



**Jet Propulsion Laboratory**  
California Institute of Technology



# **Deformable Mirror Survey for Future Exoplanet Direct Imaging Space Missions**

## **Overview and Results**

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# Survey Goals



1. Survey and document viable DM technologies across the world to inform future exoplanet missions about their capabilities and technology readiness.
2. Make recommendations for DM technologies based on factors such as mission performance requirements, estimated development cost, technology readiness, and how best to advance (directed vs competed).

# Survey Team and Scope



*We assembled a group of international Subject Matter Experts in deformable mirrors and high-contrast imaging.*

- *Tyler Groff (NASA Goddard)*
- *Matt Bolcar (NASA Goddard)*
- *Ruslan Belikov (NASA Ames)*
- *Tim Morris (UK Astronomy technology centre / Durham University)*
- *Stefan Strobele (European Southern Observatory)*
- *Pierre Baudoz (Observatoire de Paris)*
- *Jeremy Kasdin (Princeton Univ. / USFCO)*
- *Olivier Guyon (Univ. of Arizona)*
- *Chris Mendillo (U. Mass Lowell)*
- *John Trauger (JPL)*
- *Pin Chen (JPL)*
- *Camilo Mejia Prada (JPL)*

*DM Survey context: Identify a DM for a future exoplanet flagship mission, thus, the evaluation is based on such mission requirements*

# KT Matrix to organize and evaluate



## Evaluation criteria defined in agreement with SMEs

- Establish what are the WFC requirements and how this translates to DM specifications (for a future exoplanet mission)
- Identify programmatic and commercial constraints for those requirements

## The KT matrix structure was used to organize the requirements

### Descriptors (22)

- Set of technical and business characteristics that define a technology and vendor working on it.

### Musts (4)

- Essential characteristics that a given technology must be meet to be considered.
- Binary criterion, yes or no. All criteria must be met.

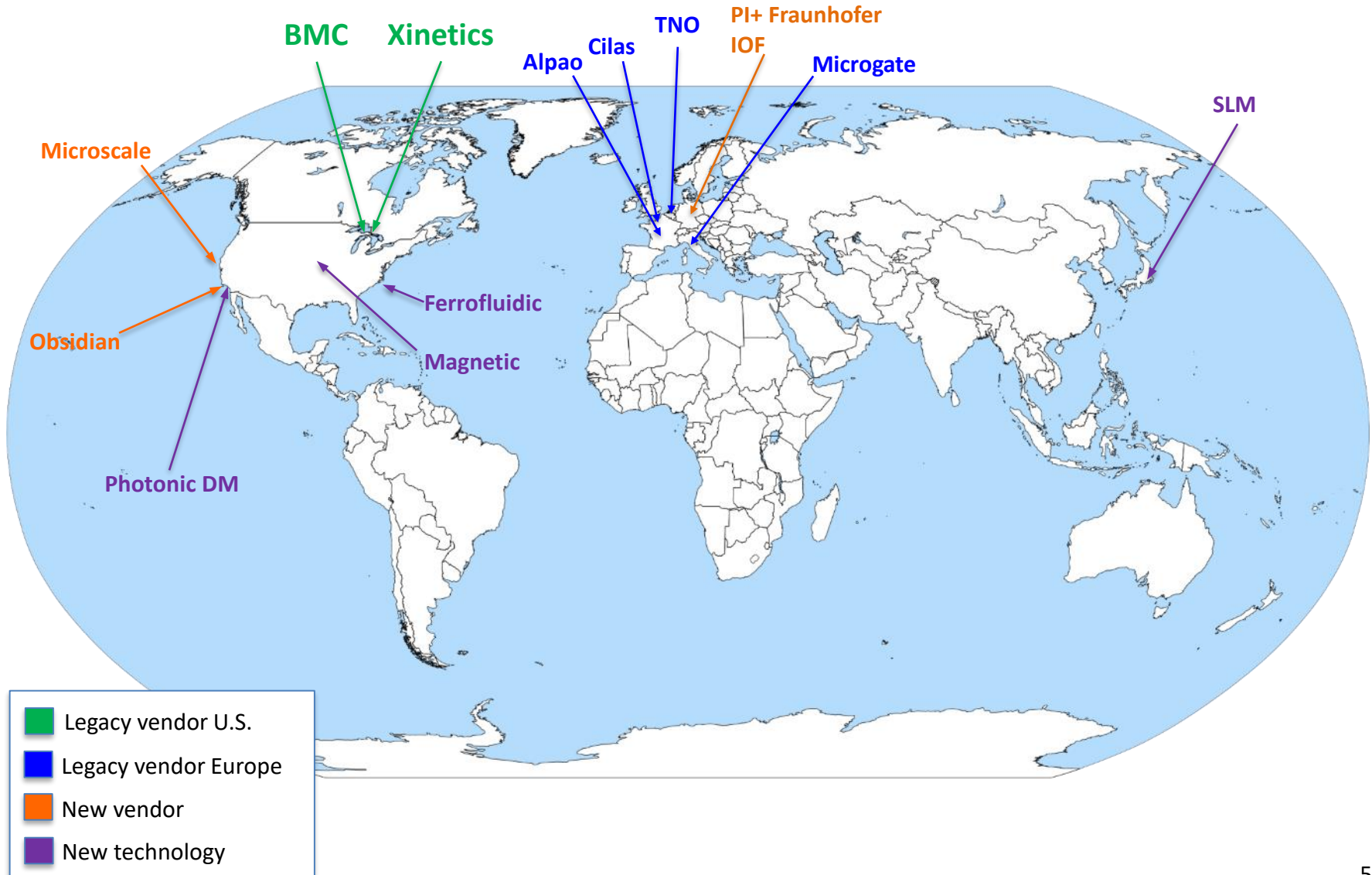
### Wants (23)

- Each one has a weight to define its importance.
- All of them have a score discretized in five levels.

### Risks (10)

- Risk are potential problems that a technology might have.
- Severity is discretized in five levels. No weights.

# Fact Finding



## Comprehensive search found 13 DM vendors or technologies

### 1) DM legacy vendors

- Four in Europe:
  - ALPAO (France)
  - Microgate (Italy)
  - Cilas (France)
  - TNO (The Netherland)
- Two in the U.S.:
  - BMC
  - Xinetics

### 2) New vendor using legacy technologies

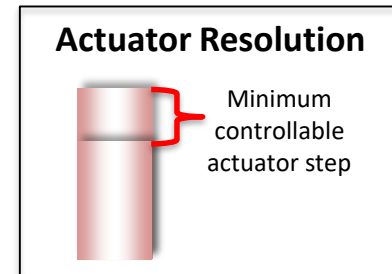
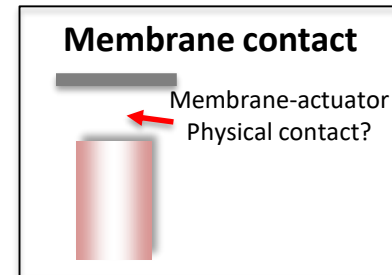
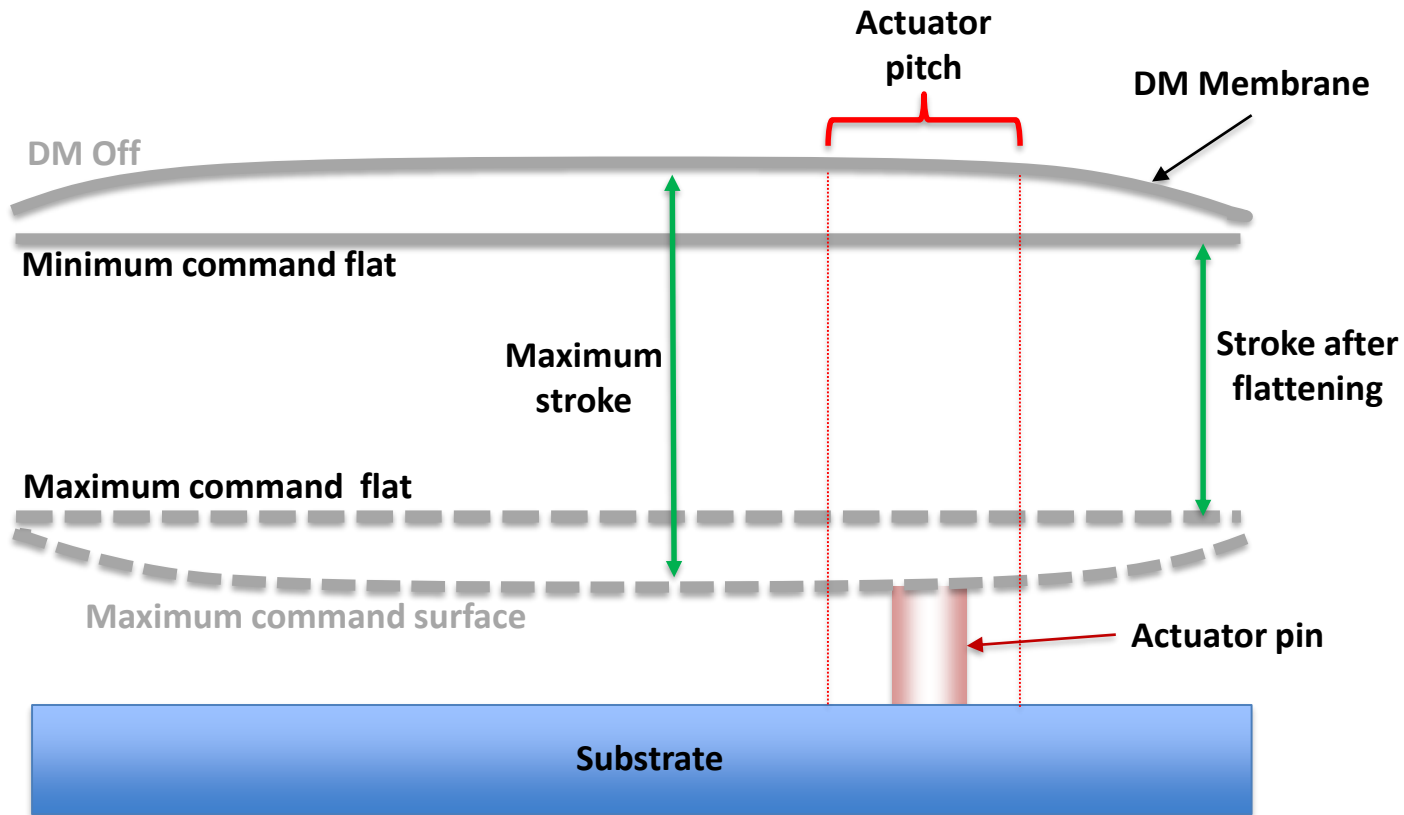
- Microscale
- PI Fraunhofer

### 3) New technology developments

- Obsidian
- Spatial Light Modulator (LCoS)
- Ferrofluidic
- Photonic DM
- Magnetic (APERTURE concept)

## DM Technologies overview

# Definitions

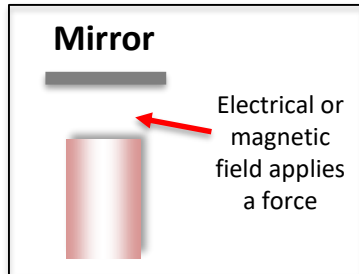




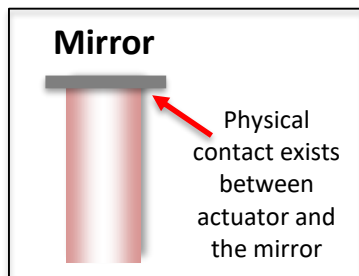
# Technologies overview

## Actuation type

Contactless technologies



Contact technologies



- Electrostatic  
BMC, Obsidian
- Electromagnetic  
ALPAO, Microgate, TNO
- Magnetic  
APERTURE

- Electrostrictive  
Xinetics, Microscale
- Piezo/monomorph  
Cilas, PI+Fraunhofer (PICMA)
- Photonic  
Sparse DM

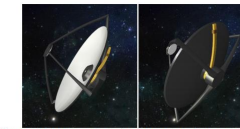
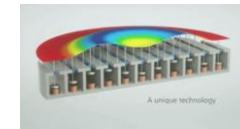
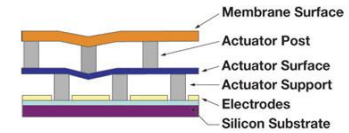
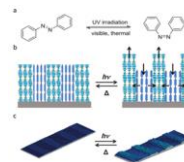
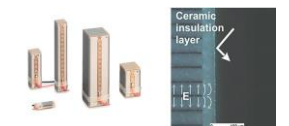
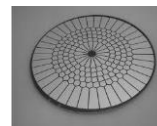
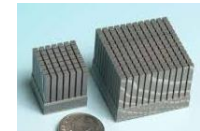
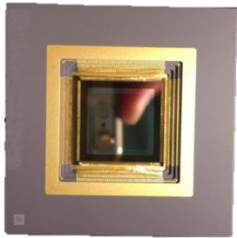


Figure 1 APERTURE concept. For simplicity only one satellite head is shown. The QR code leads to an animation depicting the concept found here <http://bit.ly/1x100a>.

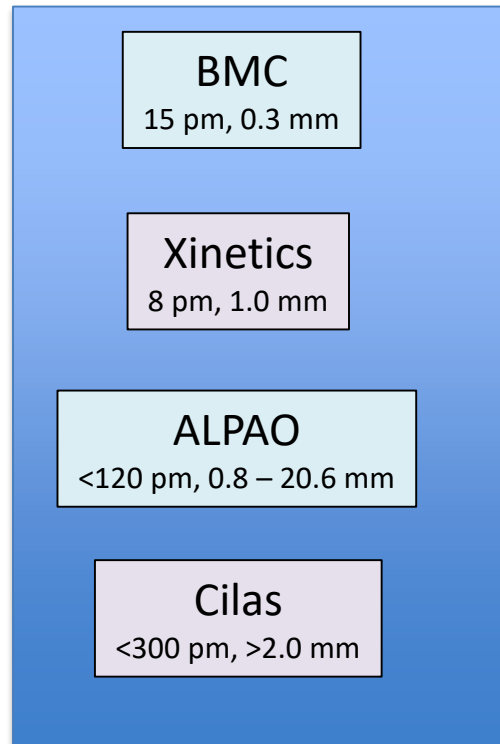


# Technologies overview

## Small format v/s large format

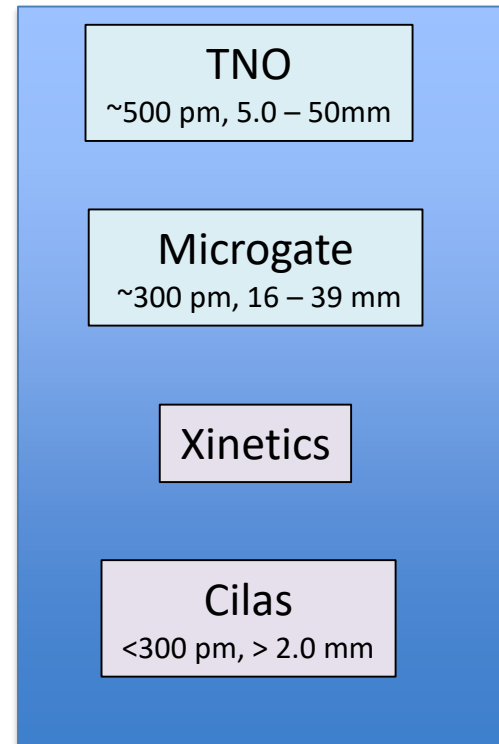


### Small format (Coronagraph level)



**U.S. & European  
vendors**

### Large format (Telescope level)



**Mostly European  
vendors**



# Legacy technologies

## Boston Micro Machines (BMC, U.S.)

**Technology:** Contactless Electrostatic actuation

### Pros:

- Fast and stable actuation
- Large format >3000 actuators demonstrated
- High stability
- High resolution
- Small actuator pitch

### Cons:

- Surface quilting
- Reduced stroke for large formats



# Legacy technologies

## AOX Xinetics (U.S.)

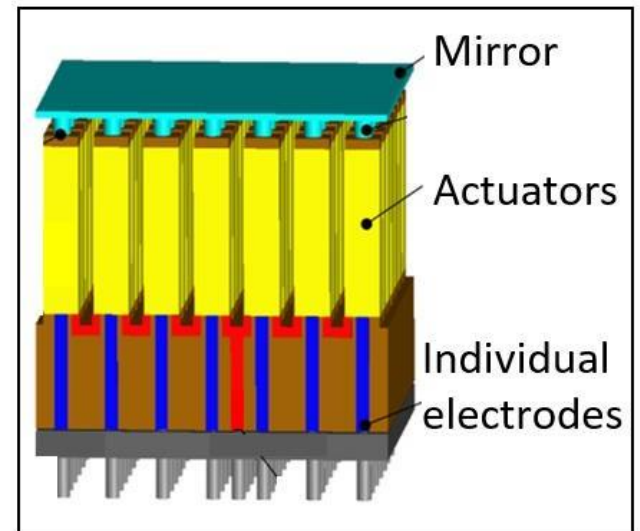
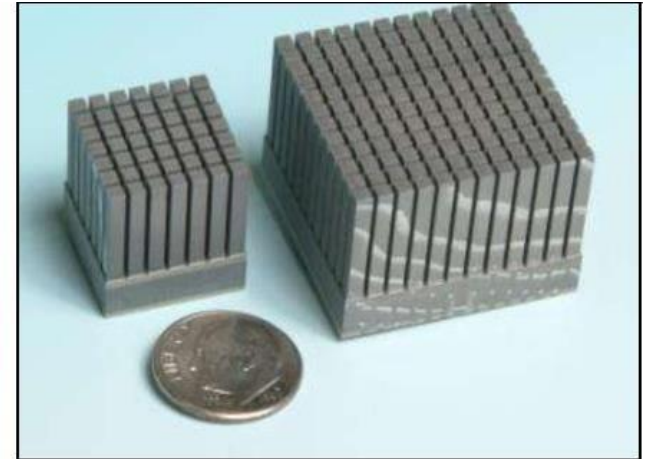
**Technology:** Contact Electrostrictive PMN technology

### Pros:

- Fast actuation
- Large format >3000 actuators demonstrated
- High resolution
- High surface quality

### Cons:

- Stability requires thermal control
- Larger actuators (than BMC) 1 mm pitch
- Small stroke



# Legacy technologies

## ALPAO (France)

**Technology:** Indirect Contact Magnetic

### Pros:

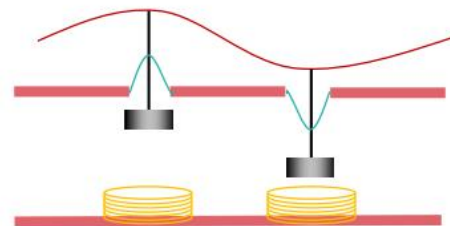
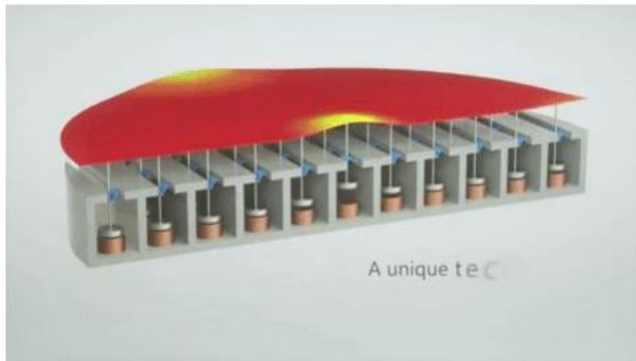
- Fast actuation
- Large format (64x64 and 128x128 for EELT)
- Large stroke
- Embedded electronics
- Low voltage operation

### Cons:

- Residual surface WFE not known at  $\sim 1\text{nm}$  level
- Sub nanometer resolution not demonstrated



- Continuous surface motioned with magnetics actuators



# Legacy technologies

## Microgate (Italy)

**Technology:** Contacless Magnetic (Voice coils with levitating thin shell mirror)

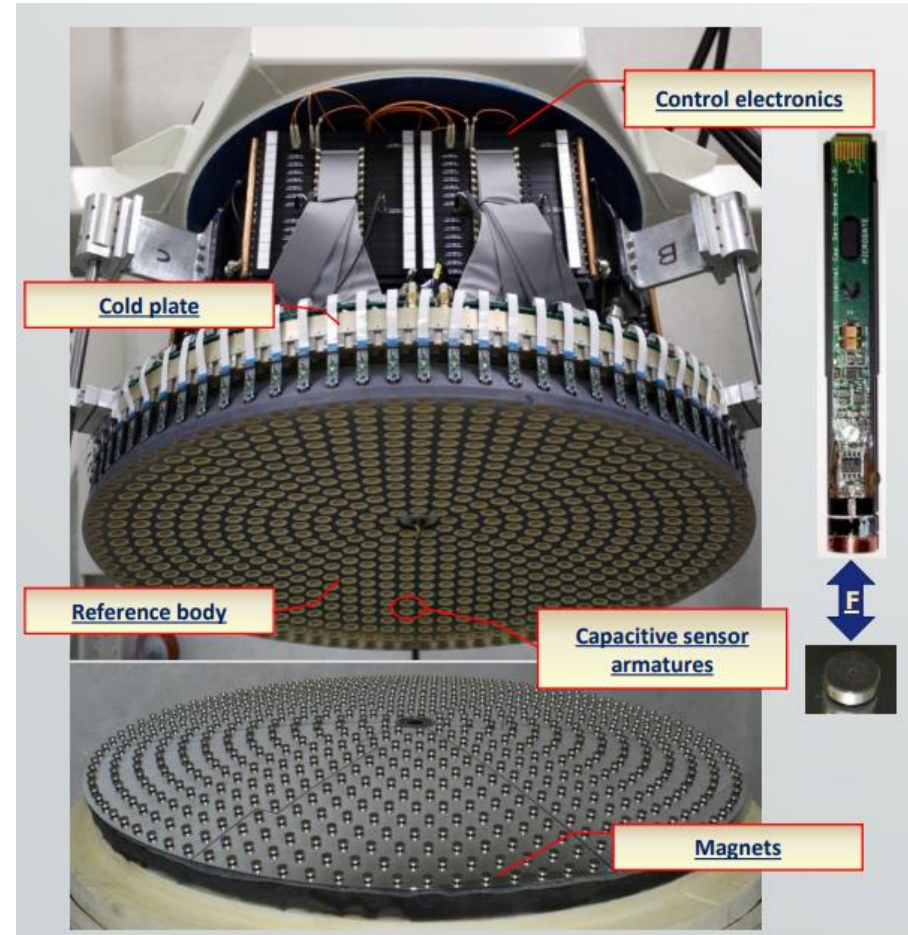
**Pros:**

- Many ground based secondaries (6.5m MMT, 8.4m LTBx2, 6.5m Magellan, UT4 VLT, GMT and ELT (5316 actuators))
- Fast actuation, levitating thin shell allows fast and pure tip/tilt control
- Large format (64x64 and 128x128 for EELT)
- Large stroke

**Cons:**

- Sub nanometer resolution not demonstrated
- Large actuators (>18 mm)

=> Potential for a secondary DM mirror in space



# Legacy technologies

## Cilas (France)

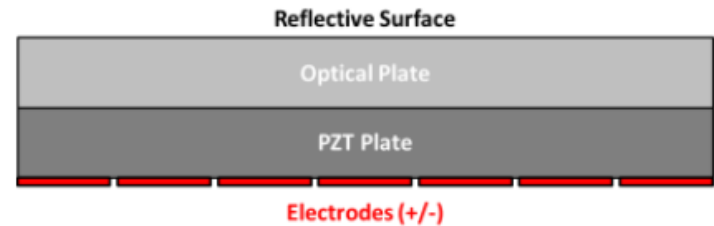
**Technologies: Bimorph and Stack**

### Pros:

- > 20 yr heritage, many ground based system
- Fast actuation
- One piece construction
- Large stroke
- OTOS space DM at high TRL but low number of actuators

### Cons:

- Few actuators (Bimorph)
- Thermal drift and hysteresis



# Legacy technologies

## TNO (Netherlands)

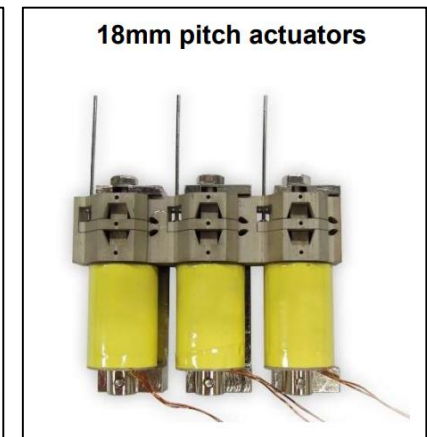
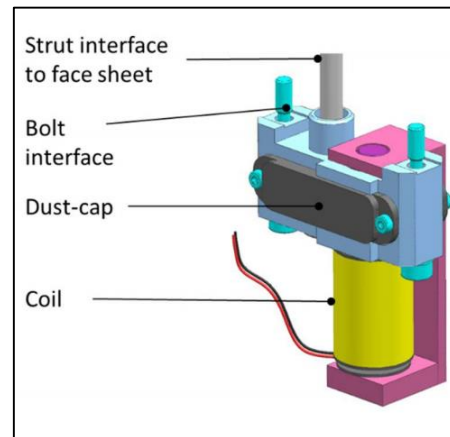
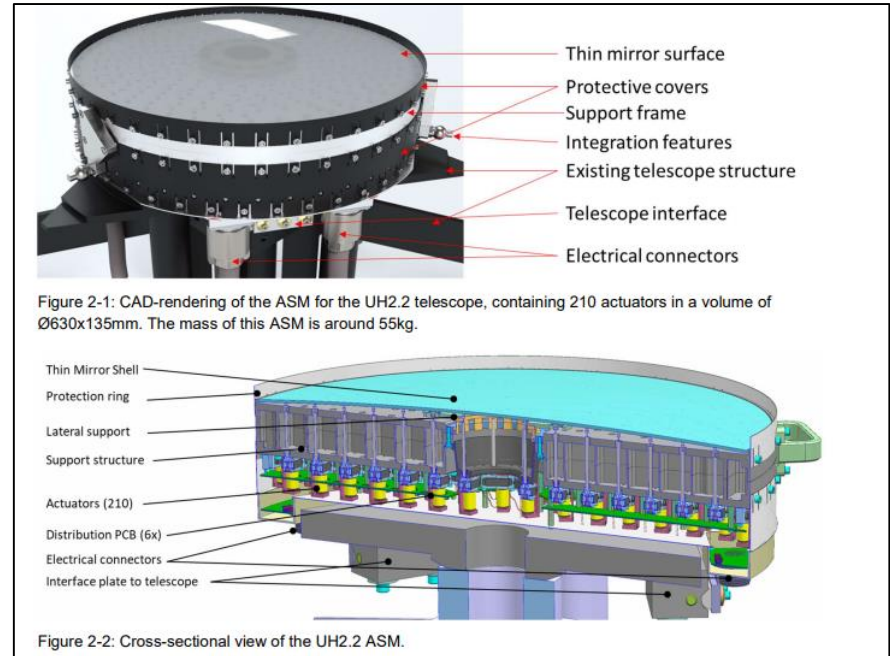
**Technology: Electromagnetic hybrid-variable-reluctance actuators**

### Pros:

- Large force and low consumption
- Large stroke
- High linearity
- Resolution v/s stroke can be traded in the mechanical lever

### Cons:

- Few units built
- Few actuators
- Thermal drift and hysteresis
- Large pitch (> 4.3mm)





# New technologies and companies

## PI + Fraunhofer (Germany)

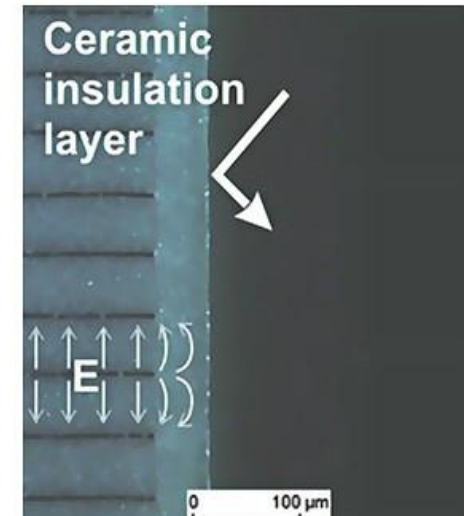
**Technology:** Multilayer PIEZO (PICMA) direct DM Actuation

### Pros:

- Scalable to >10,000 actuators
- Similar technology to PMN used by Xinetics
- Reputed vendor and ground based application in development
- Extension to space application can be explored

### Cons:

- Weight
- Polishing and print through
- Stability and drift



# New technologies and companies

## Obsidian (U.S.)

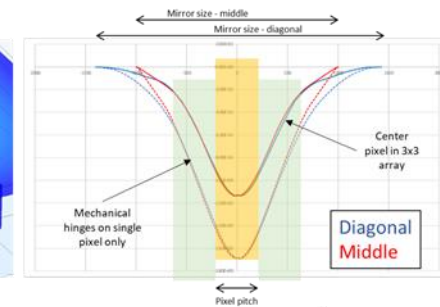
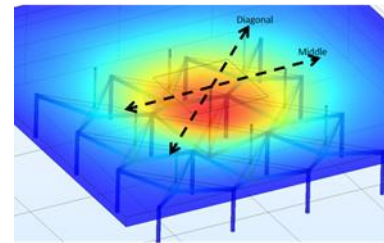
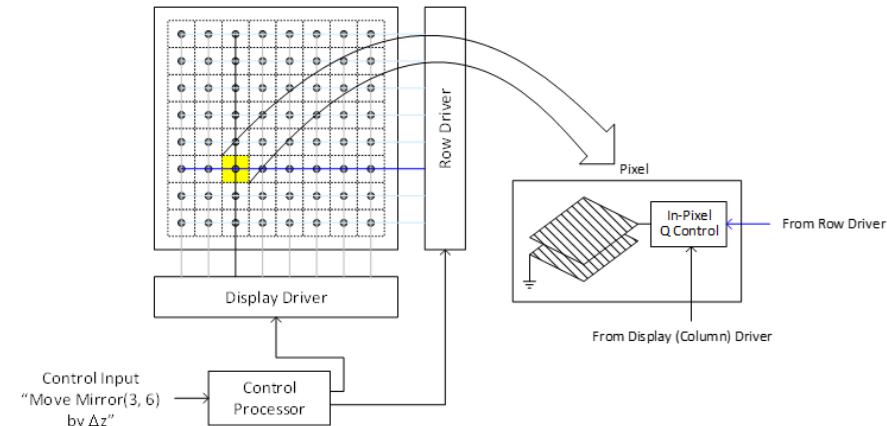
**Technology:** Active-Matrix Programmable Mirror (AMPM)

### Pros:

- N channel control, *Not*  $N^2$ , for NxN Array
- Charge Drive, *Not* Voltage Drive
- Low voltage drive, < 20V
- High accuracy using available components
  - 17-bit accuracy, using 10-bit driver IC
  - Made possible with Intrapixel Charge DAC
  - 10 pm resolution for 1  $\mu$ m stroke

### Cons:

- TRL-3
- 8-bit default dynamic range, can be increased
- Possible surface print through



Technology inherited from displays:

- Use an effect called interferometric absorption in which a thin absorbing metal layer in front of a highly reflective mirror surface selectively absorbs different colors, depending on the gap that separates the two.
- **The gap is controlled by electrostatic actuation** in a relatively simple microelectro-mechanical-system structure.

# New technologies and companies

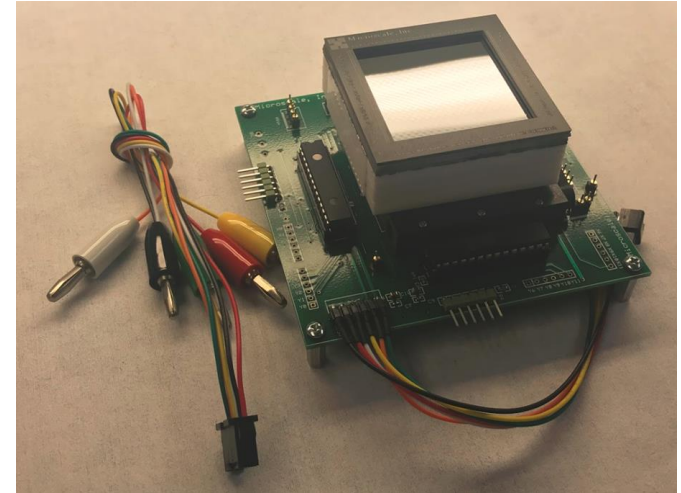
## Microscale (U.S.) NASA APRA funded Technology: ASIC controlled PMN actuator

### Pros:

- Electrostrictive PMN technology
- ASIC driver integrated with the DM
- Manufacturing ongoing
- Radiation testing ongoing
- 32x32 actuator device built

### Cons:

- Optical performance test pending
- Time multiplexing can be difficult to tune



PMN-PT stack actuator array Integrated 32x32 DM-ASIC System

# New technologies

## APERTURE (U.S.) NASA NIAC funded

### Concept:

- The mirror is made of a foldable and ultra-light metallic membrane
- Magnetic head scans the mirror and correct shape magnetizing the DM surface alloy

### Pros:

- DM is ultra-light and foldable
- DM can have power and serve as primary or secondary mirror
- Continuous DM, actuators defined by the scanning resolution
- Simpler electronics and conectorization. Only one cable to magnetic head

### Cons:

- TRL-2/3
- Difficult to validate performance on Earth
- Stability is a major challenge



Figure 1 APERTURE concept. For simplicity only one write head is shown. The QR code leads to an animation depicting the concept found here [link to video](#)

# New technologies

## Photonic DM (U.S.)

### Concept:

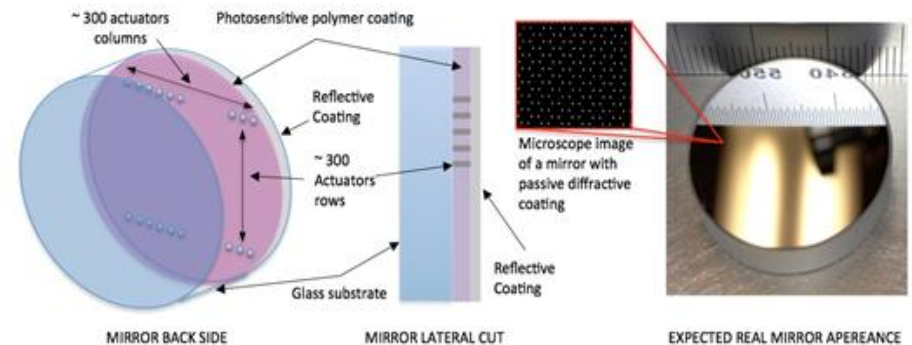
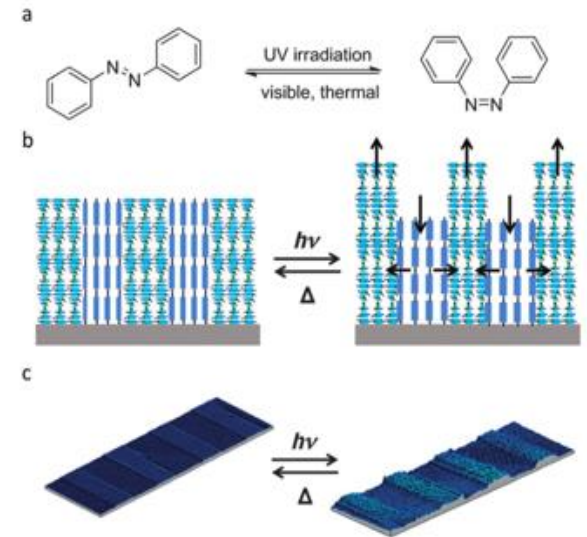
- A photosensitive polymer is applied between the mirror substrate and the reflective coating.
- Mirror actuation is achieved by illuminating the polymer from the back of the mirror causing a reversible isomerization, resulting in a volume change.

### Pros:

- Continuous DM, actuators defined by the scanning resolution
- No cabling or electronics on the DM
- Can be applied on powered surfaces

### Cons:

- TRL-2
- Polymer drift
- Small stroke (<1 $\mu$ m)



# New technologies

## Parabolic DM (U.S./France)

### Concept:

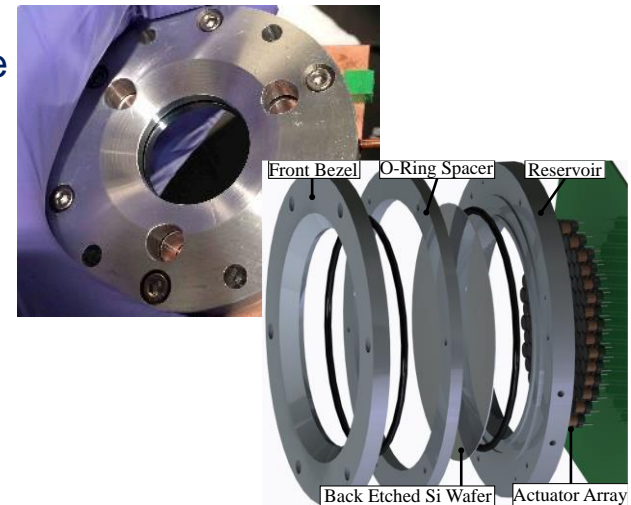
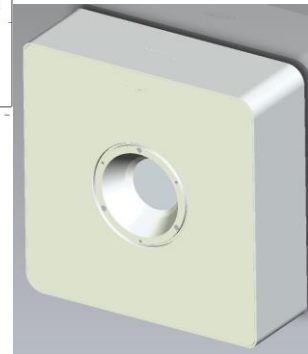
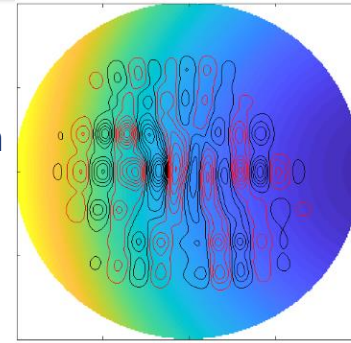
- DM integrated into the off-axis elements of the coronagraph
- Focusing on limited (~324) actuators. Scaling options exist
- Actuation methods
  - Legacy: Ferrofluids/Electromagnetic\*
  - Active Development: ALPAO Electromagnetic
  - Identified potential: PMN
- TRL 3-4

### Pros:

- Continuous DM on coronagraph's powered surfaces
- Eliminates need for a second non-pupil DM
  - Instrument with Pupil DM + Parabolic DMs requires approx. half required actuators for same performance
- Eliminates Talbot effects → Increased bandwidth
- Contributes multiple surfaces which directly compensate low and mid-spatial frequency error

### Cons:

- Some active actuation required achieve final shape to reduce prototype complexity. Static design path exists.
- Currently small stroke (<1 $\mu$ m). Available stroke increases as required stroke for OAP shape goes down
- Shares stability limitations of actuation method



# New technologies

## Spatial Light Modulator (SLM)

**Technology:** Liquid Crystal on Silicon (LCoS) that control the phase delay per pixel

### Pros:

- Millions of actuators
- Fast response
- High resolution, 16-bit over 1 wavelength
- Small, no moving parts
- Commercial component, low cost.

### Cons:

- Chromatic device
- TRL 3-4
- Not tested in vacuum
- Sensitive to intense light and radiation



# New technologies

## Free Surface Ferrofluid DM (U. Laval, Canada)

### Concept:

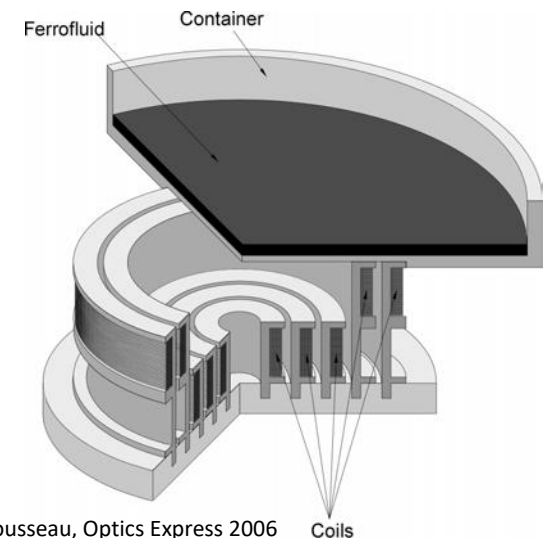
- Silver suspension over Ferrofluid
- Electromagnetic control of free-fluid surface

### Pros:

- Continuous DM
- Fast response
- Extremely high stroke

### Cons:

- TRL 3-4
- Uncontained fluid not suitable application for space
- Free fluid has potential sensitivity to vibration
- Orientation constrained to be horizontal



Brousseau, Optics Express 2006



- DM actuator resolution and stability (for contactless) is limited by the control electronics, not the actuator itself.
- Trade-off resolution versus stroke is possible for all the technologies.
- The resolution values listed in the following slides have been implemented in at least one of the DM units.
- For most DMs the resolution is interpolated from the actuator response, but not directly measured. Exceptions are Xinetics with VSG (20 pm) and BMC with Zernike WFS.

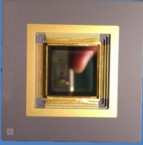

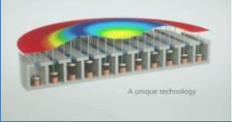

## Take away:

- 1) Custom electronics can improve the resolution of any of the DMs studied if stroke is sacrificed.
- 2) Stability is the limiting factor if resolution requirement is achieved

# Legacy vendors and technology overview

## Small format

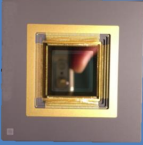

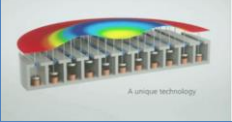



	BMC 	Xinetics 	ALPAO 	Cilas 
Technology	Electro static force between pin and membrane	Electrostrictive (PMN) material	Electromagnetic	Bimorph piezoelectric actuation
Control type	Voltage	Voltage	Current	Voltage
Membrane contact	None	Yes	Indirect	Yes

# Legacy vendors and technology overview

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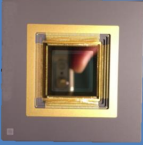

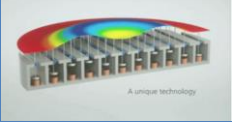



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Control type	Voltage	Voltage	Current	Voltage
Membrane contact	None	Yes	Indirect	Yes
Actuator pitch	0.3 - 0.45 mm	1.0 - 2.5 mm	0.8 – 20.6 mm	≥ 2 mm
Actuator stroke	1 to 2 $\mu\text{m}$	0.5 $\mu\text{m}$	8 – 25 $\mu\text{m}$	20 $\mu\text{m}$ (OTOS)

# Legacy vendors and technology overview

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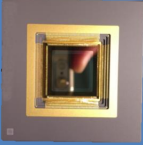

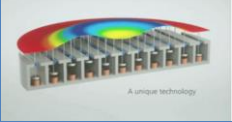



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Actuator stroke	1 to 2 μm	0.5 μm	8 – 25 μm	20 μm (OTOS)
Actuator count	4096 (64x64)	4356 (66x66)	3228 (64 across)	188(OTOS has 63)
Capability	Up to 9216 (96x96)	Up to 9216 (96x96)	Up to 12912 (128 across)	Few hundreds

# Legacy vendors and technology overview

## Small format

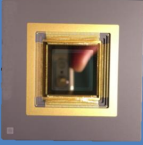

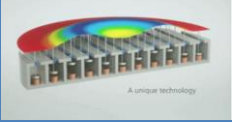



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Actuator resolution	15 μm	20 μm measured	120 μm	~300 μm
Capability	15 μm	8 μm	15 μm	50 μm

# Legacy vendors and technology overview

## Small format






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Actuator resolution	15 μm	20 μm measured	120 μm	~300 μm
Capability	15 μm	8 μm	15 μm	50 μm
Key limitations for flagship mission	Surface Quilting, actuator <b>count</b>	Actuator <b>pitch</b> , stability	Actuator <b>pitch</b>	Actuator <b>count</b> , <b>pitch</b> and resolution
Company information	U.S. Based DMs are the main business Independent company	U.S. Based DMs are the main business Parent: Northrop Grumman, strategic business unit	France DMs 70% of \$4M revenue Parent: Eveon	France DM's 10% of revenue Ariane group and AREVA

# Legacy vendors and technology overview

## Large format






	Microgate 	TNO 	Xinetics	Cilas 
Technology	Electromagnetic	Electromagnetic	Electrostrictive (PMN) material	Bimorph piezoelectric actuation
Control type	Current with feedback	hybrid-variable-reluctance principle.	Voltage	Voltage
Membrane contact	None	Yes	Yes	Yes

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Membrane contact	None	Yes	Yes	Yes
Actuator pitch	16 - 39 mm	5.0 – 50 mm	NA	≥ 2 mm
Actuator stroke	100 μm	40 μm	NA	20 μm (OTOS)



# Legacy vendors and technology overview

## Large format


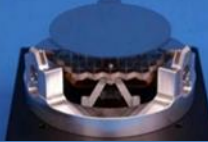



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Membrane contact	None	Yes	Yes	Yes
Actuator pitch	16 - 39 mm	5.0 – 50 mm	NA	≥ 2 mm
Actuator stroke	100 μm	40 μm	NA	20 μm (OTOS)
Actuator count	1170 (VLT UT4)	210 (UH 2.2m)	NA	188 (OTOS has 63)
Capability	Up to 5316 (E-ELT)	Up to 3500 (TMT)	NA	Up to 250

# Legacy vendors and technology overview

## Large format






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Actuator count	1170 (VLT UT4)	210 (UH 2.2m)	NA	188 (OTOS has 63)
Capability	Up to 5316 (E-ELT)	Up to 3500 (TMT)	NA	Up to 250
Actuator resolution	300 pm (based on accuracy)	500 pm	NA	~300 pm
Capability	TBC	50 pm (TBC)	NA	50 pm

# Legacy vendors and technology overview

## Large format



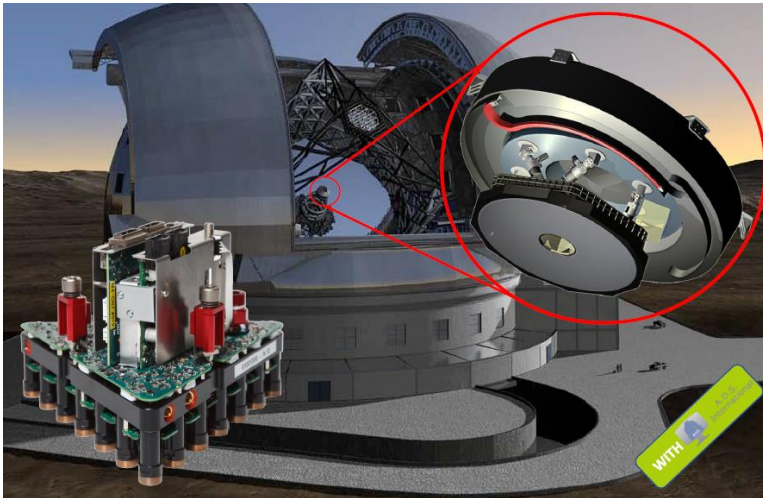
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Actuator resolution	300 pm (based on accuracy)	500 pm	NA	~300 pm
Capability	TBC	50 pm (TBC)	NA	50 pm
Key limitations for flagship mission	Actuator <b>pitch</b>	Actuator <b>pitch, count</b>	NA	Actuator <b>count, pitch</b>
Company information	Italy DMs are 30% of revenue Revenue €11M AdOptica (Microgate + ADS)	Netherlands DMs are less 1% Revenue €534M TNO and VDL	U.S. Based DMs are the main business Parent: Northrop Grumman, strategic business unit	France DM's 10% of revenue Ariane group and AREVA

\* Cilas for Bimorph, Stack technology can go up to 3000 actuators

# Is a large format DM an option for space?

## Woofers-tweeter architectures have been implemented in ground based telescopes

- Subaru AO 188 + SCExAO (2K BMC)
- Baseline for future ELTs  
For example E-ELT uses:
  - M4 (2.5m, 5316 actuators)
  - Extreme AO, 11,000 actuators



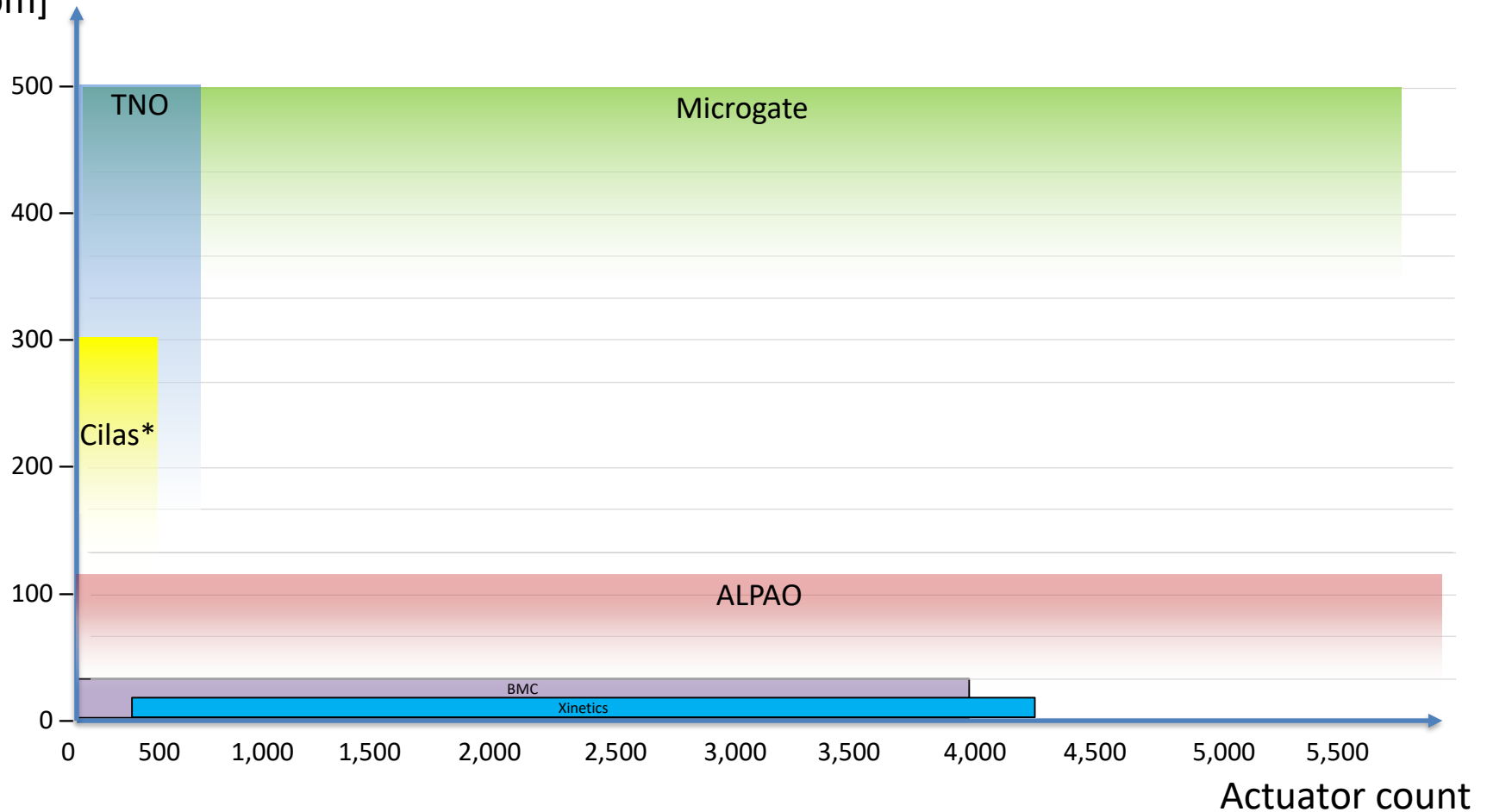
Planned M4 deformable mirror at E-ELT with 5315 actuators under development by Microgate



Deformable Secondary Mirror at the VLT UT-4 with 1170 actuators made by Microgate

# Resolution vs actuator count

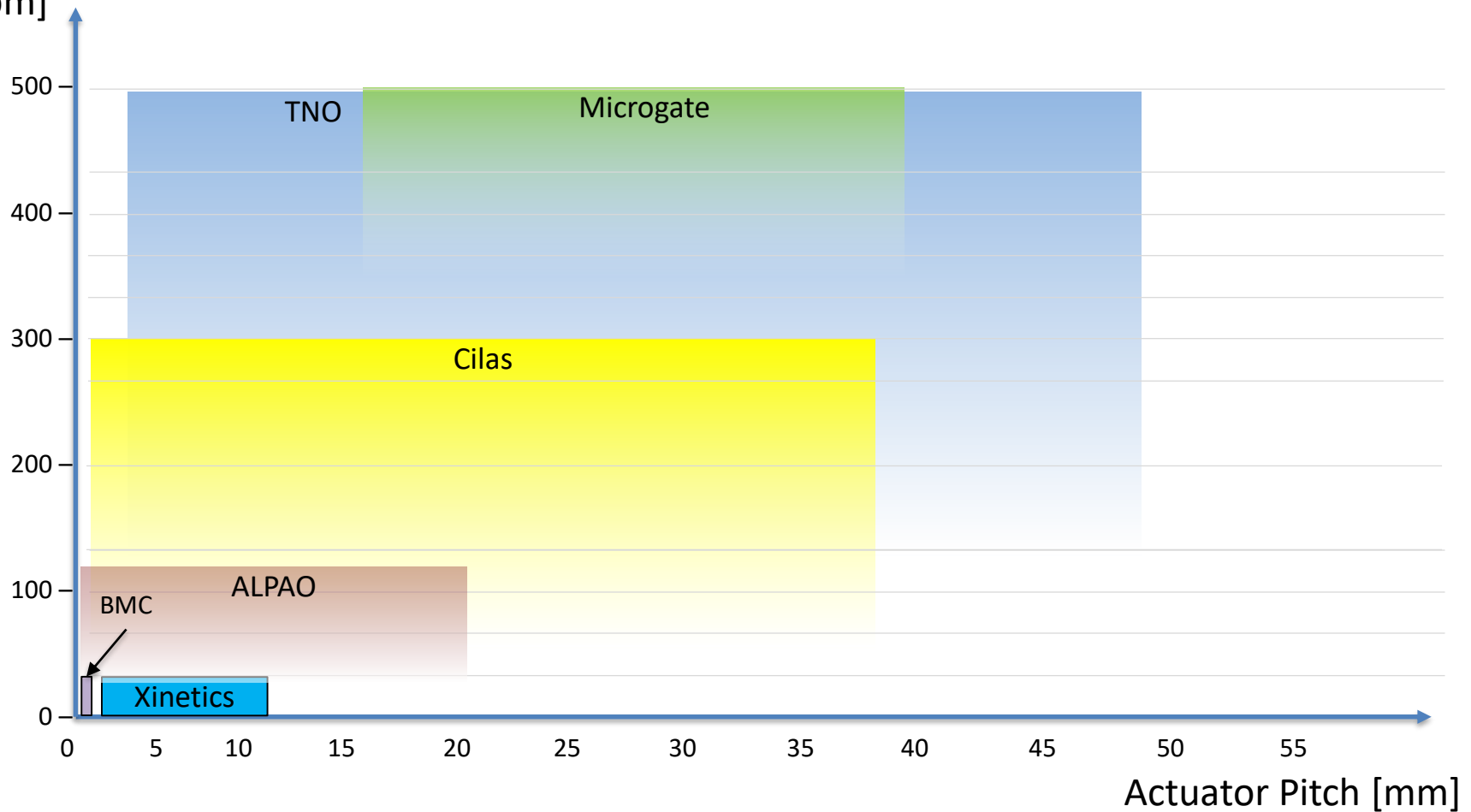
Actuator resolution  
[ $\mu\text{m}$ ]



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# Resolution vs actuator pitch

Actuator resolution  
[pm]



# Space qualification and TRL



	Qualification effort	TRL	Results/Next steps
MEMS BMC 140	DeMi cubesat mission flight	TRL-7	Measurement fidelity no high enough, orbit and mission duration not relevant.
MEMS BMC Kilo	Environmental (TVAC), Shake, vibe and performance	TRL-5	Princeton-BMC TDEM test were inconclusive, flight on Picture-C proved survivability.
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TNO 427, 57	Environmental testing and design	TRL-4/5	427 actuator prototype built. 57 actuator with hybrid-variable-reluctance being built
CILAS (OTOS 63)	Performance demonstrated in relevant environment	TRL-6	Flight demonstration pending (TRL definition may not match)

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Microgate (LATT 19)	Environmental (TVAC), Shake, vibe and performance	TRL-5	Actuator count, pitch and resolution not relevant to flagship missions. Potential for development exist as levitation is not necessary in space reducing power consumption

# Space qualification and TRL



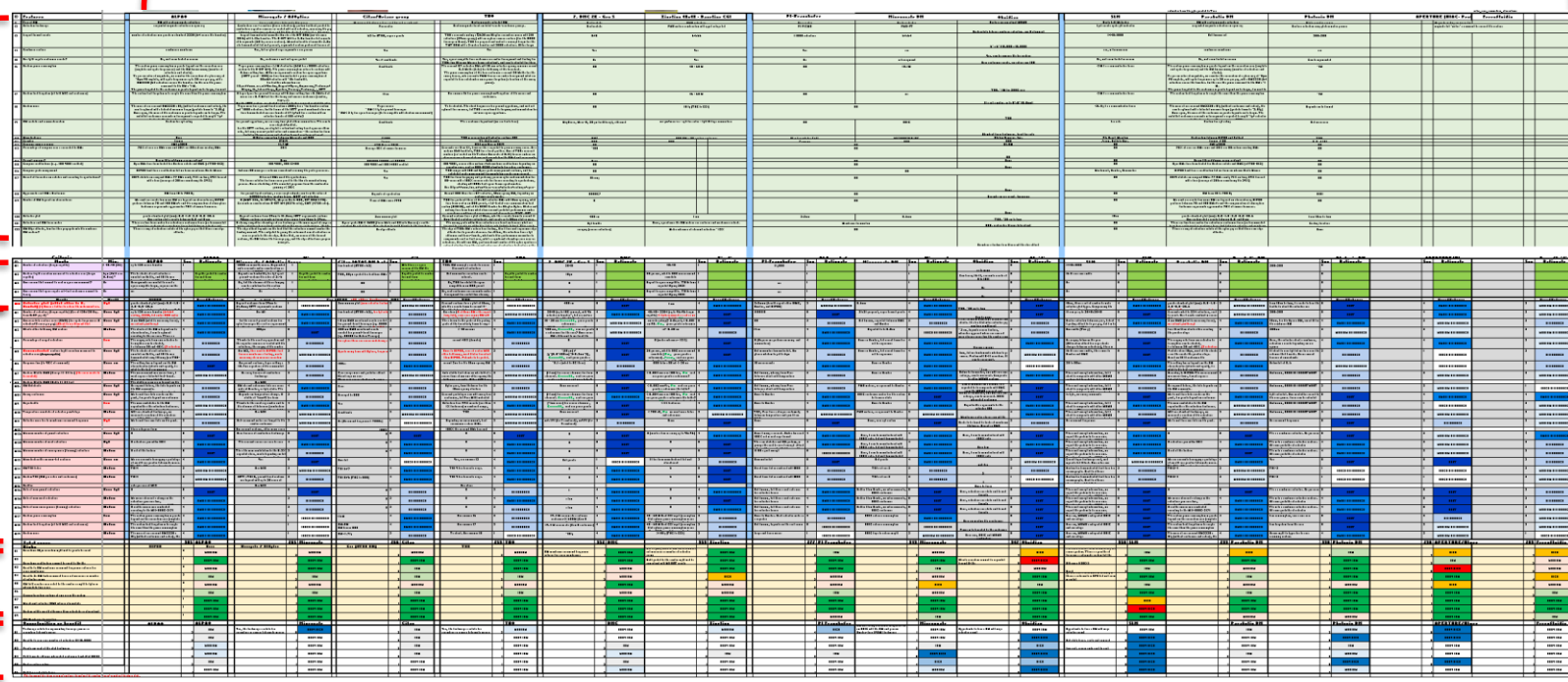
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ALPAO	Environmental	TRL-4	The company is interested in developing a space capable version. Potential for coronagraph-level DM in space

# Step 3: Scoring and populate KT Matrix

We held multiple working sessions with the SMEs to agree on the weights for each criterion and score give each DM option.

=> *The KT matrix result represent the consensus of the team*

## DM Options (Vendors)



**Descriptors**

**Musts**

**Wants**

**Risks**

**Opportunities**

# Results

## DM ranking for future flagship exoplanet mission



### DM Technology

ALPAO
Microgate
Cilas
TNO
BMC
Xinetics

*Disclaimer: Reference herein to any specific commercial product, process, or service by trade name, trademark, manufacturer, or otherwise, does not constitute or imply its endorsement by the United States Government or the Jet Propulsion Laboratory, California Institute of Technology.*

# Results

## DM ranking for future flagship exoplanet mission

DM Technology	Adjusted Final Score	
ALPAO	109	} Medium performance
Microgate	63	
Cilas	84	
TNO	62	
BMC	158	} <b>Top 2(Tied)</b> Best performance
Xinetics	152	

# Results

## DM ranking for future flagship exoplanet mission

DM Technology	Adjusted Final Score	Maturity Score
ALPAO	109	3.3
Microgate	63	3.3
Cilas	84	3.6
TNO	62	3.6
BMC	158	4.3
Xinetics	152	4.6

} **Candidate for backup**  
Medium **performance**  
Medium **maturity**

} **Top 2(Tied)**  
Best **performance**  
Highest **maturity**

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# Results

## DM ranking for future flagship exoplanet mission

DM Technology	Adjusted Final Score	Maturity Score	Risk Histogram
ALPAO	109	3.3	
Microgate	63	3.3	
Cilas	84	3.6	
TNO	62	3.6	
BMC	158	4.3	
Xinetics	152	4.6	

Candidate for backup  
 Medium performance  
 Medium maturity  
 Medium risk level

Top 2(Tied)  
 Best performance  
 Highest maturity  
 Manageable risk level

Very low	It is very unlikely that the risk will materialize
Low	It is unlikely that the risk will materialize
Medium	The risk can occur but it can be mitigated. Requires attention
High	It is likely that the risk will materialize. Requires investment to mitigate
Very high	Risk has been materialized and mitigation is uncertain even with investment

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# Conclusions



## Xinetics and BMC are the best options for DMs

- Their scores are in a statistical tie indicating best performance
- Show the highest maturity. TRL estimates between 4 and 5 for HabEx application
- Manageable risks

## Three promising new technologies identified

- Microscale, Obsidian, and SLM
- Potential high performance
- Less mature, but higher risk
- Opportunity for investment

## Conventional candidate for backup

- ALPAO has demonstrated a medium performance but could meet requirements with some development effort.
- Relatively low risk

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# Recommendations



## Develop high actuator count DMs

- No off-the-shelf units, meeting requirements requires special projects for every vendor
- Lead times are long > 2 years
- Scalability issues are difficult to predict and time consuming to debug

## Advance DM electronics performance and connectorization

- For several key parameters, the DM performance is limited by the electronics and not the DM itself
- Investment in electronics can benefit more than one technology, i.e. electronics for Xinetics and BMC are compatible

## Support the development of at least two backup technologies

- Backup technologies allow us to have a timely solution in case scalability of Xinetics and BMC does not progress satisfactorily.

## Make the DM survey a living document

- Revise scores, maturity and Risks every year
- Involve vendors and community
- Maybe talk and breakout session at AAS ExoPAG or SPIE.

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# Additional recommendations and SME comments



## Partner with Europe to develop high performance DMs

- ESO also has engaged ALPAO for the development of high resolution and stability DMs in order to perform speckle nulling from ground based telescopes equipped with AO
- NASA's ExEP and Europe could share the DM requirements and explore options to jointly fund the manufacturing of higher performance DMs
- Same for DM electronics including ASICs and HV-DACs
- Create a larger market and demand with more customers (NASA + Europe) – [\(NASA HQ recommendation\)](#)
  - Companies do not have any other market for devices with such format and performance

## Risk assessment fidelity is correlated to maturity

- Some less mature DM technologies exhibit less risks than more mature Xinetics and BMC. The reason is that less mature options has unknown risks to be discovered.
- Risk are also used as a way to communicate to vendors the SMEs concerns

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