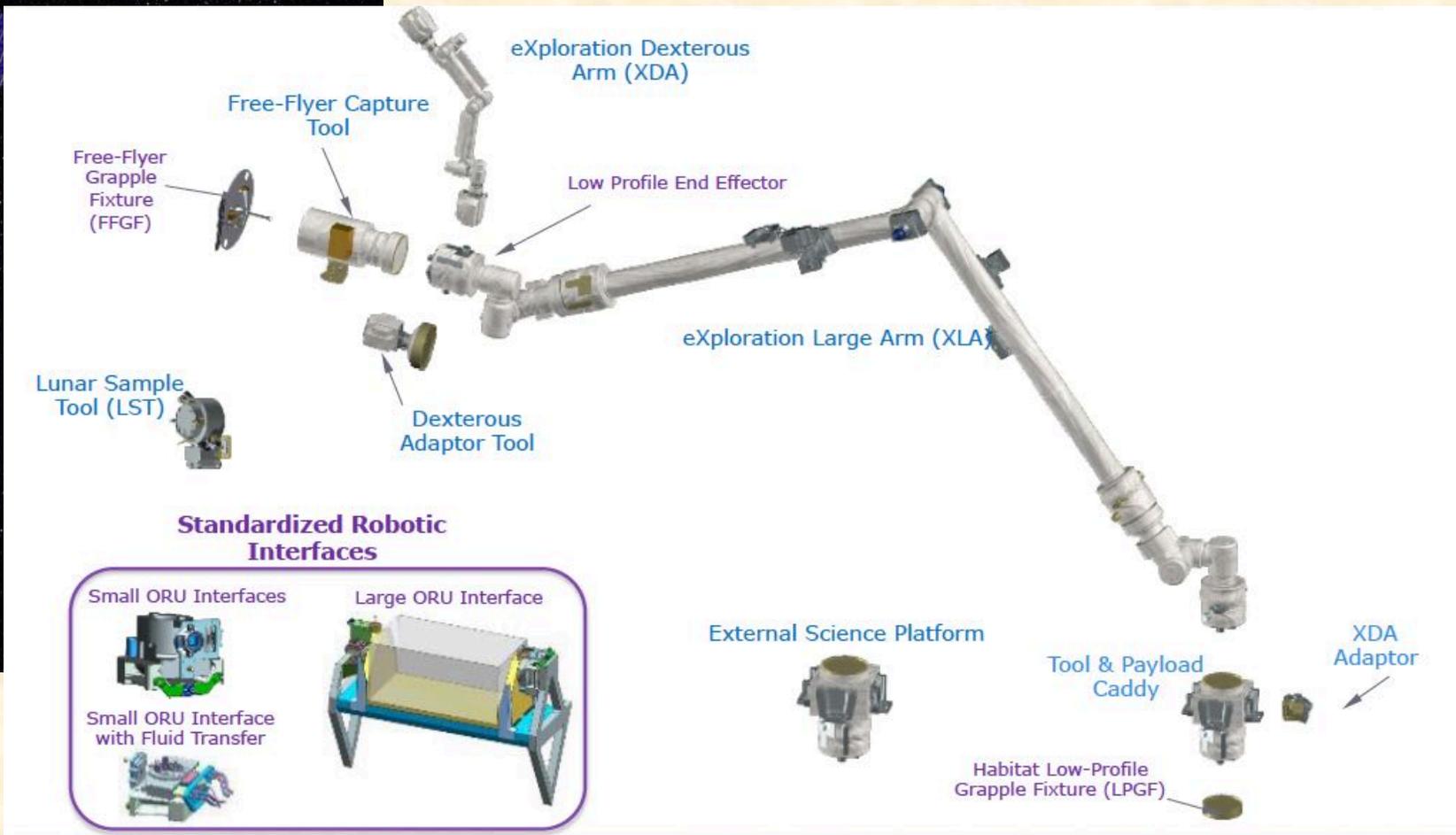
Sun-Earth-Moon transfer estimates adapted from NASA's Decade Planning Team (2000)

# Deep Space Exploration Robotics: Canadarm for the Next Decade

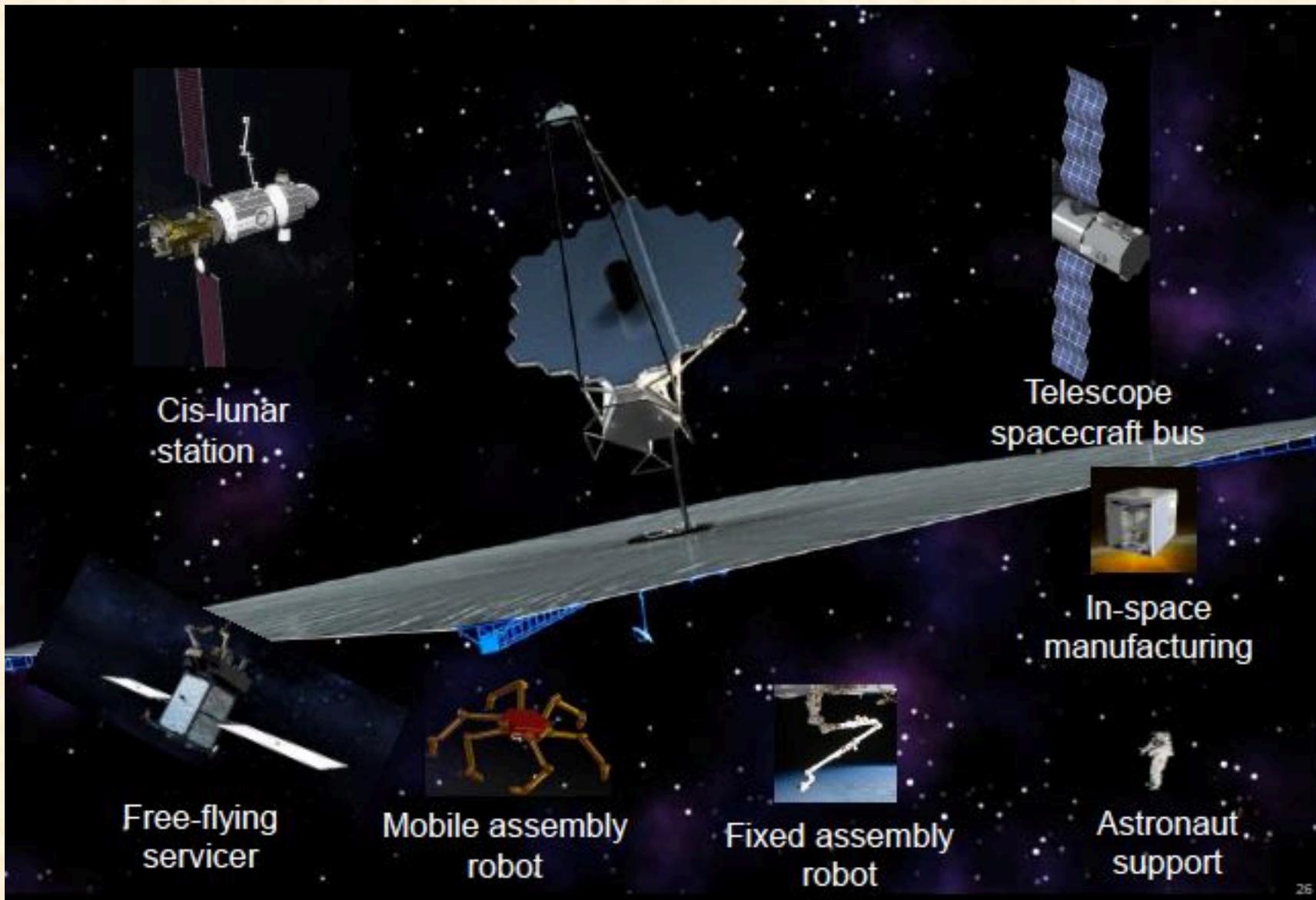


A habitation and operations site in cislunar space will require a highly capable robotic arm.

© Government of Canada 2018.  
Images courtesy MDA (Paul Fulford)  
and Daniel Rey (CSA)



# A Large “Solution Space” for Observatory Servicing and Assembly



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# In-Space Assembled Telescope (iSAT) Study

## Nicholas Siegler (Co-Chair)

Chief Technologist, Exoplanet Exploration Program Office, NASA JPL

## Rudranarayan Mukherjee (Co-Chair)

Robotics Technologist, NASA JPL

## Harley Thronson (Co-Chair)

Physics of the Cosmos/Cosmic Origins Program Offices, NASA GSFC

**Objective:** *When is it advantageous to assemble telescopes in space rather than to build them on the Earth and deploy them autonomously from individual launch vehicles?*

### Deliverables:

A report submitted to NASA HQ Astrophysics and the Decadal Survey by May 2019 that assesses

1. the telescope aperture at which in-space assembly is necessary (*an enabling capability*)
2. the telescope aperture at which in-space assembly is cheaper or lower risk with respect to traditional launch vehicle deployment (*an enhancing capability*)
3. the important factors that impact the answers (e.g., existence of HEO-funded infrastructure, architecture of space telescope (segments or other), cryogenic or not, coronagraph capable (stability) or not, etc.)
4. technology capability investments to enable in-space assembly

Info tomorrow on recent workshops and trade studies:

*Servicing and Assembly: Enabling the Most Ambitious Future Space Observatories*  
(Paper 10698-75)

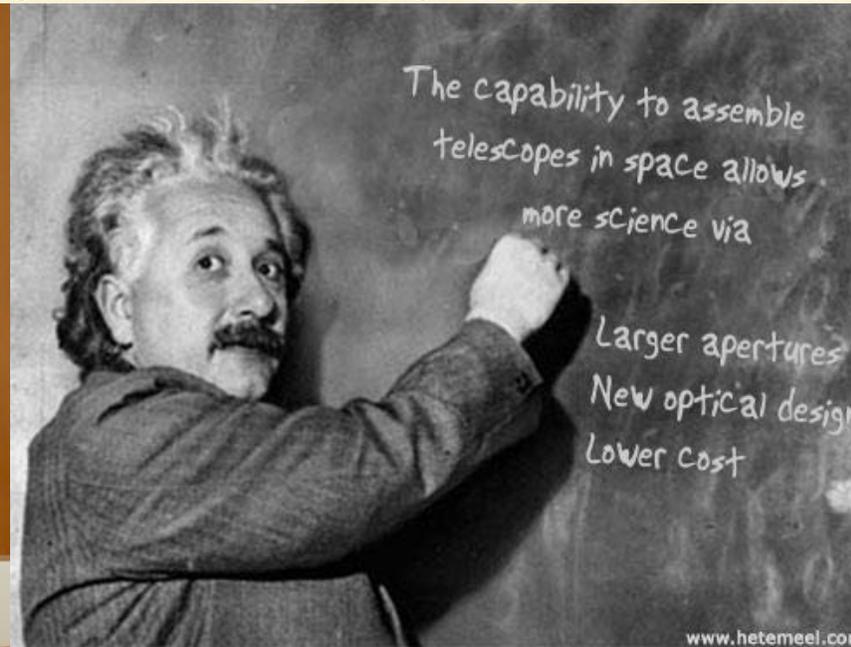
Ron Polidan *et alia*, Thursday, June 14, 4:30 – 4:50 pm

# Questions?

## Selected Images From FASST-Organized iSA Trade Study (5 – 7 June at Caltech)



David Miller (MIT)



Early Adopter



John Grunsfeld (GSFC)

## References and Additional Reading

Future Assembly/ Servicing Study Team (FASST): <https://exoplanets.nasa.gov/exep/technology/in-space-assembly/>

Future In-Space Operations (FISO) Seminar Archives: <http://fiso.spiritastro.net/archivelist.htm>

Goddard Memorial Symposium (RHGMS) 2018 Presentations: <http://astronautical.org/events/goddard/>



# **Backup/Additional Information**

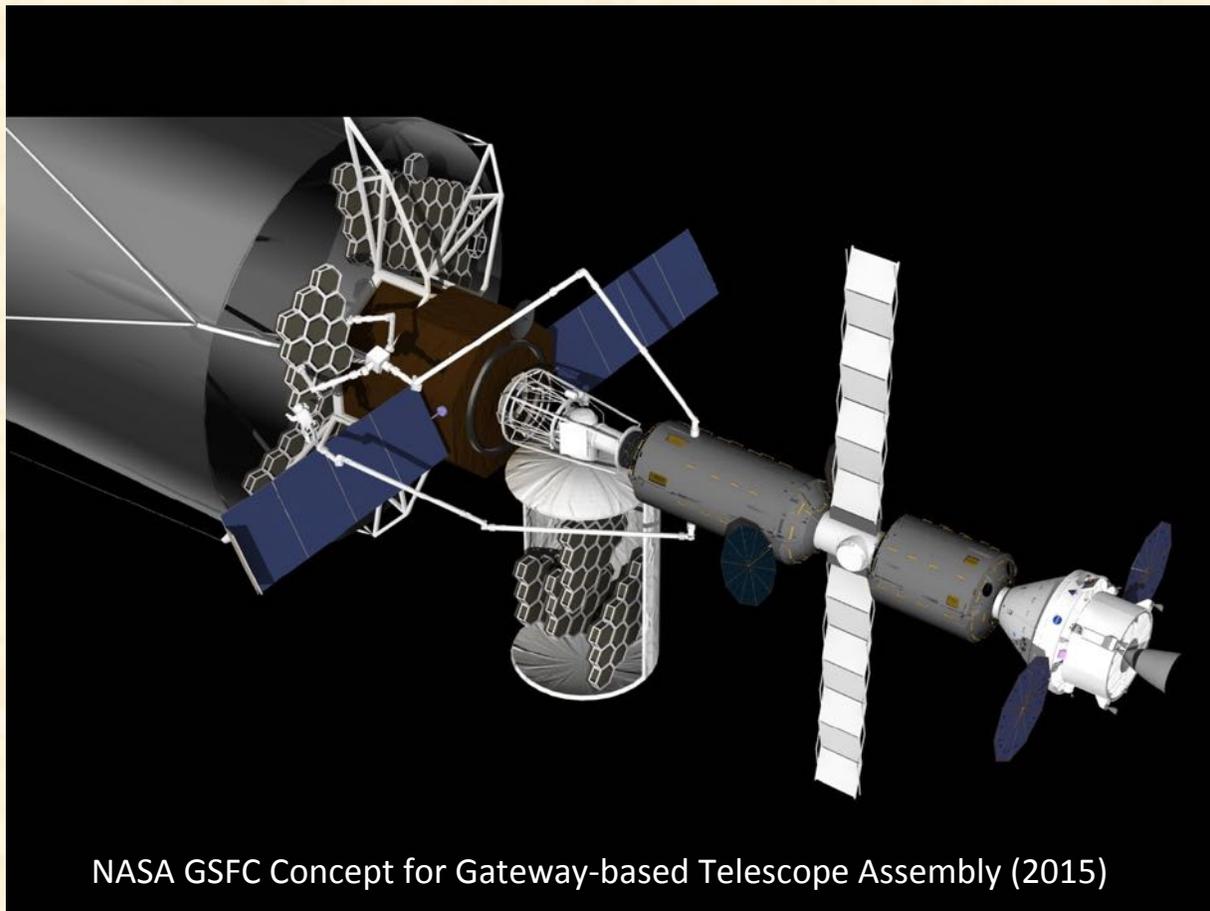
# Potential Capability Needs of the Gateway



**Proximity operations:  
Docked during  
assembly?  
Not docked during  
servicing?**

**Autonomous and  
dexterous external  
robotic arms capable  
of assembling and  
servicing**

**Berthing points for  
unpressurized cargo  
containers**



**Telerobotic  
operations from both  
Earth and the  
Gateway**

**Astronaut EVAs**

**Defined power,  
propulsion, attitude  
control**

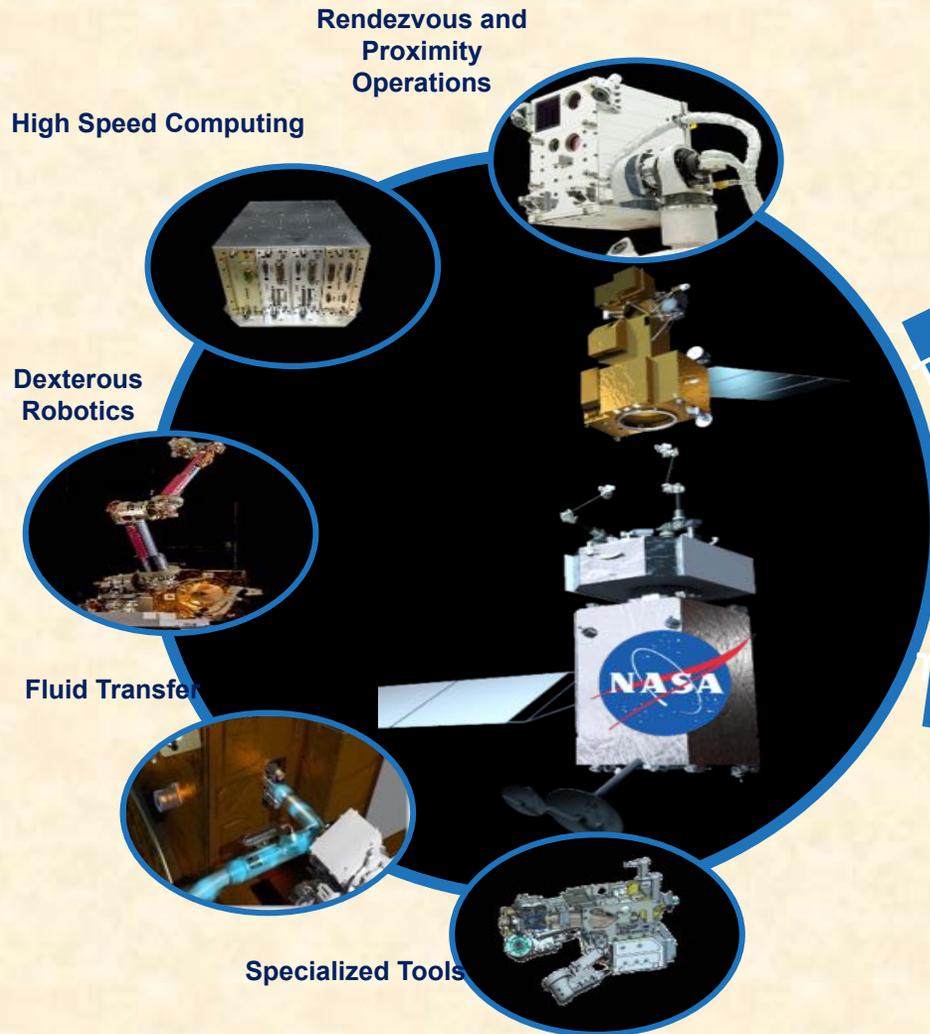
**Quiescent  
environment**

**Photogrammetry  
capabilities**

# NASA Technology Transfer Enables a Robust Servicing Industry

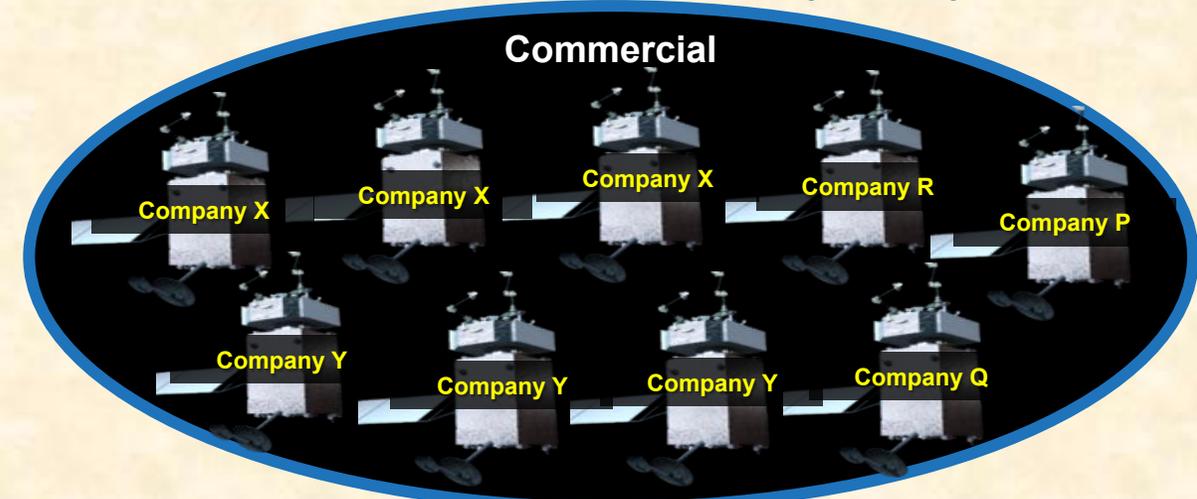


## FIRST GENERATION

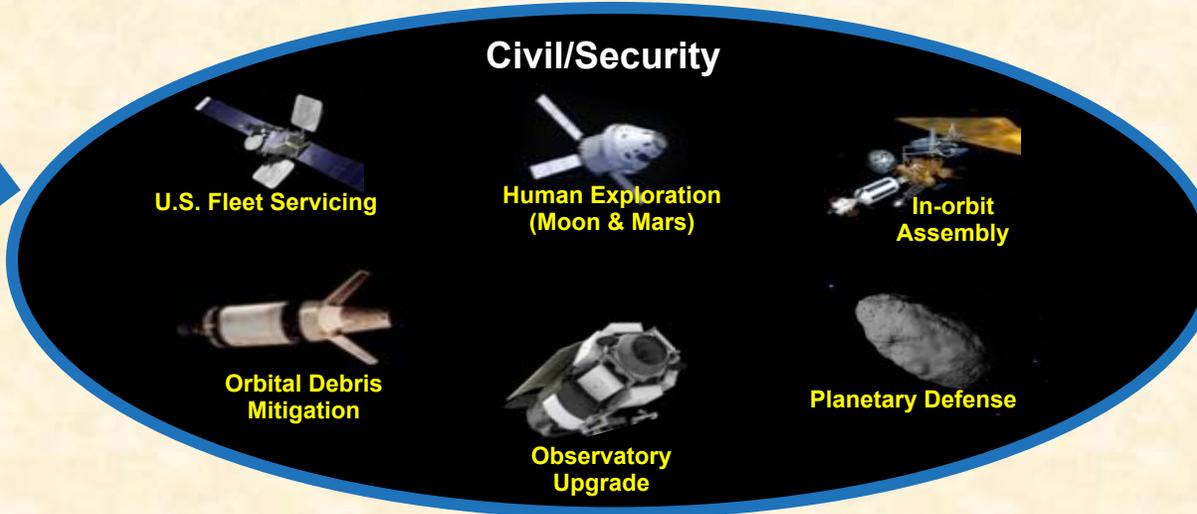


Non-recurring Engineering

## SECOND GENERATION (~2020)



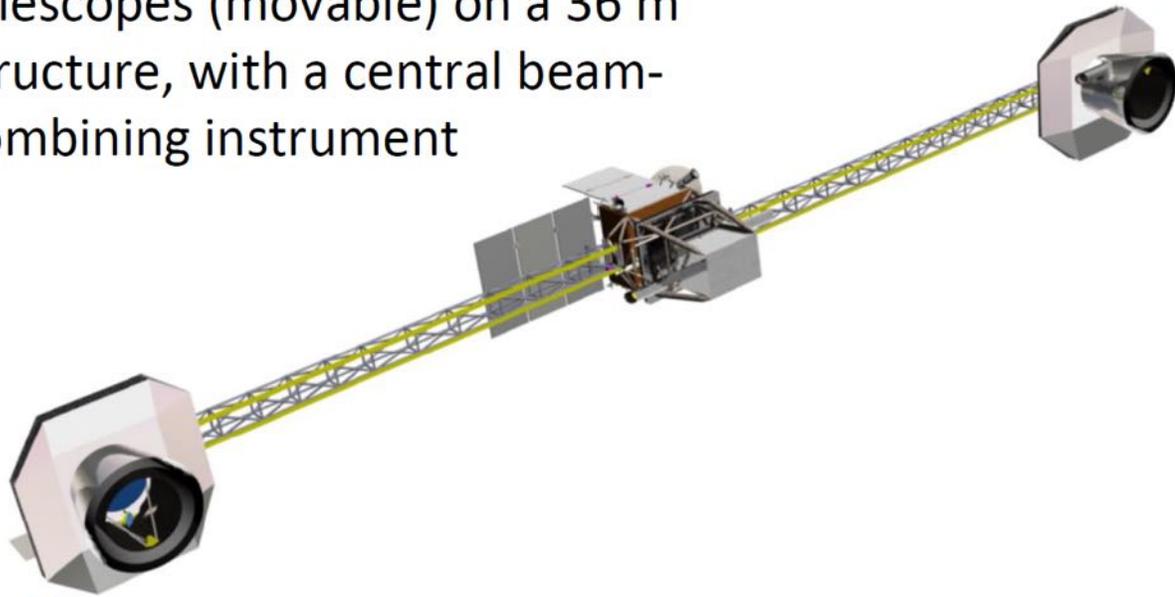
Competitive Market



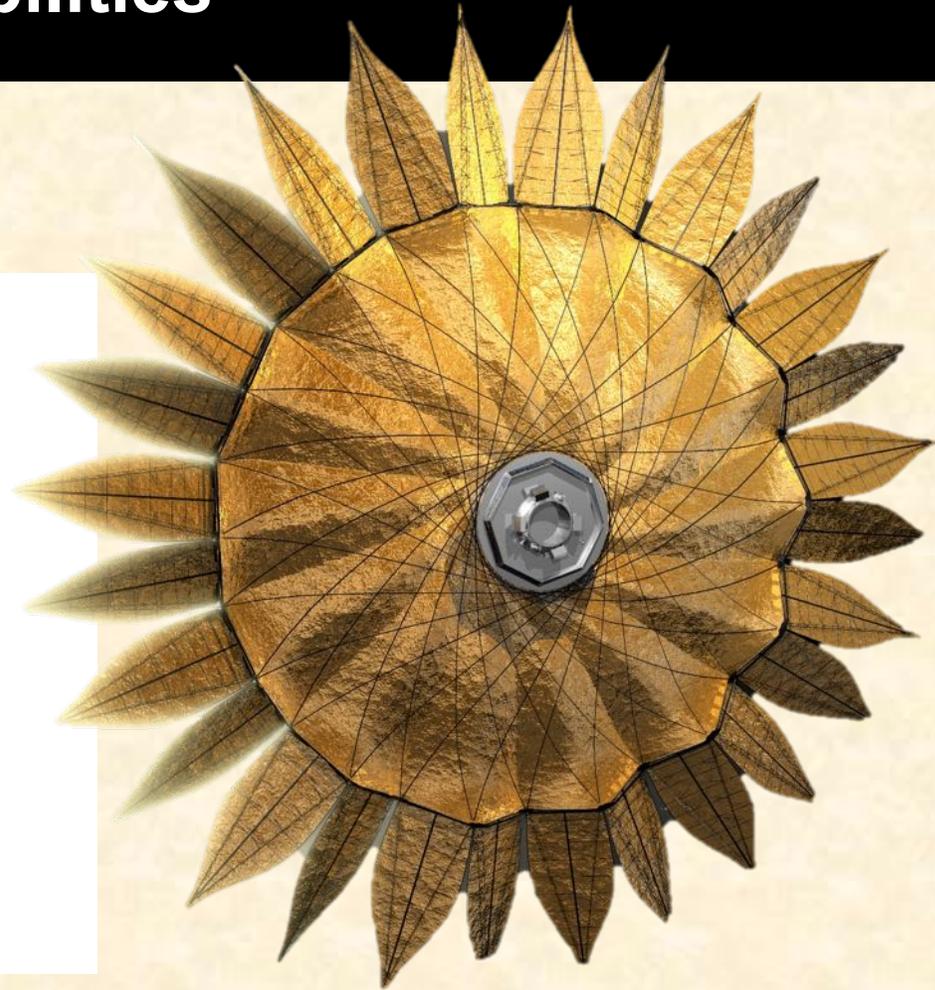
Application of Developed Technology

## Interferometers

Two 1-m diameter cryo-cooled telescopes (movable) on a 36 m structure, with a central beam-combining instrument



SPIRIT, David Leisawitz (NASA GSFC)



## Starshades

Starshade deployed to block light from central star, allowing orbiting exoplanet to be observed.



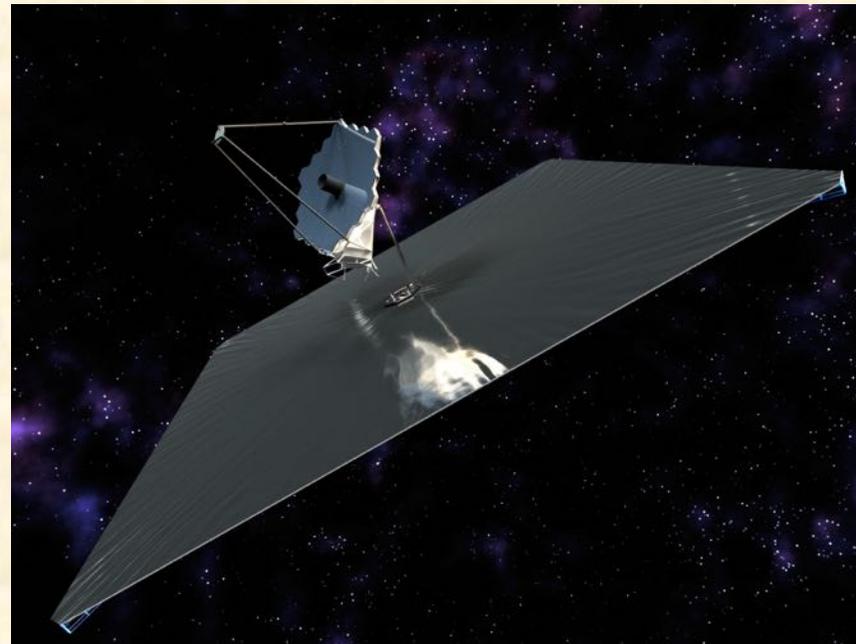
NASA/JPL/Caltech

# Summary: Assembly of Extremely Large Telescopes in Space



- Expansion of humans and their capabilities beyond LEO: robots and the Gateway
- Progressive expansion of human/robotic capabilities
- Feed forward of technologies
- Breakthrough science: the very early Universe, *Are we alone?*

HEAVY LIFT, LOW-COST MEDIUM LIFT  
DEVELOPMENT IN ROBOTICS  
HABITATS & AIRLOCKS  
EVA & MOBILITY  
TOOL & MANIPULATORS  
ON-BOARD METROLOGY  
SEGMENTED MIRRORS  
STANDARD INTERFACES  
LOW-THRUST PROPULSION



DEEP-SPACE HUMAN OPERATIONS  
HUMAN/ROBOTIC INTERACTIONS  
MODULAR ASSEMBLY  
SCALABLE ARCHITECTURES  
LOW-THRUST DELIVERY  
SPACE OBSERVATORIES  
BREAKTHROUGH SCIENCE  
NATIONAL SECURITY

*INPUT CAPABILITIES*

*OUTCOMES/  
FEED FORWARD*

LOGISTICS

First robotic capabilities in GEO

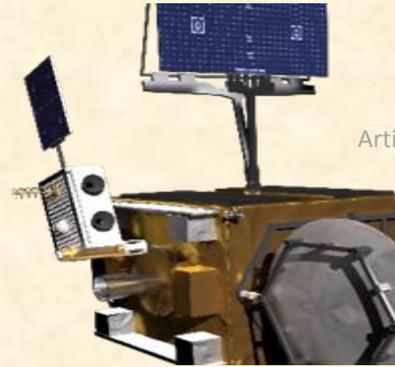


Artist's Concept



Artist's Concept

POD



Artist's Concept

OAC Capability



NASA

Fully automated space logistics

*First steps in GEO logistics*

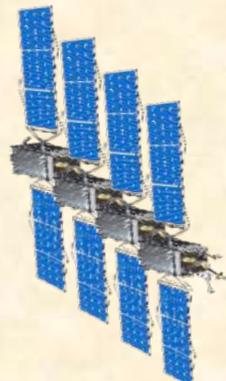
REPAIR ♦ REPOSITION ♦ INSPECT ♦ AUGMENT



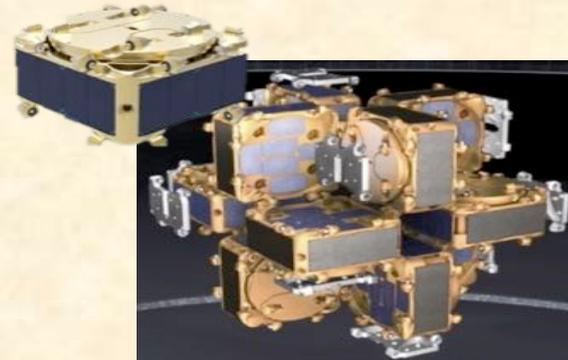
Technology development and investment

CONSTRUCTION

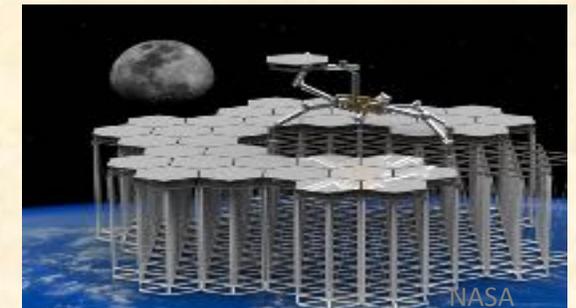
Expanded coverage, new tools, experiments



Modular spacecraft with on-orbit replaceable units



Large apertures, structures, and bases



NASA

Adapted from Roesler (FISO seminar; May 2, 2018)