

#### NASA Exoplanet Exploration Program

#### **The Coronagraph Technology Roadmap Working Group** Final Report

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- This document has been reviewed and determined not to contain export controlled technical data.
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## 1. Participants



#### **Participants**



- NUV Design-Point Lead: Roser Juanola-Parramon (GSFC)  $\bullet$
- Vis Design-Point Lead: Vanessa Bailey (JPL)  $\bullet$
- NIR Design-Point Lead: Olivier Guyon (NAOJ)  $\bullet$
- UV Target List: Eric Mamajek (ExEP), Karl Stapelfeldt (ExEP), Dmitry Savransky (Cornell)  $\bullet$
- **EBS Validation & UI Lead: Sarah Steiger (STScI)**  $\bullet$
- Detector & Dichroic-Beamsplitter Fact Finding: John Trauger (JPL)  $\bullet$
- Hybrid Lyot Coronagraph Design & Segment Edge Roll-off Simulation Software Lead: Dwight Moody (JPL)  $\bullet$
- Coating Uniformity Sensitivity Analysis: John Krist (JPL)  $\bullet$

Special thanks to Ms. Angel Zhu (formerly JPL, now Harvard) for graphic design of the roadmap chart on p. 13



## 2. Executive Summary of Findings



#### **Executive Summary**

- We summarize our findings in terms of coronagraph technology gaps to achieving TRL 5 for the Habitable Worlds Observatory
- The impact of each gap is quantified using the Provisional Key Driving Requirements (Section 3). Their derivation utilized the open-source Error Budget Software (EBS) developed under CTR, with comparisons to relevant literature.
- The gaps sizes are based on current State of the Art (Section 4).
- This report is a roadmap to reducing these gaps (by advancing SotA) Impact:

Low: insignificant to small reduction in projected mission return Medium: moderate reduction in projected mission return High: significant reduction in projected mission return

#### Gap size:

Small: Requirement < 2 x SotA performance Medium: Requirement < 10 x SotA performance Large**:** Requirement > 10 x SotA perfromance

Priority for technology road maps:

Dark blue: Invest immediately in multiple technology options, including emergent technologies where appropriate. Balance portfolio in consideration of impact.

Medium Blue: Invest timely in SotA technologies. Balance portfolio in consideration of impact

Light Blue: Advance existing technologies with appropriate timeline





The Coronagraph Technology Roadmap

#### **Ex[ecutive Summary](https://github.com/chen-pin/ebs)**

- After summarizing the top gaps, this report substantiates the gap evaluations in terms of assumed/provisional [requirements and](https://exoplanets.nasa.gov/exep/)  technological SotA (Section 5).
- The rest of the report presents a maturation plan that builds upon **v** lear[n from the Roman Spac](https://exoplanets.nasa.gov/exep/)e Telescope Coronagraph Instrument ( Coronagraph or "CGI") (Section 6). We first present Required V&V facilities (Section 7) and then the actual maturation plan (Section 8).
- We developed EBS and used it to derive many key provisional requirements. Full documentation of the computation settings and will be available on the code repository by the end of August 2024: https://github.com/chen-pin/ebs
- **This report focuses on identifying technology gaps and maturation schedule. For potential technological solutions, we reference the following recent reports and publications:**
	- ExEP Coronagraph Design Survey Working Group (Co-Leads: R. Belikov, C. Stark), 2024, "The Coronagraph Design Survey Final Report" (will be posted at https://exoplanets.nasa.gov/exep
	- ExEP Deformable Mirror Technology Roadmap Working Group (Co-Leads: E. Bendek, T. Gro 2024, "The Deformable Mirror Technology Roadmap Working Group" (will be posted at https://exoplanets.nasa.gov/exep/)
	- ExEP Coronagraph Technology Roadmap UV Design Point Team, 2024, "A near-ultraviolet co instrument study for the Habitable Worlds Observatory"
	- N. Jovanovic, et al., 2023, "2023 Astrophotonics Roadmap: pathways to realizing multi-functio integrated astrophotonic instruments," J. Phys. Photonics, 5, 042501, DOI 10.1088/2515-7647

#### **Executive Summary**

- **All gaps are based on SotA performance (not projected future performance)**
- **WFE-Stability Environment Gap.** The coronagraph instrument is not able to achieve required contrast noise floor for planet detection in relevant environment of observatory and DMs WFE instabilities. **Large gap, High impact.**
- **Starlight-Suppression-Optics Subsystem Gap**. Starlight-suppression optics do not meet static performance (throughput, IWA/FoV, raw contrast, wavelength, and bandwidth) requirements to enable mission exoplanet yield. NUV and NIR testbed capabilities need to be developed. Development of a standalone UV instrument might be necessary. NIR coronagraphy/spectroscopy might require emergent technologies. **Medium gap for Vis, Large gap for UV & IR, High impact.**
- **Mission efficiency Gap.** HWO design concepts utilize dichroic beam splitters for multichannel observations. Such optics have never been tested. **Large gap, Medium impact.**
- **Detectors Gap:** Detectors do not meet noise, dynamic range, and lifetime requirements. **Small gap for imaging, Large gap for spectroscopy, Medium impact (imaging) High impact (spectroscopy).**



#### **Executive Summary**

- **Deformable Mirrors Gap.** DM subsystem not meeting actuator count, stability, surface, mass/volume, and/or schedule requirements. **Large gap for actuator count, Medium gap for everything else, High impact**.
- **Algorithms Gap.** Starlight-Suppression and post processing. Dark-hole-digging algorithms not able to compute solutions. Post processing enhancement insufficient for required planet detection/characterization. **Medium gap, Medium impact.**
- **Modelling Gap**. Model does not capture all contributions to instrument noise floor. Knowledge gap. **Large gap before CGI flight, Medium gap after Roman Coronagraph flight, High impact.**



The Coronagraph Technology Roadmap

#### **Executive Summary**



#### **This report discusses how to advance technologies to close gaps**



### **Timeline Assumptions**

- Astro2020 recommended that crucial technologies reach TRL 5-6 before the Independent Review. Astro2020 envisioned that HWO technology development to take 6 years, requiring \$800M (FY2020) total technologymaturation investment. Therefore, we assume a timeline of six years starting from initiation of funding flow approximating at least  $\sim$  \$100M/year (in 2020 dollar) to reach TRL 5. For example, if this level of investment starts in October 2025, the envisioned TRL-5 completion can occur by September 2031.
- Based on the current HWO plan, HWO can reach CML 4 by mid 2026, which will provide key definitions for technology development:
	- Draft STM produced and **driving requirements documented**
	- Initial high level scenarios, timelines and **operational modes documented**
	- **System architecture & instrument designs described by mechanical configuration drawings**
	- **Instrument performance requirements** traced to level-1 requirements
	- **Technology options characterized and baseline options selected and justified**



### **Maturation Plan: Notional Baseline**

- The next slide shows our roughly estimated maturation schedule to meet the sixyear timeline described in Astro2020
- We posit that the different critical technology elements (starlight suppression optics, adaptive optics, full-scale DMs, etc.) can be matured and validated independently for TRL-5, with clearly defined interface requirements between elements
- We derived notional timescales using the following boundary conditions
	- Overall timeline for developing critical HWO technologies is six years, based on Astro2020
	- The six year clock starts when NASA begins investing in HWO technology on the  $\sim$  10<sup>8</sup> \$/yr scale
	- The overall timeline show comprises the above-mentioned six years plus a lead-in period (starting now)
	- Within each development tack of critical technology element, we estimated the relative required timescale for each phase and fit the end-to-end timescale into the overall timeline
- As such, this is *not* a grass-roots-estimated schedule
- The end of each arrow-shaped bar represents a milestone (in accomplishing the corresponding task/objective)
- **Whether or not the envisaged schedule can be accomplished depends on invested resources**



#### **Maturation Plan: Opportunities**

- The next slide shows opportunities in risk reduction by integrating different critical technology elements before TRL 5
- Each critical technology element is represented by a different symbol.
- Appearance of a symbol in the track of another critical technology element represents an integration opportunity





#### **Executive Summary**

#### **Key findings:**

- Multiple vacuum testbeds are necessary. At least one per bandpass (UV/VIS/IR) and one dedicated to wavefront stability (AO).
- DM development needs to start as early as possible.
- System level risk will be carried by model. Significant testbed ressources need to be invested for model validation.
- Multiple opportunities for system-level risk reduction exist after year 2.
- See recommendations in Sec. 5 "Gap Details"



## 3. Deliverables, Scope, & Assumptions



### **CTR Deliverables**

- 1. Presented and served as panelist at the "Starlight Suppression Technologies for the IR/O/UV Flagship" splinter session, AAS Meeting, Seattle (Jan 2023)
- 2. Submitted CTR task plan for ExoTAC review (May 2023)
- 3. Delivered DM Spatial-Temporal Stability Requirements to DMTR (Jun 2023)
- 4. Delivered requirement on inter-segment reflectance uniformity to USORT (Jun 2023)
- 5. Produced a provisional HWO UV Target List (Jul 2023)
- 6. Presented at the "Science with the Habitable Worlds Observatory and Beyond worksop," Baltimore, (Jul 2023)
- 7. Presented at the "Towards Starlight Suppression for the Habitable Worlds Observatory Workshop," Pasadena (Aug 2023)
- 8. Developed open-source Error Budget Software (EBS) (Sep 2023)
- 9. Co-authored the "UV Technology to Prepare for the Habitable Worlds Observatory" white paper (Sep 2023)
- 10.Briefed HWO TAG on CTR work (Dec 2023)
- 11.Briefed HWO TAG on Coronagraph Technology Focus Areas (Dec 2023)
- 12.Supported development of HWO's Coronagraph Exploratory Cases (Feb 2024)



### **CTR Deliverables (cont'd)**

- 13.Briefed HWO Integrated Modeling Working Group on end-to-end modeling for investigating exo-Earth yield sensitivity to dynamic wavefront error (WFE) with coronagraph AO (Mar 2024)
- 14.Participated in HWO Exoplanet Science Yield Working Group's Exposure-Time Calibration task (Mar 2024 - present)
- 15.Produced the "UV Coronagraph Point Design" white paper (May 2024)
- 16.Delivered the Coronagraph Technology Roadmap Final Report (May 2024)
- 17.Will present ExEP Technology Colloquium Series Talk: The Coronagraph Technology Roadmap (June 2024)
- 18.Presented at SPIE conference, "A standalone UV coronagraph instrument for the Habitable Worlds Observatory," Juanola-Parramon et al. Yokohama, (Jun 2024)
- 19.Presented at SPIE conference, "Simulated performance of microwave kinetic inductance detectors towards exoplanet imaging with the Habitable Worlds Observatory," Steiger et al., Yokohama, (Jun 2024)
- 20.Presented at SPIE conference, "A Coronagraph Technology Roadmap for Future Space Observatories to Directly Image Earth-like Exoplanets," Chen et al., Yokohama, (Jun 2024)



### **Scope**

#### Driving Question: **Where and when does NASA need to invest in coronagraph technology to enable the Habitable Worlds Observatory?**

**Objectives** 

- 1. Create a roadmap for coronagraph technologies to reach **TRL 5** for the Habitable Worlds Observatory and describe the path to TRL 6
	- Identify viable coronagraph technology candidates while incorporating insights from CGI and basing on LUVOIR and HabEx studies wherever relevant
- 2. Formulate tasks that ExEP/HCIT should conduct to achieve critical objectives—e.g. **1010 contrast demonstration**

Scope

- 1. We treat the coronagraph as a system that includes adaptive optics (aka WFS&C or LOWFS), starlight-suppression optics, detector, and postprocessing
- 2. We treat the observatory as a critical part of the relevant *environment* in which the coronagraph must perform



### **Operating Assumptions: Mission Architecture**

- 1. Any mission architecture we study must be feasible for launch in the first half of the 2040s
- 2. The observatory is the most significant part of the *relevant environment* in which the coronagraph must perform
- 3. We assume a segmented telescope with a coronagraph as the reference architecture.
- 4. Telescope diameter is 6 meters, with characteristics compatible w/ USORT
- 5. The telescope will have IR, vis, and UV capabilities (but not necessarily the coronagraph instrument)
- 6. The telescope primary aperture will be at least 6-m in inscribed diameter
- 7. In-space robotic servicing will be available (e.g. to refurbish the telescope, refuel, update instruments)
- 8. The telescope will be starshade compatible
- 9. The telescope will be off-axis with the primary-mirror geometry shown below (8 mm gaps between segment edges)
- 10. Based on the LUVOIR and HabEx reports, we assume the primary molecular targets are  $H_2O$ ,  $O_2$ , and  $CO_2$ , while  $O_3$  and  $CH_4$  are highly desirable.
- 11. UV and IR are used only for follow-on characterization, with known location of the planetary target to relax coronagraphic FoV (i.e. dark-hole area) requirements.
- 12. We assume an observing scenario similar to that of the Roman Coronagraph



The Coronagraph Technology Roadmap

## **Op[erating Assumptions: Fiducial Stars](https://exoplanetarchive.ipac.caltech.edu/cgi-bin/TblView/nph-tblView?app=ExoTbls&config=DI_STARS_EXEP)**

- Purpose: To formulate provisional requirements, we select fiducial targets drive exposure time calculations & error budgeting
- **Approach** 
	- Include F, G, and K spectral types
	- Fiducials stars should drive coronagraph performance for  $\sim$ 100 eftective of  $\sim$ HZs: minimal zodi, small HZ separation
- Selection strategy
	- Start with the HWO ExEP Precursor Science Stars list: https://exoplanetarchive.ipac.caltech.edu/cgi-bin/TblView/nphtblView?app=ExoTbls&config=DI\_STARS\_EXEP
	- Consider only Tiers A and B stars (99 total), which have minimal zo interference
	- $\bullet\;$  Pick at least one representative star from each of F, G, and K spe types with the minimal Earth-equivalent-insolation angular separa (EEIAS)
	- Added a "Solar-twin" star (Datson et al. 2014 MNRAS): 18 Scorp

#### **ExEP Target List for HWO**











### **Fiducial Stars**



In this report, the impact of a given gap is assessed by the associated performance parameters' impact on required integration time (to achieve required SNR) for these five fiducial stars



# 4A. Provisional Key Driving Requirements: Starlight-Suppression Key Performance Parameters (KPPs)



## **Visible**

- **Spectral coverage and resolution** [LUVOIR Final Report]
	- H2O: **0.94 μm**, **20% BW**, **SNR=8.5** photometry
	- O2: **0.76 μm**, **20% BW**, **SNR=10**, **R = 140** spectroscopy
- **Core throughput 0.3**
- **IWA 60 mas**
- **Raw Contrast 3 x 10-10**



- Exozodi brightness (at 3 zodis) is equivalent to 6 x  $10^{-10}$   $\sim$  1 x  $10^{-9}$ flux-ratio levels for our fiducial stars, buffering the impact of raw contrast
- o However, stellar speckles are coherent. They can amplify the effects of WFE instability via the cross term, whereas zodiacal light is incoherent. Our error-budget analyses indicate that **raw contrast has a significant effect (on required integration time) only when it is** ≳ **3 x 10-10**



### **Infrared**

#### **Spectral coverage and resolutions**

[Damiano & Hu 2022]

- $\circ$  H<sub>2</sub>O: 1.1 µm, 20% BW, SNR=20, R = 40 spectroscopy
- CO2: **1.6 μm**, **20% BW**, **SNR = 20**, **R = 40** spectroscopy
- **Core throughput 0.3**
- **IWA: 60 mas**
- **Raw contrast:** ~ **3 × 10-10**



0.4



○ IR features key spectroscopic diagnostics essential to contextualize Vis spectrum.  $\circ$  Max resolution in IR is very dependent on available detector technology ○ **60 mas IWA = 1.1 λ/D** for λ=1.6 μm & D=6 m. **Major NIR challenge**



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*yield vs. IWA vs* 

### **Ultraviolet**

- **Spectral coverage and resolutions** 
	- O3: **250 - 300 nm**, **20% BW**, **SNR = 20,** 
		- **R = 7** photometry
- **Core throughput 0.2**
- **IWA 60 mas**
- **Raw contrast**  $\sim$  **1**  $\times$  **10<sup>-10</sup>**



#### **UV coronagraph can tolerate larger IWA (in λ/D) but needs higher throughput than Vis coronagraph.**





# 4B. Provisional Key Driving Requirements: Wavefront-Stability Environment



## **Flux-Ratio Error Budget**

- The planet-star flux ratio, the target SNR, and the integration time required to reach the SNR drive the error budget
- Note that required integration time becomes infinity when the residual-noise-equivalent photon rate  $(r_{\Lambda}$ <sup> $\prime$ </sup>) is equal to the planet rate divided by the target SNR

 $t = \infty$  if  $r_{\Delta l} = r_{\rho l} / SNR$ 

• Hence, **there is a break point in** *r***<sub>Δ</sub>, over which planet detection is not possible**, regardless of integration time

#### **Integration-Time Equation** Glossary

$$
t = \frac{\text{SNR}^2 r_n}{r_{\text{pl}}^2 - \text{SNR}^2 r_{\Delta I}^2}
$$

- ppt: part per trillion
- $r_n$ : random-noise equiv. photon rate
- $r_{pl}$ : planet photon rate
- *r*<sub>Δ</sub>*i*: residual noise equiv. photon rate (after post-processing)



#### **Notional Example of an Error Budget for Earth-Twin Detection** Nemati et al. 2020 *JATIS* Planet flux ratio System Sun Earth at 10 pc  $\xi_{\rm nl}$ ExoZodi/solar  $212$  ppt  $3X$



#### **Requirements on the WFE Environment**

- The crucial parameter  $r_{\Lambda}$  (see previous slide) is a product of **WFE instability at the coronagraph's focal-plane mask (FPM)**, the **contrast sensitivity** to the WFE, and **postprocessing factor** (in mitigation of effective WFE)
- Our error-budget study for detection of the 5 fiducial stars indicate the following key-driving requirements
	- Assumptions
		- Contrast sensitivities w.r.t. "Low" (Z1 Z11) and "Mid" (4 - 16 cyc/D) spatialfrequency modes: 3 - 10 ppt/pm
		- Raw contrast:  $\sim 3 \times 10^{-10}$
	- **Allowable WFE** in Low & Mid spatialfrequency bins: **2 pm RMS (at the FPM, after observatory stabilization and coronagrah AO, assuming no post-processing gain)**



Fig. 26 Nemati et al. 2020 JATIS

> **A critical requirement for HWO coronagraphy!**



#### **Comments re. WFE Environment Requirements**

- The 2 pm RMS provisional requirement is in agreement with that in Nemati et al. 2020 (6 pm RMS) considering the following:
	- Nemati et al. assumes a post-processing gain = 2, whereas we do not assume any post-processing enhancement (i.e. gain=1)
	- Our F fiducial star drives contrast-stability requirements, whereas Nemati et al. analyzed a Sun-Earth-twin scenario.
- The following factors can *relax requirements on the observatory WFE stability*:
	- AO in the coronagraph instrument
	- Improvements in contrast sensitivities to WFEs (aka coronagraph robustness)
	- Post-processing advancements (the above-stated provisional requirement assumes no post-processing gain)



#### **Comments re. WFE Environment Requirements**

Required Integration Time (hr, SNR=5.0) vs. Contrast  $10<sup>3</sup>$ HIP 32439 A. F8V inner HZ outer H7  $10<sup>2</sup>$  $10<sup>1</sup>$ **Baseline WFSC Factor**  $10<sup>3</sup>$ 32439 A. F8V ntegration Time (hours) er HZ  $10<sup>2</sup>$  $10^{1}$ 2x Worse WFSC Factor  $10^{3}$ HIP 32439 A. F8V nner H7  $10<sup>2</sup>$  $10^{1}$ 5x Worse WFSC Factor  $10^{-10}$  $10^{-11}$  $10^{-8}$  $10^{-12}$  $10^{-9}$  $10^{-7}$ 

Contrast

- **Degradation w.r.t. static raw** contrast is gradual with a knee  $at \sim 3 \times 10^{-10}$
- Degrading WFS&C factor by 2x has only slight impact
	- **Degrading WFS&C factor by** 5x poses a clear breakpoint, where required integration time blows up (for the inner HZ). This corresponds to 2 pm at FPM. Note: *t* does not blow up for the outer HZ because of the smaller assumed HIGH spatial frequency WFEs from the telescope (see p. 37) compared to LOW & MID.
- See the same behavior for all (FGK) fiducial stars.



4C. Provisional Requirements: Coronagraph AO



## Provisional Requirements: AO

Adopted USORT's spatio-temporal binning approach based on Coyle et al. (2019, SPIE), with the addition of a static "temporal-frequency" bin

#### **Temporal Frequency Bins**





## Provisional Requirements: AO

Adopted USORT's spatio-temporal binning approach based on Coyle et al. (2019, SPIE), with the addition of a static "temporal-frequency" bin

#### **Spatial Frequency Bins**





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# Provisional Requirements: AO

Assumed open-loop RMS wavefront changes between target and reference star observations (based on values from USORT, B. Sitarski)

LF1 | 87.30 26.20 40.00 0.00 LF2 87.30 26.20 40.00 0.00 LF3 87.30 5.20 3.50 0.00 MF 17.50 5.20 3.50 0.00 HF 17.50 5.20 3.50 0.00

**Spatial frequency**

Required drift-mitigation factors (assuming AO subsystem using DMs to compensate WFE changes)

#### **Spatial frequency**



These values are representative results of an **EBS Monte Carlo run** that yield reasonable exposure times (~ 1 - 5 days for planet detection)

#### $LOW$   $MID$   $HICH$   $HIGH+$ STATIC 20000 15000.00 5000.00 5000.00

**WFE [pm]**

This document has been reviewed and determined not to contain export controlled technical data.



# Provisional Requirements: AO

## Final, post-AO wavefront "at the FPM"

**Spatial frequency**



Final Contrast floor (coronagraph sensitivities based on Nemati et al. 2020 *JATIS*)



These values are representative results of an **EBS Monte Carlo run** that yield reasonable exposure times.



# Provisional Requirements: DM

- See the DMTR Final Report for a comprehensive set of DM performance goals
- Actuator count: ≥ 96 actuators across the pupil diameter
- Rationale
	- Nyquist frequency (48  $\lambda/D$ ,  $\lambda = 0.6$  µm, D = 6 m) corresponds to 1" in the image plane, this supports imaging outer HZ of nearby stars and outer giant planets. It is also between LUVOIR and HabEx baseline values
		- LUVOIR: 128 actuators/D,  $D = 8$  or 15 m
		- HabEx: 64 actuators/D,  $D = 4$  m
		- 96 actuator
	- 96 actuators/D is approximately the limit of feasibility using incumbent manufacturing methodologies for PMNelectrostrictive and MEMS-electrostatic DMs

*Future HWO Trade: Science return, DM actuator format & stroke, wavefront control architecture, telescope architecture*



# Provisional Requirements: DM

### **Stroke**



\*Stroke values do not assume a DM apodization command or gravity offloading during ground testing

**Stability** 



\*Soft requirement, can be larger but requires large move at "power on"

DM settling time of  $\sim$ 1 month at "power on", ~0.5 days during science operations in follow up mode.

40 **pending woofer-tweeter architecture, coronagraph design, and telescope stability) Required stroke (after flattening), including budget for telescope WFE + drift, coronagraph apodization, EFC, & AO/LOWFS: > 500 nm PV (possible relaxation** 



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# 4D. Provisional Requirements: **Detectors**



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# **Provisional Requirements: Detectors**

- Spectroscopy drives detector noise requirement
- Exo-zodiacal light is frequently the dominant randomnoise source. Therefore, we require detector noise << exo-zodi noise
- For  $R = 140$  in the vis, 3 zodi exo-zodiacal brightness level, exo-zodiacal count rate is on the order of 0.01 count/s  $\Rightarrow$  exo-zodiacal shot noise  $\sim$  0.1 Hz<sup>-1/2</sup>
- We set a **requirement of < 0.01 Hz-1/2 detector noise**  (5x below exo-zodi)

\*Computation of exo-zodi wavelength dependence is currently under investigation



## **Provisional Requirements: Detectors (cont'd)**



**Assuming Roman-CGI EMCCD Noise Levels Noiseless Detector**

### **Detector noise requirement is a strong function of throughput. High throughput is required even with a noiseless detector**



# 4E. Provisional Requirements: Post-processing



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# **Provisional Requirements: Post Processing**

- We define post-processing as a numerical procedure that enhances the effective contrast stability (i.e. effectively reduces  $\sigma_{AC}$  in Nemati et al. 2020 JATIS). This is a generalization of the Roman Coronagraph and Nemati et al. (2020) definition.
- Roman CGI simulations using a PCA post-processing algorithm estimated gain  $\sim$  2 for CGI. Per Roman Coronagraph's definition, the 2x gain is the factor obtainable beyond single-roll classical RDI.
- We do not set a specific provisional requirement for postprocessing gain
- The above-stated provisional AO, contrast sensitivity, and WFE stability requirements were derived assuming no postprocessing gain (i.e. gain  $= 1$ )
- **Advancing post-processing methodologies to relax the formidable requirements on WFE stability is very important** This document has been reviewed and determined not to contain export controlled technical data.  $45$



# 5. State of the Art (SotA) and Technology Gaps



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## **Deformable Mirrors**

- ExEP completed a DM Technology Survey in 2021 and identified 3 top manufacturers, each using a fundamentally different technology: Northrop Grumman's AOA Xinetics (AOX), Boston Micromachines Corp. (BMC), ALPAO
- **See the DMTR Final Report for the DM technology maturation roadmap**
- We briefly summarize distinguishing characteristics of each technology



# **Deformable Mirrors: Electrostrictive Actuation**

- <u>Main vendor</u>: AOX
- Actuation mechanism: electrostriction using PMN (lead magnesium niobate) actuators



- Pros
- Delivered flight DMs for Roman Coronagraph Instrument (CGI)
- The only DMs that currently enable raw contrast substantially better than 10-9 contrast
- Cons
- PMN has intrinsic settling time of  $\sim$  1 week to reach 1 pm/hr stability
- Connectorization methods thus far involve imposing stress on the PMN, which in turn can significantly change the mirror shape.
- Ultimate array-size limit with established manufacturing processes: 96x96



# **Deformable Mirrors: Electrostatic Actuation**

- Main vendor: Boston Micromachines Corp. (BMC)
- Actuation mechanism: electrostatic force using MEMS actuators



- Pros
	- No observable drift observed thus far at  $\sim 10^{-9}$  raw contrast level
	- Wire-bonded connectorization avoid stress on the mirror surface
- Cons
	- Surface print-through pattern, with repeating fine structure at every actuator, produce harmonic satellite speckles leaking into the coronagraphic dark zone. Currently limiting contrast to  $\sim$  1x10<sup>-9</sup> in the High Contrast Imaging Testbed
- Ultimate array-size limit with established manufacturing  $processes: ~ 96x96$



## **Deformable Mirrors: Electromagnetic Actuation**

- Main vendor: ALPAO (France)
- Actuation mechanism: electromagnetic force using voice-coil-like structure
- Pros
	- High achievable actuator count
- Cons
	- Large actuator pitch
	- Heat dissipation at each actuator, which can cause mirror deformations
	- Picometer stability/resolution not demonstrated





## **DM State-of-the-Art Performance Summary**



#### Credit: DMTR Final Report



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# **Deformable Mirrors: General Conclusions**

- **See the Deformable Mirror Technology Roadmap (DMTR) for a comprehensive report**
- Overall Status:
	- No technology meets all requirements
	- Two technologies are clearly the most mature: PMN/electrostrictive and MEMS/electrostatic
	- Array Size Limit: Using current fabrication technologies for either approach, exceeding  $\sim$  96 x 96 array size will be difficult
- **Major Technology Gaps:** 
	- Both technologies: **production yield** of DMs with all actuators meeting requirements
	- Current **test facilities** are not adequate to verify milestone demonstrations (e.g. pm stability at short timescales) of DMs, esp. as we develop them to full 96x96 format
	- Compact drive electronics with path to flight



## **Deformable Mirrors: General Conclusions (cont'd)**

- **Major Technology Gaps**:
	- PMN Technology,
		- **DM connectorization** is a technology gap deserving major attention; attaching  $\sim$  10<sup>4</sup> pins to the back of a mirror while maintaining picometer surface stability is really hard!
		- PMN has intrinsic **drift** that settles over time. The can become a high impact gap if this prevents achieving adequate contrast in time frames compatible with HWO's observing scenario.



A 48x48 PMN DM, with (nonflight) pins on the back side connecting to flex-print cables

- MEMS Technology
	- **Print-through surface error diffract light** into the image dark zone, currently limiting contrast to 10<sup>-9</sup> level.

**Membrane Surface Actuator Post Actuator Surface Actuator Support** Electrodes **Silicon Substrate** 



CLC: classic Lyot coronagraph HLC: hybrid Lyot coronagraph VVC4: vector vortex charge 4 coronagraph PAPLC: phaseapodized pupil Lyot coronagraph PIAA-CMC: phase-induced amplitude apodization complex mask coronagraph NI: normalized intensity (similar to raw contrast, ref. Nemati et al. 2020)



Credit: Mennesson et al. 2024, submitted to JATIS [https://arxiv.org/abs/2404.18036]

- JPL's High Contrast Imaging Testbed (HCIT) facility's Decadal Survey Testbed (DST) currently has a baseline contrast of  $4x10^{-10}$  mean contrast, 3 - 8  $\lambda$ /D full annular dark zone, 10% bandwidth
- Analysis by Seo et al. (2019) identified the following terms of residual light



Recent demonstration of 20-bit electronics and ghost-reflection analysis provide a path to 2x10-10



- **General Status** 
	- See Mennesson et al., "Current laboratory performance of starlight suppression systems, and potential pathways to desired Habitable Worlds Observatory exoplanet science capabilities," 2024 (submitted to *JATIS*) for a comprehensive review
	- No single type of coronagraph has simultaneously achieved all (contrast, throughput, FoV, IWA, spectral bandwidth, spectral coverage) requirements
	- CLC & HLC lead in contrast, PIAA-CMC in throughput, PAPLC in IWA, while VVC offers a good balance of characteristics
	- Plugging demonstrated combinations of characteristics (raw contrast, core throughput, bandwidth, etc.) into an exposure time calculation for an Earth twin at 12 pc predicts:
		- Detection requires  $> 10$  hr integration time for SNR = 7, Earth-twin  $@$  12 pc
		- **Spectroscopy requires > 1 month integration time at R=70, λ = 0.75 μm, SNR = 10 (noiseless detector)**



## **Major Performance Gap**

- Simultaneous achievement of 3 x 10-10 raw contrast and 0.3 core throughput with 20% bandwidth, while maintaining SoTA contrast sensitivity.
	- In general, SotA coronagraphs demonstrate only one of these three KPP at a time





- **Major Ground Test Facility Gaps**
	- Existing coronagraphic testbeds have not demonstrated the capability to make the following key types of measurements
		- Raw broadband contrast  $< 4 \times 10^{-10}$
		- Contrast sensitivity to WFEs
		- $\blacksquare$  Measurements outside the 0.55 0.8 µm range (i.e. lacking near-UV and near-IR testbeds)
		- Measurements with sources simulating natural stars (thermal source with finite angular diameter). Broadband measurements thus far utilize supercontinuum, spatially unresolved sources



## **Starlight Suppression Optics: Simulated Performance**



- Full-annulus dark zones
- The table includes only coronagraphs recently analyzed by ExEP Segmented Coronagraph Design & Analysis (SCDA) study program
- The designs used DMs with 64 actuators across the diameter
- Manufacturability of the designs will be assessed (as part of the Coronagraph Technology Roadmap work)
- All 3 coronagraphs are extremely sensitive to shear between telescope's exit pupil and the coronagraph's entrance pupil, not shown in this table. The tolerance is  $\sim 10^{-5}$  x pupil diameter
- **See the ExEP CDS Final Report for a comprehensive survey**



## **Starlight Suppression Optics: Simulated Performance**

- General Status
	- The table above is indicative of SotA modeled performance for full annular dark zones vis-a-vis segmented pupils. LUVOIR-A is on axis and LUVOIR-B is off-axis with 6.7 m inscribed diameter, a close analog to Astro2020's HWO description.
	- Coronagraphs with best contrast performance (e.g. HLC, APLC) tend to have relatively poor core throughput

### • **Major Technology Gaps**

- Simultaneous achievement of core throughput ( $\geq 0.3$ ), raw Contrast ( $\leq 1E-10$ ), and low contrast sensitivity to WFEs
- IWA ( $\leq 60$  mas) at wavelengths longer than  $\sim 0.6$  µm
- NIR coronagraph designs
- UV coronagraph designs



## Starlight Suppression Modeling, Roman Coronagraph

### • **Status**

*Roman CGI HOWFSC model successfully validated multiple times*: on testbed during CGI Tech Dev phase; before CGI PDR (for HLC/narrow-FOV); and again with Roman CGI during CGI thermal-vacuum test (TVAC):

- **Consistent good agreements** on **raw coherent contrast floor**, *convergence speed, and key sensitivities* (pred err <35% mostly )
- Validated model **a critical tool** throughout CGI project phases from flight design, fabrication, component issue risk assessment, CGI TVAC HOWFSC execution guidance and PFRs resolutions, etc.

## • **Gaps**

- Incoherent contrast of the as-built systems still significantly higher than in model
- Validity itself not automatically extends to new coronagraph types (of HWO), while some lessons applicable

Zhou et al. Proc. SPIE, 10407(2017); Proc. SPIE, 11443(2020); Zhou et al. JATIS (2025, in preparation)

## **Starlight Suppression Modeling, Roman Coronagraph**

## **HOWFSC Model Validation – Pre-PhaseA, Tech.**

#### **Excellent agreement** between model predictions and testbed results (% errors) **Dev.**

- ❖ *Contrast floor* (coherent)*:* mean ~30%; chromaticity ~34% avg
- ❖ *Contrast convergence speed*: comparable (envelope)
- 
- ❖ *Contrast sensitivity* (open Loop): Occulter mask lateral shear: <20%, at 1e-10 ΔC

Low order Zernike Z2~11 WFE: max < 25%; avg ~ 9%, @ 1nm rms

Shaped pupil mask lateral shear: ~33%, at 1e-8 ΔC



#### **SPC/Spect mode**

Zhou, H., et al., Proc. SPIE, 10400 (2017)

This document has been reviewed and determined not to contain export controlled technical data.

## **Starlight Suppression Modeling, Roman Coronagraph**

## **HOWFSC Model Validation – PhaseB**

**Excellent agreements** on both raw **coherent** *contrast floor & its convergence speed:*  prediction error (ground and  $\text{IOC}$ ):  $\sim$  < 35% of TB

10-4 Testbed (modulated) vs model, in-orbit commisioning WFC

#### *Step 1***. Ground DM Solution WFSC** *Step 2***. (IOC) WFSC**



**c)** 

#### $10^{-5}$  $10^{-6}$ Contrast  $10^{-7}$  $10^{-8}$ **d)**   $10^{-9}$  $\Omega$ 20 25 5 10 15 3U Iter Contrast (3-9 lam/D) = 1.74e-09 **Run483it00534, C (mod) =1.5e-09 b)**  $f(x) = 0$   $f(x) = 0$   $f(x) = 0$   $f(x) = 0$ **e)**

#### Testbed (coherent) Model Testbed (coherent) Model

**Testbed (modulated** 

Model

#### **HLC/nFOV mode**

### Good agreement on key contrast sensitivities:



Zhou, H., et al., Proc. SPIE, 11443 (2020)

un482it03227, C (mod) = 8.1e-10

Contrast  $(3-9 \text{ lam/D}) = 1.09e-0$ 

This document has been reviewed and determined not to contain export controlled technical data.

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## **Starlight Suppression Optics: Roman Space Telescope Coronagraph (RST-CGI)**

- CGI will be the first coronagraph in space with active wavefront control (dark-hole digging using DMs)
- Pupil obscurations by secondary-mirror-support structure presented a new challenge in coronagraph design, culminating in a new era of coronagraphy for obscured/segmented pupils
- Utilizes a baseline combination of 3 coronagraphs: hybrid-Lyot with narrow FoV (HLC-nFOV), shaped pupil for spectroscopy (SPC-spec), and shaped pupil with wide FoV (SPC-wFOV)
- Threshold requirements:
	- Capability to measure, with  $SNR \geq 5$ , an astrophysical point source located between 6 - 9  $\lambda$ /D from a star of M<sub>y</sub>  $\leq$  5, with a flux ratio  $\geq 10^{-7}$
	- Bandwidth:  $10\%$  @  $\lambda$  < 0.6 μm
- Surpassed performance requirements in recent thermal-vacuum testing.
- Delivery to RST in May 2024.
- Launch Date: May 2027



## **Starlight Suppression Optics: Roman Space Telescope Coronagraph (RST-CGI), cont'd**

- Current best estimate of in-orbit performance using high fidelity models 0.05
	- Contrast: 6 x 10-9
	- Core throughput: 4%





#### Zhou et al. 2023 Proc. SPIE



Fig. 11 HLC band 1 field PSF core throughput fraction versus field position.



Fig. 6 HLC (band 1) contrast changes relative to low-order aberration measured over a  $r = 3$  to 5  $\lambda_c/D$  annulus. The default image was obtained after running WFC on the aberrated system model and includes polarization but no jitter and has a dark hole mean NI of  $9 \times 10^{-10}$  over 3 to 5  $\lambda_c/D$ . Vertical dashed lines indicate the approximate aberration sensitivity transitions from linear (leftward) to quadratic (rightward). The spherical and coma transitions occur < 10 pm RMS.

Krist et al. 2023 JATIS



## **Starlight Suppression Optics: Roman Space Telescope Coronagraph (RST-CGI), cont'd**

- Extremely informative, recent papers on CGI
	- Krist et al. (2023), "End-to-end numerical modeling of the Roman Space Telescope coronagraph," *JATIS*, doi: 10.1117/1.JATIS.9.4.045002
	- Nemati et al. (2023), "Analytical performance model and error budget for the Roman coronagraph instrument," *JATIS*, doi: 10.1117/1.JATIS.9.3.034007
	- Zhou et al. (2023), "Roman Coronagraph HOWFSC Modeling: Case Study and Raw Contrast Performance Prediction," *Proc. SPIE*, doi: 10.1117/12.2681773



The Coronagraph Technology Roadmap

## **Starlight Suppression Optics: Near Infrared**

- State of the Art: Near-IR coronagraphs observe exoplanets from the ground and in space, but not at HWO performance levels
	- JWST NIRCam operates routinely at 1x10-4 raw contrast, 1x10-5 post processed, and 4x10-7 on a bright star [e.g. Ygouf et al. 2024 *ApJ*]. NIRCam does not have DMs.
	- Ground based coronagraphs operates routinely at 1x10-5 raw contrast, 1x10-6 post processed, 5x10-7 on a bright star. Ground based coronagraphs use DMs for atmospheric correction



## **Starlight Suppression Optics: Near Infrared (cont'd)**

- State of the Art: Lab Demos & Emergent Tecnologies
	- Currently, there is a paucity of coronagraph designs or laboratory demonstrations that **provide adequate IWA to reach habitable zones above 1 μm**
	- Photonic nulling technologies
		- Photonic Lantern Nuller (PLN) nullers and spectrometers can work at small IWA
			- Mode-selective photonic lantern separates incident light into individual fiber-propagation modes, thereby distinguishing off-axis planetary light from on-axis starlight
			- Fundamental limit at  $\lambda/(2D)$
			- Modal cross-talk and testbed WFEs currently limit achievable contrast to  $\sim 10^{-2}$  [refs. in fig. caption below]
			- Significant theoretical and experimental work is necessary to understand fundamental limits

Fig. 39 from Jovanovic et al. (2023) showing how a PLN maps LP modes of input light into singlemode fibers, resulting in selective ports that suppress on-axis light. Also see Xin et al. (2024) *JATIS*.





## **Starlight Suppression Optics: Near Infrared (cont'd)**

- State of the Art: Lab Demos & Emergent Tecnologies
	- Photonic nulling technologies
		- Photonic Nulling Chips (PNCs)
			- Valdez et al. @ Stanford U.: Four Mach Zenhder interferometers (4- MZI) integrated on chip demonstrated 1 x 10<sup>-7</sup> suppression with 4-MZI PIC (wavelength  $1550 \pm 10$  nm); same architecture reported recently in Jewell et al. 2024 SPIE and Sirbu et al. 2024 SPIE. This is an on-chip nulling demonstration and does not directly map into an IWA/OWA/core throughput paradigm.
			- $\bullet$  8 x 10<sup>-9</sup> suppression with 6-MZI PIC; also at 1550 nm reported in overview SPIE presentation Sirbu et al 2024 (Valdez et al forthcoming with additional technical details).
			- Free-space coupling demonstration showing coronagraphic nulling on-axis and coronagraphic throughput on-axis; this was a functional demonstration with a small fill-factor on the chip, also at 1550 nm and reported in Sirbu et al. 2024 (Fogarty et al also forthcoming with additional technical details on model vs testbed comparisons)
			- Main performance limitation: manufacturing imperfections and environmental factors causing errors in light-splitting ratios (i.e. imbalances in interferometric nulling)



## **Starlight Suppression Optics: Near Infrared (cont'd)**

- State of the Art
	- Vortex Fiber Nulling (VFN)
		- An optical vortex in the pupil paired with a single-mode fiber in the focal plane rejects on-axis starlight but transmits light in an annular zone.
		- Insensitive to planet position within the annular (orbital) region
		- Broadband lab-demo [Echeverri et al. 2023, Proc. SPIE]
			- Null depth:  $9 \times 10^{-5}$
			- Planet coupling efficiency: 7.7%
			- Contrast (null depth/planet coupling efficiency):  $1 \times 10^{-3}$
			- Bandwidth:  $15\%$  @ 0.65 µm
			- IWA: 0.8 λ/D
			- OWA: 1.9 λ/D
		- On-Sky Performance at Keck II Telescope [Echererri et al. 2023, JATIS, 2024 ApJ Lett]
			- Detection of companion at 2 x 10<sup>-3</sup> flux ratio with SNR = 3, leveraging high spectral resolution to extract planetary signal from background
		- Currently limited by sensitivity to WFE instability and mask chromaticity



## **Starlight Suppression Optics: Near-Infrared, cont'd**

- **Major Technology Challenges & Gaps**
	- **Achieving IWA (60 mas) is the primary challenge in the near-IR.** 60 mas is merely 1.1  $\lambda/D$  for  $\lambda = 1.6$  µm, D = 6 m
		- Achievable IWA is limited by stellar angular size, WFE instability (especially pointing jitter), and design of starlight-suppression optics (coronagraph masks)
	- Nulling technologies can meet the IWA challenge but face substantial gaps
		- Contrast needs many  $(2, 7)$  orders of magnitude improvement
		- Device and mask imperfections limit performance
		- Sensitivity to WFE instabilities (especially pointing jitter) place limits on performance, as nulling techniques rely on spatial-mode selection to achieve contrast.
		- The is a knowledge gap regarding fundamental limits of photonic nulling technologies
		- VFN FoV is limited to  $\sim$  1 λ/D annular band per vortex mask



## **Starlight Suppression Optics: Near-Ultraviolet**

- **See the CTR UV Report "A near-ultraviolet coronagraph instrument study for the Habitable Worlds Observatory" led by R. Juanola Parramon**
- **Major Technology Challenges & Gaps**
	- Low detectable photon flux
		- Low throughput due to lower coating reflectance than vis
		- Lower detector QE compared to vis
		- Stars are dimmer, and therefore lower planetary flux as well, compared to vis
		- CTR estimated the UV system throughput/QE (see Appendix slides) and conducted a UV target analysis. We found that this might eliminate **26% of viable (vis) targets** in the ExEP HWO Target List. The loss was mainly in K stars.



Number of Accessible Targets in the Galex NUV Band for O3 Detection. Preliminary estimates by K. Stapelfeldt, E. Mamajek, D. Savransky. (June 7, 2023)


### **Starlight Suppression Optics: Near-Ultraviolet (cont'd)**

### • **Major Technology Challenges & Gaps**

- Tighter wavefront sensing and control requirements
	- The same WFE physical amplitude is double in phase amplitude at 250 nm vs. 500 nm, requiring tighter sensing and control
- More intense scattered light by optical surfaces and particles
	- Knowledge gap: large uncertainties exist in scattering into small angles, especially by particulate contaminants
- Higher sensitivity to contamination
	- Absorption and scattering by contaminants are much stronger in the UV
	- Need to evaluate whether this is an (contamination control) engineering or technology problem



### **Starlight Suppression Optics: Near-Ultraviolet (cont'd)**

#### • **Major Technology Challenges & Gaps**

- Larger polarization aberrations
	- Contrast degradation due to polarization aberrations is especially pronounced at short wavelengths.
	- The effect projects mainly into tip-tilt and astigmatism. Thus, degradation occurs at small working angles.
	- Fortunately, most UV targets are at large working angles in terms of λ/D.
		- 100 mas  $\Rightarrow$  12 λ/D @ λ = 250 nm, D = 6 m
	- Coronagraphs can be designed to mitigate effects of polarization aberration, by enhancing low-order-WFE tolerance







# **Coronagraph AO: Simulations**

*Future HWO Trade: Artificial vs. natural reference source for AO*

- Potier et al. (2022), numerical study on coronagraph AO main general conclusions
	- Sensor SNR fundamentally limits control performance. Therefore, photon rate fundamentally limits control gain and bandwidth using an optical wavefront sensor
		- **In the photon-noise-limited regime**, WFS&C provides useful contrast stabilization **only when the fiducial light source is sufficiently bright and the wavefront perturbations are sufficiently large**
	- Predictive control can significantly increase control performance, effectively extending useful source brightness, but has fundamental limitations
		- Per **Bode's theorem (aka the "waterbed effect")**, if sensitivity to disturbance is suppressed at some frequency range, it is necessarily increased at some other range.
	- Results highly dependent on spatial modal content, e.g. segment to segment correlations.
	- Therefore **from a coronagraph AO PoV, it is better to have wavefront variance concentrated in a smaller number of vibrational modes. Telescope structures w/ fewer DoF, higher symmetry, and higher stiffness are desirable.**



The Coronagraph Technology Roadmap

### **Coronagraph AO: Simulations**

- Pueyo et al. (2022) and Sahoo et al. (2022) used semi-analytical models to quantify fundamental limits associated with stellar brightness in the worse case scenario of random/uncorrelated movements of segments w.r.t. to neighbors. Theoretical gains of factors of 10 - 100. The more robust the coronaraph the greater the gain.
	- Results consistent with Potier et al. For drift timescales longer than ~1 mins (thermal) enough photons for AO correction at 3x10-11
- Dube et al. (2022) JOSA "Exascale integrated modeling of low-order wavefront sensing and control for the roman Coronagraph Instrument": Demonstrated techniques for  $\lambda$ /10000-precision modeling of wavefront sensing and control with large improvements in computational speed.





# **Coronagraph AO: Laboratory Demonstration**

- **Picometer (or better) sensing and actuation have been demonstrated in the lab**
	- Ruane et al. (2020, *JATIS*) demonstrated 0.75 pm sensitivity with 1.2 h integration using a Zernike wavefront sensor
	- Noyes et al. (2023, *Proc. SPIE*) demonstrated 1-pm DM wavefront control Zernike WFS Measured



Left panel: DM surface height extracted from 10,000 wavefront-sensor images Right panet: Histogram of DM actuation displacements showing 0.65 pm resolution [Noyes et al. 2023]





**0.75 pm WFE Sensing Demo**: Blue solid trace shows empirical measurement error vs. number of exposure frames integrated (10 ms/frame). [Ruane et al. 2020]







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### **Coronagraph AO: Laboratory Demonstration (cont'd)**

#### • **CGI Demonstrations**

- Shi et al. (2019, *SPIE*)
	- Demonstrated sub-mas sensing and control of vibration induced line of sight using Roman CGI LOWFS architecture
	- Demonstrated contrast maintenance below 1e-8 (controlling Z1-Z3) using Roman CGI LOWFS architecture
- Dube et al. (AAS 2020) demonstrated contrast maintenance below 1e-8 (controlling Z1-Z7) using Roman CGI LOWFS architecture and low photon flux.



Figure 5. LoS performance with multiple RWA disturbances injected by the JM. The figure shows the time traces of LOWFS sensed LoS tip-tilt errors labeled as Z2 (blue) and Z3 (red). The LOWFS sensor measurements (nm RMS) have been converted to the on-sky LoS angle in unit of milli-arcsecond (mas). The main panel on top shows the time traces of the measured LoS with FSM loops open (left segment), closed loop with feedback (FB) control only (middle segment), and closed loop with both feedback (FB) and feed forward (FF) controls (right segment). The RMS LoS error of Z2 and Z3 of each segments are listed on top of corresponding segments. At the bottom, three panels show the zoom-in view of the time traces under different control conditions. Please noted the open loop plot (lower left panel) has a much larger Y-axis scale.

Shi et al. (2019)



# **Coronagraph AO: Laboratory Demonstration (cont'd)**

- Pourcelot et al. (2022, A&A) and Soummer et al. (2022, SPIE) demonstrated contrast maintenance at  $~5x10^{-8}$  (controlling Z1-Z11) using APLC+LOWFS architecture
- Redmond et al. (2022, SPIE) demonstrated contrast maintenance at  $~5x10^{-8}$  using science camera images in the Dark Hole.
- Poon et al. (2023, SPIE), demonstrated contrast maintenance at  $\sim$ 5x10<sup>-8</sup> using science camera images outside of the Dark Hole (LDFC)

**Multiple sensing and control architectures being demonstrated in testbed. CGI will provide TRL 9 demonstration of LOWFS in space**







# **Coronagraph AO: Ground Test Facility**

### ● **SotA**

- Stability of existing vacuum testbeds  $\sim$ 1e-10 per hour drift (Seo et al. 2019). Hypothesized root cause, DM drift.
- Experimental environment need to be sufficiently quiet:
	- to inject disturbances commensurate with HWO thermal and dynamical environment at sufficient SNR.
	- measure noise rejections levels that validate models of closed loop operations.





### **Coronagraph AO: Laboratory Demonstration (cont'd)**

### **Major Performance Gaps**

- $\circ$  Operations around a 3 x 10<sup>-10</sup> raw contrast, or around a wavefront commensurate with  $3 \times 10^{-10}$  raw contrast (if no coronagraph in AOTF)
- Contrast stability at the 3 x 10<sup>-11</sup> level, or wavefront stabilization at levels commensurate with 3 x 10<sup>-11</sup> contrast stability (if no coronagraph in testbed).
- Contrast stabilization in the presence of the disturbances commensurate with HWO thermal and dynamical environment (note that both control gain and capture range are important).
- **Major Simulations Gaps** 
	- o Predicted/simulated wavefront noise rejection levels need to be validated with experimental data.



# **Detectors: State of the Art**

- Survey of the state of the art was not carried out in the context of CTR (TAG to conduct it).
- Detector technologies for science instrument can be developed in parallel of starlight suppression technologies. Data obtained using a bright source can be made noisier after the fact to validate algorithms in the low photon count regime (Redmond et al., 2022).
- Detector technologies for wavefront sensing need to be integrated into starlight suppression technologies. WFS biases can be a limiting factor for raw contrast.
- SotA detector noise is a major factor in error budget for spectroscopy
- CTR's detector fact-finding spreadsheet is included in the appendix



# **Spectroscopy: State of the Art**

- R~20-70 routinely used for self-luminous exoplanet detection using ground based instruments at  $\sim$ 1x10<sup>-5</sup> contrasts.
- R~2000 will be routinely used for self-luminous exoplanet characterization with JWST at  $\sim$ 1x10<sup>-5</sup> contrasts. (Ruffio et al., 2023).
- R~30000 routinely for self-luminous exoplanet characterization using ground based instruments at  $\sim$ 1x10<sup>-5</sup> contrasts. (Xuan et al., 2022).



Ruffio 2023, arxiv, submitted to ApJ

This document has been reviewed and determined not to contain export controlled technical data. 83



# **Spectroscopy: Gaps**

### ● **Major Knowledge gaps:**

- $\circ$  How does contrast gain scale with spectral resolution in the reflected light regime?
- $\circ$  How does chromaticity of speckle (at  $\sim$ 3x10<sup>-10</sup> level) impact the measurement of the planet's continuum.

### ● **Major experimental gap:**

○ Lack of vacuum tests coupling coronagraphs and spectrograph at ~3x10<sup>-10</sup> levels





# 6. Gap Details



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# **Gap: WFE-Stability Environment**

#### **Description**

A coronagraph instrument built on SotA technology is not able to achieve required contrast noise floor for planet detection in relevant environment of observatory WFE instabilities

- Key issues
	- WFE stability has a critical impact on planet detectability. Beyond a threshold WFE instability, the coronagraph cannot detect the target planet regardless of integration time and raw contrast level.
	- AO in the coronagraph system can relax observatory requirements, but SotA control bandwidth and gain are limited by the fiducial lightsource's photon flux, contrast sensitivity, coronagraph AO, post processing.
	- Improving coronagraph robustness, post-processing, and other methodologies can mitigate the gap as well, but need substantial innovation and development



# **Gap: WFE-Stability Environment (cont'd)**

Impact: High

Impacts on Level-1 mission requirements

Gap Size: Large

- Current coronagraph sensitivities require  $\sim$  2 pm RMS WFE stability *at the focal-plane mask* (FPM) in low and mid spatial frequencies. This requires substantial developments in technologies including observatory stabilization, coronagraph design, post processing, PSF subtraction, and/or dark-hole maintenance technologies.
- Potential mitigating technologies require investments and/or increase system complexity (and thereby, mission schedule risk)



# **Gap: WFE-Stability Environment (cont'd)**

### Recommendations:

Study feasibility and realizable enhancements from the following technologies and invest where appropriate

- High bandwidth measurement of WFEs (at the coronagraph entrance pupil) from observatory mechatronic sensors (e.g. capacitive edge sensors) to circumvent the photon-flux limit
- Post processing & PSF subtraction
- Dark-hole maintenance methodologies
- Conducting these studies ASAP is imperative because the findings can impact mission-level design and observing scenario.
- Invest in developing coronagraph designs with high WFE tolerance
- Conduct early trade of artificial vs. natural wavefront-fiducial source, with evaluations of performance risk and system complexity



# **Gap: Starlight-Suppression-Optics Subsystem**

**Description** 

SotA Starlight-suppression optics do not meet static performance (throughput, IWA/FoV, raw contrast, wavelength, and bandwidth) requirements to enable required mission exoplanet yield

- Key issues
	- Substantial gaps exist between demonstrated and predicted contrast performances, indicating gap between asmanufactured optical characteristics and idealized model representations.
		- Need error-budget, modeling, and V&V of starlightsuppression test beds to *understand* noise contributors at ~ 10-11 level
	- NIR requires very small IWA in terms of λ/D
	- UV involves high sensitivity to scattering, contamination, and polarization aberrations



# **Gap: Starlight-Suppression-Optics Subsystem (cont'd)**

Impact: High

Impacts on Level-1 mission requirements

Gap Size: Medium for Vis (due to CGI heritage), Large for UV and IR

- Meeting starlight suppression + all other performance requirements in the UV, and IR is a major leap compared to SotA.
- DST has mitigated the Vis contrast gap, but all other performance requirements need to be demonstrated.
- Existing demonstrations fall between 0.55 and 0.8 μm. IR demonstrations with DMs do not exist. No demonstration in the UV.
- A possible pathway is to utilize separate UV and vis/IR instruments and different types of coronagraphs to get the job done. However, the increase in mission complexity add mission schedule and cost risk.
- Emergent, possibly disruptive technology concepts exist, but are at low maturity with substantial knowledge gaps



# **Gap: Starlight-Suppression-Optics Subsystem (cont'd)**

### Recommendations:

- Invest in error-budget, modeling, and V&V activities of starlightsuppression test beds to fully identify and quantify noise contributors at  $\sim$  3 x 10<sup>-11</sup> level
- Develop ground-test-facility roadmaps for NUR, NIR, and emergent technologies
- Define HWO NIR coronagraphy requirements ASAP
- Devise on- and off-ramps for NIR emergent technologies
- Leveraging findings in the CDS Final Report, develop and implement a NIR coronagraph technology roadmap.



# **Gap: Deformable Mirrors**

#### **Description**

SotA DMs with larger than 64x64 actuator format (e.g. 96x96 actuators) have not demonstrated required stability, the ability to enable required contrast, form factor to support required mass/volume, and/or manufacturing schedule requirements

- Key issues
	- DM interconnects: Need > 7K connections/DM with insignificant stress on the mirror surface
	- Need simultaneous achievement of adequate surface quality and stability
	- Manufacturing schedule is long  $($   $\sim$  3 years per production cycle)
	- SotA flight DM electronics can drive HWO system mass/volume budget
	- DM actuator pitch can drive instrument volume and, in in turn, observatory configuration
	- Supply chain risk (small number of vendors, each with substantial challenges)

Impact: High

• Impacts Level-1 mission requirements



# **Gap: Deformable Mirrors (cont'd)**

Gap Size: Large

• Technology-development paths exist to address major issues, but need to be proven. Existence of multiple issues increases overall likelihood.

### **Recommendations**

- Implement DM technology development according to the ExEP DMTR findings, some key issues to address are highlighted in the previous slide
- Initiating investments ASAP is imperative due to long development and production cycles.
- Conduct a thorough study of wavefront-control architectures (e.g. woofer tweeter, super-Nyquist wavefront-control, sparse DMs) vs. DM maturity, risk, and cost



# **Gap: Mission efficiency**

#### **Description**

Current HWO design concepts utilize dichroic beam-splitters to split light from the telescope into multiple beams to achieve simultaneous multichannel observations, which might be necessary to achieve mission science yield. The requirements to ensure quality of these optics for coronagraphy to the 10-10 level have not been defined. Throughput, bandwidth, IWA, etc. impact mission efficiency as well; they are included in the starlight-suppression optics area.

#### Impact: Medium

• This gap, if not closed, can impact overall mission science return: time devoted to exoplanet science case might be larger than envisioned by LUVOIR/HabEx.

### **Gap Size: Large**

• There is a high likelihood that requisite spatial uniformity will not be demonstrated in testbed at 3x10-10 contrast. If true, mission efficiency will be factors of many away from what HWO needs.



# **Gap: Mission efficiency (cont'd)**

#### Recommendations

Conduct early study to assess feasibility of using dichroic beam-splitters

- Thin-film and coronagraph modeling to establish a preliminary set of requirements using assumed manufacturing tolerances and patterns of spatial variations
- Design and procure a custom set of dichroic beamsplitters
- Design and build a broadband Mueller-matrix polarimeter
- Characterize the dichroic beamsplitters. Update/validate the modeled manufacturing tolerances and spatial patterns. Produce updated requirements for HWO.
- Conducting the study ASAP is imperative because this gap, if not closed, can impact observatory-level design and overall mission science return



# **Gap: Detectors**

**Description** 

SotA detectors do not meet noise, dynamic range, and lifetime requirements.

- Key issues
	- SotA, EMCCD, detectors produce excessive noise for HWO spectroscopy, and their in-orbit lifetimes need to be improved (e.g. Nemati's error-budget analysis for  $O<sub>2</sub>$  spectroscopy with HWO-like observatory using SotA EMCCD indicate excessive required integration time to achieve SNR). There is a need for low noise detectors for all (NUV, vis, and NIR) bands, especially for NIR spectroscopy
	- SotA NIR photon-counting detectors' operating temperatures challenge observatory thermal design
	- If HWO decides to utilize energy-resolving detectors, which require sub-Kelvin operating temperatures, the starlight-suppression subsystem must be isolated from mechanical disturbances generated by the cryogenic subsystem

Impact: High

• Impacts Level-1 mission requirements

Gap Size: Medium for imaging, Large for spectroscopy (NIR)



The Coronagraph Technology Roadmap

# **Gap: Detectors (cont'd)**

#### Recommendations:

- Conduct early detector trades
- Formulate and implement the technology roadmap that the HWO TAG Detector Technology Subgroup will produce



### **Gap: Algorithms**

**Description** 

SotA dark-hole-digging algorithms are likely not able to compute solutions quickly enough vis-a-vis DM drift and/or mission observing scenario. Post-Processing algorithms might not yield the necessary contrast gain.

- **Key Issues** 
	- SotA algorithm (EFC) can require many hours to achieve required contrast for each science exposure, depending on factors such as image acquisition, computation, and model fidelity.
	- Complexity of EFC (or equivalent algorithms) might require ground-in-theloop computing architecture, thus placing stringent stability requirements just for dark hole digging.
	- Temporal or chromatic properties of the dark-hole speckle field might not be comparable to post-processing factors obtained with other (e.g ground based) instruments.

Impact: Medium

• Dark-hole-digging timescales mostly impact mission efficiency. Post processing not as essential if AO is used.

Gap Size: Medium

• Existing methods sufficient for CGI, significant improvements is needed for HWO but not an enormous leap.



### **Gap: Algorithms**

#### Recommendations:

- Mature and dedicate early testbed time to more efficient (faster convergence, less CPU hungry) dark-hole-digging, dark-holemaintenance, PSF/background removal, and multi-star-wavefrontcontrol algorithms.
- Conduct early trade of on-board vs. ground-in-the-loop computation, develop and implement computation technology roadmap
- Conduct early trade of post-processing methodologies, spectrometers, and detectors (including energy-resolving detectors).
- Conducting this study ASAP is imperative because it can impact mission design
- Conduct studies to investigate the other above-mentioned key issues, develop and implement a post-processing technology roadmap



# **Gap: Modelling**

**Description** 

Models underlying starlight suppression error budget do not sufficiently capture as-built instrument properties in a HWO scenario

- Uncertainties in coronagraph sensitives are large
- Optical properties at millimeter to sub-micron lateral and subnanometer to picometer vertical scales have not been characterized with sufficient precision
- Stray light or luminescence interference need to be modeled and assessed in a HWO-relevant manner

Impact: High

Impacts L1 requirements.

Likelihood: High (before CGI flight), Med (after CGI flight)

• Successful CGI tech demo will mitigate some aspects of this gap.



# 7. Learning from CGI



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# **Learning fr[om the Roman Space T](https://smd-cms.nasa.gov/wp-content/uploads/2023/11/02a-lessons4future-cgi.pdf)elescope [Coronagraph Instrument Experience](https://smd-cms.nasa.gov/wp-content/uploads/2023/11/02a-lessons4future-cgi.pdf)**

- ExEP conducted extensive surveys to capture experienc the CGI project that are useful for future reference. Plea the CGI Knowledge Share and the DM Knowledge Share reports, due out later this year.
- See also Feng Zhao's (CGI Deputy Project Manager) "Ro Coronagraph Instrument (CGI) 'Lessons' for the Future" presentation: https://smd-cms.nasa.gov/wpcontent/uploads/2023/11/02a-lessons4future-cgi.pdf
- We summarize in the follow slides some high level points relevant to HWO

# **Learning from CGI: Architecture & Early Trades**

- Conduct early trades on allocating functionalities (e.g. dark-hole digging) to on-board vs. ground-in-the-loop computation
- Conduct an early trade on Spectroscopy approach (e.g. IFS, slit spectrograph, energy-resolving detectors)
- Avoid non-common-path errors in wavefront sensing
- Adopt a coronagraph architecture that can accommodate multiple coronagraph mask configurations, and allow later infusion of technology breakthroughs.
- Prioritize software architecture in system design and trade studies
- Invest in early detector technology studies and trades, including associated electronics and firmware/software functions. Define operational requirements to detectors based on science cases.



- Procure deformable mirrors (DMs) early. Each DM has unique characteristics that can impact design and ConOps
- In conjunction with the above, plan two cycles of flight mask design if possible, with the final design and fab as late as possible to capture any asbuild defects from other assemblies, flight DMs in particular.
- Reserve engineering resources and con-ops to accommodate as-built DMs with requirement deviations
- Invest early in high circuit density, high reliability (rad hard) ASICs for DM electronics
- Procure enough flight spares to allow for more a robust implementation plan and build flight-like engineering modules (EMs) to prevent subsystems from using up spares as test units
- Plan out stability model cross-checks and select experiments on key components that have the highest risks of model incompleteness.
- Due to coronagraph complexity, build full instrument engineering model, not only at the sub-element level. Run flight-like software to enforce writing meaningful/portable software early in instrument development.



- For optical modeling of coronagraphs, adequately staff the team with modelers representing different skills sets, including diffractive/HOWFSC, ray-tracing, and stray light (at a lower level). The modelers need to be have continuous insight into both the optical testbeds and flight design and built (including deformable mirrors and wavefront control software architecture), to make sure the modeling addresses project's concerns in a relevant and timely manner. Modeling team must exercise rigorous configuration control of all models.
- Ensure that the coronagraph team is in the approval loop on the observatory design requirements and changes.
- Team members at partnering centers should be provided as much access as possible to project lines of communication (meeting attendance, data repository, direct contact with all members of the team rather than through single point-of-contact).
- Ensure staffing continuity of key cognizant engineers, QA, and specialized technicians through all stages of hardware development



- Fund 2 types of DMs in parallel, make flight optical bench to accommodate either type, and select the ones that meet technical/schedule requirements
- Invest in physics-based performance and control models and validation in testbeds. System-level performance models are extremely important in timely assessment of designs, as-built flight components, and assemblies to protect schedule and preserve performance.
- Factor in cost V&V cost early in the project because it is a critical effort that requires developing a test system more stable and accurate than the coronagraph instrument. Invest enough time and resources to understand the minimum acceptable V&V plan and carefully derive its requirements. Avoid low-ball designs of key V&V equipment that prohibit later upgrades. In particular, treat dynamic simulator of light from the observatory (GSE) as instruments of equal complexity as their corresponding coronagraphs.



- Build in extra (volume, mass, power, etc.) margins beyond current Flight Project Best Practices and Design Principles at MCR and MDR for new technologies to accommodate uncertainties
- Ensure requirements flowdown are communicated and appropriately discussed avoid unnecessarily tight requirements on optical components (including DMs), which can drive schedule, complicate parts procurement, and consume valuable resources.
- Ensure communications between cognizant engineers and designers regarding bases of specifications and parts selection.
- Include all stakeholders in GSE design process, especially the end-users that will actually have to use it.



### **Learning from CGI: Modeling, Verification & Validation**

- Subsystem level testing on flight units reduces risk that issues are found at instrument level test. Or, additional testing on testbed if configuration has flight-like hardware in flight-like configuration/quantities.
- Testbed with high fidelity modeling and preferably an instrument EM are critical for validation of stability models
- As the optical hardware is delivered and aligned, incorporate the measured wavefront and alignment data into as-built ray-trace and diffractive optical models in a timely manner in parallel with the alignment process. Both asbuilt models are important in addressing questions during alignment and testing.
- Perform material testing early to validate design and analysis based on default material properties. Build an institutional database to capture all the material testing done by other projects.
- Apply engineering tolerances to all coronagraphic mask designs, including fabrication errors, alignment errors, etc. and incorporate into performance budget.


# 8. Technology Maturation Plan and Required V&V Facilities



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### **Technology Maturation Approach**

- We envision a **multipronged approach to TRL-5** by developing and testing the following critical technology subsystems of the coronagraphinstrument system in parallel
	- AO, including detectors
	- Full-scale DM
	- Starlight-suppression, including coronagraph masks and dark-hole digging computations
	- Spectrometer and post processing
	- Science camera
- The approach implies clearly defined interface requirements between components/subsystems and **carrying risks in integrated performance**. However, we posit it is the approach to reach TRL 5 within the requisite HWO-GOMAP timeframe
- **Not demonstrating at integrated-system level might become an unacceptable risk, of which HWO must be watchful**. Our maturation chart indicates opportunities for integrating subsystems to reduce risk.
- Maturation requires models and error budgets validated by test results



### **Required Facilities: Overview**

- We envision the following minimum set of test facilities to support major development activities
	- a. Subscale-pupil starlight suppression ground test facility (SSTF)
	- b. Representative-scale-pupil AO ground test facility (AOTF)
	- c. DM ground test facility (DMTF)
	- d. Spectrometer & Post-processing ground test facility (SPTF)
	- e. Detector ground test facility (DTF)
- All testbeds need models and error budgets to support (mission and instrument) systems V&V, integrated modeling, and interfacerequirement definitions



### **Required Facilities: Subscale-Pupil Starlight-Suppression Ground Test Facility (SSTF)**

- The SSTF must enable the following functionalities
	- Validate raw contrast as a function of angular separation
	- Validate predicted coronagraphic throughput as a function of angular separation
	- Validate predicted planetary PSF footprint
	- Validate predicted starlight-suppression bandwidth
	- Validate contrast sensitivities to WFEs
	- Characterize manufactured performance of key optical components for incorporation into models
	- Validate models of coronagraphic performance to optical imperfections and manufacturing tolerances
	- Characterize performance dependence on detector characteristics
	- Enable validations at required HWO wavelengths



### **Required Facilities: Subscale-Pupil Starlight-Suppression Ground Test Facility (cont'd)**

- **Comments** 
	- The SSTF will need different types of testbeds/test-stations
		- coronagraph testbeds
		- optical-component characterization test stations
	- For validation, coronagraph testbed performance must exceed mission requirements to serve at the "ruler." Raw contrast is a key parameter, and it needs to be  $\leq 1 \times 10^{-10}$ .
	- Pupil screens ("phase plates") and specialized DMs can be utilized to generate stimuli for contrast-sensitivity measurements
	- $\circ$  Combination of source  $+$  detectors in the testbeds should have characteristics scalable to the flight noise level.
	- GOMAP will need a sufficient number of coronagraph testbeds to enable simultaneous testing of multiple coronagraphs. HWO will likely require a combination of coronagraphs, each optimized for distinct objectives, to achieve all of its requirements.



### **Required Facilities: Subscale-Pupil Starlight-Suppression Ground Test Facility (cont'd)**

- **Comments** 
	- Initially, the coronagraph testbed does not require full-scale DMs. Current 48x48-actuator DMs should suffice.
	- Proving emergent technologies will require innovations in testbeds
		- Testbed design for photonic technologies require substantial studies. In particular, photonic technologies are inherently sensitive to WFEs, but requirements for characterization are currently unclear.
		- Experience in designing and implementing UV coronagraph testbeds is lacking, which has unique requirements (e.g. contamination control).



The Coronagraph Technology Roadmap

## **Closing gaps with SSTF**



Robust

Better contrast, IWA help **Static performance**



Dichroic validation helps **Mission efficiency** 



### High throughput helps **Detectors**



**Count** Lo  $Cou$ SSTF is **DMs** end to end test facility



SSTF demonstrates faster DH **Algorithms**



SSTF measures sensitivities used for **Modelling**



A dedicated testbed is needed for **Emerging Tech**





## **Required Facilities: Representative-Pupil AO Ground Test Facility (AOTF)**

- Functional requirements:
	- Utilize a segmented OTA simulator of an adequate dimensional scale (e.g., scaled telescope stimulus optics with angles of incidence representative of a full-scale optical system)
	- Utilize mission-relevant light sources and detectors
	- Validate coronagraph AO performance
		- Demonstrate dynamic contrast stability in the presence of time varying disturbances representative of the observatory dynamical environment.
		- Demonstrate dynamic contrast stability in the presence of time varying disturbances representative of the observatory thermal environment.
	- Validate predicted scattered-light noise



## **Required Facilities: Representative-Pupil AO Ground Test Facility (AOTF)**

- Key performance requirements:
	- Demonstrate contrast-stability, and scattered-light requirements at IWA and OWA,  $\sim$  10x beyond science requirements (derived by EBS, yield calculations, near-angle scatter models).
	- Extrapolation, with uncertainty quantification, to contrast stability science requirements using high fidelity modeling.
	- **Comment** 
		- The AOTF does not necessarily require a starlight-suppression subsystem



AOTF is will closes

## **Closing gaps with AOTF**



Stable wavefront enables degraded **Static performance Mission efficiency betectors** 



AOTF demonstrates WFS&C + PP **Algorithms**









AOTF measures noise rejection predicted by **Modelling Emerging Tech**







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### **Required Facilities: Spectrometer & Postprocessing Ground Test Facility (SPTF)**

- Functional requirements
	- Demonstrate integrated throughput of spectrograph architectures
	- Demonstrate post-processing techniques that might relax stability requirements during long spectroscopic exposures.
- Key performance requirements
	- Throughput driven by science requirements (EBS, yield calculations).
	- Requirements on post-processing gains TBD.



### **Closing gaps with SPTF**

Post processing with SPTF will reduce impact of **WFE-Stability**



SPTF demonstrate operations with degraded **Static performance**



### **Mission efficiency**



SPTF demonstrates **Detectors** in relevant environment



**Count** Lo **Count** Low Med High Large Med Small Impact Gap Size DMs

SPTF will demonstrate PP **Algorithms**



SPTF anchors spectrograph **Modelling**



SPTF demonstrates **Emerging Tech** for spectroscopy





## **Required Facilities: Detector Ground Test Facility (DTF)**

- Functional requirements:
	- Validate detector performances (QE, read noise, dark, flat, CIC) for imaging.
	- Validate detector performances (read noise, dark, flat, CIC) for spectroscopy.
- Key performance requirements
	- o Detector performances for imaging and spectroscopy are driven by science requirements (EBS, yield calculations).
	- Detector performances for wavefront sensing are driven by high fidelity model for contrast stability.
- Comment
	- If HWO decides to utilize energy-resolving detectors, DTF and SPTF might become one and the same



The Coronagraph Technology Roadmap

### **Risk reduction with DTF** DTF might enable









DTF will validate **Detector**  technologies









SPTF will anchor detector **Modelling**



**Emerging Tech**





## **Closing gaps with DTF**



DTF enable degraded **Static performance**  (throughput)



DTF demonstrates higher **Mission efficiency** 



DTF closes **Detectors** Gap





**Algorithms**



SPTF anchors detector

**Modelling**



### **Emerging tech**





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## **Maturation Plan: Notional Baseline**

- The next slide shows our roughly estimated maturation schedule to meet the sixyear timeline described in Astro2020
- We posit that the different critical technology elements (starlight suppression optics, adaptive optics, full-scale DMs, etc.) can be matured and validated independently for TRL-5, with clearly defined interface requirements between elements
- We derived notional timescales using the following boundary conditions
	- Overall timeline for developing critical HWO technologies is six years, based on Astro2020
	- The six year clock starts when NASA begins investing in HWO technology on the  $\sim$  10<sup>8</sup> \$/yr scale
	- The overall timeline show comprises the above-mentioned six years plus a lead-in period (starting now)
	- Within each development tack of critical technology element, we estimated the relative required timescale for each phase and fit the end-to-end timescale into the overall timeline
- As such, this is *not* a grass-roots-estimated schedule
- The end of each arrow-shaped bar represents a milestone (in accomplishing the corresponding task/objective)
- **Whether or not the envisaged schedule can be accomplished depends on invested resources**



### **Maturation Plan: Opportunities**

- The next slide shows opportunities in risk reduction by integrating different critical technology elements before TRL 5
- Each critical technology element is represented by a different symbol.
- Appearance of a symbol in the track of another critical technology element represents an integration opportunity





# 9. Glossary of Abbreviations



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### **Glossary of Abbreviations**





### **Glossary of Abbreviations (cont'd)**





### **Glossary of Abbreviations (cont'd)**





### **Glossary of Abbreviations (cont'd)**





# Feedback from Working Group Members



### **Readme**

- A draft of this report was circulate to all members of the CTR Working Group for feedback
- The following slides summarize the 116 feedback comments from 11 members: M. Bottom (U. Hawaii), N. Jovanovic (Caltech), B. Dube (NASA JPL/Caltech), A. Carrier (Lockheed Martin), H. Zhou (NASA JPL/Caltech), C. Stark (NASA GSFC), O. Guyon (U. Arizona), V. Bailey (NASA JPL/Caltech), R. Belikov (NASA ARC), R. Juanola-Parramon (GSFC), N. Siegler (NASA ExEP, JPL/Caltech)
- Rows shaded green indicate that we have implemented suggested changes (or, in a few cases, we removed the content to which the comment pertained). Responses to other comments are yet to be implemented.






















































# 10. Appendix



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#### ExEP

# **Estimate of UV Throughput for Target-List Calculations**

Pin Chen June 26, 2023



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### **Reflective Losses**

- Using Exo-C as a telescope-coronagraph optical layout driven by coronagraphy (per J. Trauger's suggestion)
- Number of reflections
	- Telescope: 2
	- Downstream: 13
		- 1 tertiary mirror
		- 1 FSM
		- 2 pupil re-imaging mirror
		- 2 DMs
		- 1 focusing mirror
		- 1 collimating mirror (to form Lyot pupil conjugate)
		- 1 focusing mirror (for field stop)
		- 1 collimating mirror (for filters)
		- 1 fold mirror
		- 1 focusing mirror
		- 1 flip mirror
	- TOTAL: 15 reflections
- Reflection throughput, AI coating  $(R = 0.92)$ :  $0.92^{15} = 0.29$



#### **Exo-C Instrument Layout**



Figure 5.5-1. Instrument bench optical layout. The elements are distributed into two planes to provide a compact package, so there are no interferences between elements and light paths even where apparently conflicting in the figure.



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# **SSTF initial experimental plan**

- **A. Demonstrate** *repeatable* **raw contrasts that are sufficiently deep for compelling science yield and achievable contrast stability.**
- In this case the raw contrast goal ought to ultimately be set following analyses from START and TAG.
- While waiting for the outcome of such analyses, an immediate goal is to improve upon the contrast floor of this experiment by tracking the limiting factors identified in Seo et al. (2019) .
- In order to establish repeatability, it will be important to identify the root cause of the contrast instabilities reported in Seo et al. (2019), and in particular investigate the hypothesis that these drifts are driven by DM settling.



# **SSTF initial experimental plan**

#### **B.Change/add key components one at a time and repeat step A.**

- Possible changes of components are, in no particular order:
	- $\circ$  Add a UV coating on one of the optics.
	- Change the coronagraph mask for one optimized at smaller inner working angles, or for higher throughput.
	- $\circ$  Introduce a dichroic in the optical train.
	- $\circ$  Introduce a segmented pupil without residual static segment phasing errors.
	- $\circ$  Introduce a segmented pupil with residual static segment phasing errors.
- In between each experiment with a new component, stable contrast (step A) should be reproduced in order to re-establish the baseline.
- Experiment prioritization ought to be set following analyses from START and TAG.



# **SSTF initial experimental plan**

**C. For architectures tested in A, and B, once the required contrast is reached, the modulated (e.g. coherent) sensitivities to wavefront errors should be measured using the procedure reported in Zhou et al. (2020, Proc. SPIE)**

Possible wavefront sensitivities to measure, in no particular order:

- $\circ$  Low order wavefront errors at the entrance pupil.
- Coronagraph mask misalignment.
- Pupil misalignments, magnification, beam shear, and beam walk.
- Wavefront error due to segmentations (segmented pupil with residual static segment phasing errors).
- In case of limited resources, prioritization of the most pressing sensitivity measurements, as well as actual magnitude of wavefront changes for these experiments, ought to be set following analyses from START and TAG.





#### Detector Fact-Finding Spreadsheet (J. Trauger, V. Bailey, B. Dube)

